

RESEARCH

Open Access



# $M_\varphi M_\psi$ -convexity and separation theorems

Mea Bombardelli<sup>1\*</sup>  and Sanja Varošaneć<sup>1</sup>

\*Correspondence:

[mea.bombardelli@math.hr](mailto:mea.bombardelli@math.hr)

<sup>1</sup>Department of Mathematics,  
Faculty of Science, University of  
Zagreb, Zagreb, Croatia

## Abstract

A characterization of pairs of functions that can be separated by an  $M_\varphi M_\psi$ -convex function and related results are obtained. Also, a Hyers–Ulam stability result for  $M_\varphi M_\psi$ -convex functions is given.

**MSC:** 26E60; 26A51; 26D07; 39B72

**Keywords:**  $M_\varphi M_\psi$ -convex function; Separation theorem; Hyers–Ulam stability; Quasi-arithmetic mean

## 1 Preliminaries

The concept of classical convexity has been generalized in various ways. Among numerous generalizations, we pay attention to the  $M_\varphi M_\psi$ -convexity described in [11].

Let  $\varphi$  and  $\psi$  be two continuous, strictly monotone functions defined on intervals  $I$  and  $J$  respectively. By  $M_\varphi$  we denote a quasi-arithmetic mean:

$$M_\varphi(x, y; t) := \varphi^{-1}(t\varphi(x) + (1-t)\varphi(y)), \quad x, y \in I, t \in [0, 1].$$

It is obvious that the power mean  $M_p$  corresponds to  $\varphi(x) = x^p$  if  $p \neq 0$  and to  $\varphi(x) = \log x$  if  $p = 0$ . If it is clear from the text that the weight next to  $\varphi(x)$  equals  $t$ , then we omit parameter  $t$  and simply write  $M_\varphi(x, y)$ .

We say that a function  $f: I \rightarrow J$  is  $M_\varphi M_\psi$ -convex if

$$f(M_\varphi(x, y)) \leq M_\psi(f(x), f(y))$$

for all  $x, y \in I$  and  $t \in [0, 1]$ . The  $M_\varphi M_\psi$ -concavity and  $M_\varphi M_\psi$ -affinity are defined in a natural way. If  $\psi$  is strictly increasing (strictly decreasing), then  $f$  is  $M_\varphi M_\psi$ -convex if and only if  $\psi \circ f \circ \varphi^{-1}$  is convex (concave) in the usual sense [11, p. 68].

The most known examples are classes of  $M_\varphi M_\psi$ -convex functions where  $M_\varphi$  and  $M_\psi$  belong to  $\{A, G, H\}$ , where  $A$ ,  $G$ , and  $H$  are weighted arithmetic, geometric, and harmonic mean, respectively. Some of them are known under specific names. For example,  $AG$ -convex function is usually known as log-convex function,  $GG$ -convex function is called multiplicatively convex function,  $HA$ -convex function is named harmonically convex function. Of course,  $AA$ -convex function is the usual convex function.

© The Author(s) 2022. This article is licensed under a Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other third party material in this article are included in the article's Creative Commons licence, unless indicated otherwise in a credit line to the material. If material is not included in the article's Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit <http://creativecommons.org/licenses/by/4.0/>.

A lot of examples of  $AG$ -convex or log-convex functions connected with various functionals, which have appeared in the investigation of  $n$ -convexity, are given in [5] and [6, pp. 105, 155-160, 177]. Every polynomial with nonnegative coefficients is  $GG$ -convex or multiplicatively convex function, every real analytic function  $f(x) = \sum a_n x^n$  with  $a_n \geq 0$  is  $GG$ -convex on  $[0, R)$  where  $R$  is the radius of convergence [11, Chap. 2]. Particularly, functions  $\exp$ ,  $\sinh$ ,  $\cosh$  on  $(0, \infty)$ ,  $\arcsin$  on  $(0, 1]$  are  $GG$ -convex. Examples of special functions which are  $GG$ -convex are the following: the gamma function, the Lobachevski function, and the integral sine. In [3], an example of  $HG$ -convex function is given. Namely, the function  $V_n^{-1}(p) = 2^{-n} \frac{\Gamma(1+n/p)}{\Gamma(1+1/p)^n}$  which is connected with the volume of the ellipsoid  $\{x \in \mathbb{R}^n : \|x\|_{L^p} \leq 1\}$  is  $HG$ -convex on  $(0, \infty)$ . Also, it is  $AG$ -convex.

The aim of this paper is to give a separation (sandwich) theorem in this settings. A characterization of pairs of functions that can be separated by a convex function is given in [2], and it is stated as follows.

**Theorem 1.1** *Let  $f, g : I \rightarrow \mathbb{R}$  be two functions. The following statements are equivalent:*

- (i) *For all  $x, y \in I$  and  $t \in [0, 1]$ ,*

$$f(tx + (1-t)y) \leq tg(x) + (1-t)g(y).$$

- (ii) *There exists a convex function  $h : I \rightarrow \mathbb{R}$  such that*

$$f \leq h \leq g.$$

As a consequence of the above-mentioned theorem, the Hyers–Ulam stability result for convex functions is obtained also in [2]. Namely, if  $\varepsilon > 0$  and  $f : I \rightarrow \mathbb{R}$  is a function such that

$$f(tx + (1-t)y) \leq tf(x) + (1-t)f(y) + \varepsilon, \quad x, y \in I, t \in [0, 1],$$

then there exists a convex function  $h : I \rightarrow \mathbb{R}$  such that

$$|f(x) - h(x)| \leq \frac{\varepsilon}{2}, \quad x \in I.$$

Finally, we mention a sandwich theorem involving affine functions which are considered in [12].

**Theorem 1.2** *Let  $I \subseteq \mathbb{R}$  be an interval and  $f$  and  $g$  be real functions defined on  $I$ . The following conditions are equivalent:*

- (i) *There exists an affine function  $h : I \rightarrow \mathbb{R}$  such that  $f \leq h \leq g$  on  $I$ .*  
 (ii) *There exist a convex function  $h_1 : I \rightarrow \mathbb{R}$  and a concave function  $h_2 : I \rightarrow \mathbb{R}$  such that  $f \leq h_1 \leq g$  and  $f \leq h_2 \leq g$  on  $I$ .*  
 (iii) *The following inequalities hold:*

$$f(tx + (1-t)y) \leq tg(x) + (1-t)g(y),$$

$$g(tx + (1-t)y) \geq tf(x) + (1-t)f(y)$$

*for all  $x, y \in I$  and  $t \in [0, 1]$ .*

In this paper we show that the above-mentioned theorems have their counterparts in the setting of  $M_\varphi M_\psi$ -convex functions. We prove that two functions  $f, g$  can be separated by an  $M_\varphi M_\psi$ -convex function  $h$  if and only if

$$f(M_\varphi(x, y)) \leq M_\psi(g(x), g(y))$$

for all  $x, y \in I$  and  $t \in [0, 1]$ . In the same section we give a result for an  $M_\varphi M_\psi$ -affine function which is a generalization of Theorem 1.2. The last section is devoted to the counterpart of the Hyers–Ulam stability theorem.

## 2 Separation theorems

**Theorem 2.1** *Let  $\varphi$  and  $\psi$  be two continuous, strictly monotone functions defined on intervals  $I$  and  $J$  respectively. Let  $f, g : I \rightarrow J$  be real functions.*

*The following statements are equivalent:*

- (i) *There exists an  $M_\varphi M_\psi$ -convex function  $h : I \rightarrow J$  such that*

$$f \leq h \leq g.$$

- (ii) *The following inequality holds:*

$$f(M_\varphi(x, y; t)) \leq M_\psi(g(x), g(y); t) \quad (1)$$

*for all  $x, y \in I, t \in [0, 1]$ .*

*Proof* Assume that  $\psi$  is an increasing function. Then  $\psi^{-1}$  is also increasing.

First we prove that (i) implies (ii).

Since  $h \leq g$ ,

$$t\psi(h(x)) + (1-t)\psi(h(y)) \leq t\psi(g(x)) + (1-t)\psi(g(y))$$

and then

$$\psi^{-1}(t\psi(h(x)) + (1-t)\psi(h(y))) \leq \psi^{-1}(t\psi(g(x)) + (1-t)\psi(g(y))),$$

i.e.,

$$M_\psi(h(x), h(y)) \leq M_\psi(g(x), g(y)). \quad (2)$$

Using the fact that  $f \leq h$ ,  $h$  is  $M_\varphi M_\psi$ -convex and inequality (2)

$$\begin{aligned} f(M_\varphi(x, y)) &\leq h(M_\varphi(x, y)) \\ &\leq M_\psi(h(x), h(y)) \leq M_\psi(g(x), g(y)). \end{aligned}$$

Now assume that (ii) holds. For any  $u, v \in \text{Im } \varphi$ , there exist  $x, y \in I$  such that  $u = \varphi(x)$ ,  $v = \varphi(y)$ . From (1) it follows

$$\psi(f(\varphi^{-1}(tu + (1-t)v))) \leq t\psi(g(\varphi^{-1}(u))) + (1-t)\psi(g(\varphi^{-1}(v))).$$

This can be written as

$$F(tu + (1-t)v) \leq tG(u) + (1-t)G(v), \quad (3)$$

where  $F = \psi \circ f \circ \varphi^{-1}$  and  $G = \psi \circ g \circ \varphi^{-1}$ ,  $F, G : \text{Im } \varphi \rightarrow \mathbb{R}$ . Inequality (3) holds for all  $u, v \in \text{Im } \varphi$  and for all  $t \in [0, 1]$ .

Now we may apply Theorem 1.1 to conclude that there exists a convex function  $H : \text{Im } \varphi \rightarrow \mathbb{R}$  such that

$$F \leq H \leq G. \quad (4)$$

Then  $H \circ \varphi$  is well defined.

Since  $F(u) \leq H(u) \leq G(u)$ , i.e.,  $\psi(f(x)) \leq (H \circ \varphi)(x) \leq \psi(g(x))$ , and since  $\psi$  is a continuous, strictly increasing function defined on the interval  $J$ , the value  $(H \circ \varphi)(x)$  is in the domain of  $\psi$ . This allows us to define  $h = \psi^{-1} \circ H \circ \varphi$ ,  $h : I \rightarrow J$ . As  $H$  is convex, it follows that  $h$  is  $M_\varphi M_\psi$ -convex, and from (4) it follows that  $f \leq h \leq g$ , i.e., (i) holds.

If  $\psi$  is decreasing, the proof is analogous.  $\square$

**Theorem 2.2** *Let  $\varphi$  and  $\psi$  be two continuous, strictly monotone functions defined on intervals  $I$  and  $J$  respectively. Let  $f, g : I \rightarrow J$  be real functions.*

*The following statements are equivalent:*

- (i) *There exists an  $M_\varphi M_\psi$ -affine function  $h$  such that*

$$f \leq h \leq g.$$

- (ii) *The following inequalities:*

$$f(M_\varphi(x, y; t)) \leq M_\psi(g(x), g(y); t), \quad (5)$$

$$g(M_\varphi(x, y; t)) \geq M_\psi(f(x), f(y); t)$$

*hold for all  $x, y \in I$  and  $t \in [0, 1]$ .*

*Proof* Let  $h$  be an  $M_\varphi M_\psi$ -affine function such that  $f \leq h \leq g$ . This means that

$$h(M_\varphi(x, y)) = M_\psi(h(x), h(y)), \quad \forall x, y \in I.$$

Let  $F = \psi \circ f \circ \varphi^{-1}$ ,  $G = \psi \circ g \circ \varphi^{-1}$ ,  $H = \psi \circ h \circ \varphi^{-1}$ . It is easy to show that  $H$  is an affine function.

Let  $\psi$  be an increasing function. Then  $F \leq H \leq G$  on  $\text{Im } \varphi$ . (If  $\psi$  is decreasing, then  $G \leq H \leq F$ , and the proof is similar.)

Applying Theorem 1.2 ((i) implies (iii)), we obtain

$$F(tu + (1-t)v) \leq tG(u) + (1-t)G(v), \quad (6)$$

$$G(tu + (1-t)v) \geq tF(u) + (1-t)F(v) \quad (7)$$

for all  $u, v \in \text{Im } \varphi$  and  $t \in [0, 1]$ .

From (6), for all  $x, y \in I$  and  $t \in [0, 1]$ , it follows

$$\begin{aligned}(\psi \circ f \circ \varphi^{-1})(t\varphi(x) + (1-t)\varphi(y)) &\leq t(\psi \circ g)(x) + (1-t)(\psi \circ g)(y), \\ f(\varphi^{-1}(t\varphi(x) + (1-t)\varphi(y))) &\leq \psi^{-1}(t\psi(g(x)) + (1-t)\psi(g(y))),\end{aligned}$$

i.e.,  $f(M_\varphi(x, y; t)) \leq M_\psi(g(x), g(y); t)$ .

In the same way,  $g(M_\varphi(x, y; t)) \geq M_\psi(f(x), f(y); t)$ .

Now assume (ii).

From (5) it follows

$$\begin{aligned}F(tu + (1-t)v) &\leq tG(u) + (1-t)G(v), \\ G(tu + (1-t)v) &\geq tF(u) + (1-t)F(v), \quad \forall u, v \in \text{Im } \varphi, \forall t \in [0, 1],\end{aligned}$$

where  $F = \psi \circ f \circ \varphi^{-1}$  and  $G = \psi \circ g \circ \varphi^{-1}$ ,  $F, G : \text{Im } \varphi \rightarrow \mathbb{R}$ .

From Theorem 1.2 ((iii) implies (i)) we conclude that there exists an affine function  $H : \text{Im } \varphi \rightarrow \mathbb{R}$  such that  $F(w) \leq H(w) \leq G(w)$  for all  $w \in \text{Im } \varphi$ .

Then, as in the proof of the previous theorem,  $h = \psi^{-1} \circ H \circ \varphi$ ,  $h : I \rightarrow \mathbb{R}$  is well defined, and  $f \leq h \leq g$ . It is easy to verify that  $h$  is an  $M_\varphi M_\psi$ -affine function.  $\square$

### 3 Hyers–Ulam stability

**Theorem 3.1** *Let  $\varphi$  be a continuous strictly monotone function on an interval  $I$ . Let  $\varepsilon > 0$  be a fixed number. A function  $f : I \rightarrow \mathbb{R}$  satisfies*

$$f(M_\varphi(x, y)) \leq tf(x) + (1-t)f(y) + \varepsilon \quad (8)$$

for all  $x, y \in I$ ,  $t \in [0, 1]$ , if and only if there exists an  $M_\varphi A$ -convex function  $h : I \rightarrow \mathbb{R}$  such that

$$|f(x) - h(x)| \leq \frac{1}{2}\varepsilon, \quad \forall x \in I. \quad (9)$$

*Proof* Assume that  $f$  satisfies (8). For  $g = f + \varepsilon$ , we have

$$A(f(x), f(y)) + \varepsilon = A(g(x), g(y)).$$

Therefore, from (8) it follows

$$f(M_\varphi(x, y)) \leq A(g(x), g(y)),$$

which is a form of condition (ii) from Theorem 2.1.

We conclude that there exists an  $M_\varphi A$ -convex function  $h_1 : I \rightarrow \mathbb{R}$  such that  $f \leq h_1 \leq g$ , i.e.,  $f \leq h_1 \leq f + \varepsilon$ .

Let  $h = h_1 - \frac{1}{2}\varepsilon$ . Then  $-\frac{1}{2}\varepsilon \leq f(x) - h(x) \leq \frac{1}{2}\varepsilon$  for all  $x \in I$ , so (9) holds.

Since

$$h(M_\varphi(x, y)) = h_1(M_\varphi(x, y)) - \frac{1}{2}\varepsilon \leq A(h_1(x), h_1(y)) - \frac{1}{2}\varepsilon = A(h(x), h(y)),$$

$h$  is also  $M_\varphi A$ -convex, which completes the proof.

Now let  $h: I \rightarrow \mathbb{R}$  be an  $M_\varphi A$ -convex function such that (9) holds. This condition can be written in the form

$$f(x) - \frac{1}{2}\varepsilon \leq h(x) \leq f(x) + \frac{1}{2}\varepsilon.$$

Using Theorem 2.1 we can conclude that functions  $f_1 = f - \frac{1}{2}\varepsilon$  and  $f_2 = f + \frac{1}{2}\varepsilon$  satisfy

$$f_1(M_\varphi(x, y)) \leq A(f_1(x), f_1(y)).$$

This is equivalent to

$$f(M_\varphi(x, y)) - \frac{1}{2}\varepsilon \leq A(f(x), f(y)) + \frac{1}{2}\varepsilon,$$

which proves (8).  $\square$

As we mentioned in the first section, the corresponding results for convex functions, i.e., for  $AA$ -convex functions, are given in [2] and [12]. A special case of Theorem 2.2, where  $\psi = \varphi$ , is given in [8]. Particular cases of Theorem 2.1 and Theorem 3.1 for  $HA$ -convex functions are given in [4].

Results about the separation problem for some other classes of functions which are not particular cases of the class of  $M_\varphi M_\psi$ -convex functions, i.e., for strongly convex functions,  $m$ -convex and  $h$ -convex functions, set-valued functions, and convex functions with control function, are given in [7, 9, 10, 13], and [1] respectively.

#### Acknowledgements

Not applicable.

#### Funding

The publication charges for this manuscript are supported by the University of Zagreb, Faculty of Science, Department of Mathematics.

#### Availability of data and materials

Not applicable.

#### Declarations

##### Competing interests

The authors declare that they have no competing interests.

##### Authors' contributions

SV: conceptualization, writing the original draft, computation. MB: computation, analyzing the results, writing and editing. Both authors read and approved the final manuscript.

#### Publisher's Note

Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

Received: 17 November 2021 Accepted: 4 May 2022 Published online: 23 May 2022

## References

1. Adamek, M.: On a generalization of sandwich type theorems. *Aequationes Math.* **92**, 641–647 (2018)
2. Baron, K., Matkowski, J., Nikodem, K.: A sandwich with convexity. *Math. Pannon.* **5**(1), 139–144 (1994)
3. Borwein, D., Borwein, J., Fee, G., Girgensohn, R.: Refined convexity and special cases of the Blaschke-Santaló inequality. *Math. Inequal. Appl.* **4**, 631–638 (2001)
4. Bracamonte, M., Giménez, J., Medina, J., Vivas-Cortez, M.: A sandwich theorem and stability result of Hyers-Ulam type for harmonically convex functions. *Lect. Mat.* **38**, 5–18 (2017)
5. Khan, A.R., Pečarić, J., Varošanec, S.: Positivity of sums and integrals for convex functions of higher order of  $n$  variables. *Math. Inequal. Appl.* **19**(1), 221–247 (2016)
6. Khan, A.R., Praljak, M., Pečarić, J., Varošanec, S.: *General Linear Inequalities*. Element, Zagreb (2017)
7. Lara, T., Matkowski, J., Merentes, N., Quintero, R., Wróbel, M.: A generalization of  $m$ -convexity and a sandwich theorem. *Ann. Math. Sil.* **31**, 107–126 (2017)
8. Matkowski, J., Zgraja, T.: A separation theorem for  $M\phi$ -convex functions. *Math. Pannon.* **9**(1), 103–109 (1998)
9. Merentes, N., Nikodem, K.: Remarks on strongly convex functions. *Aequationes Math.* **80**, 193–199 (2010)
10. Mitroi-Symeonidis, F.C.: Convexity and sandwich theorems. *Eur. J. Res. Appl. Sci.* **1**, 9–11 (2015)
11. Niculescu, C., Persson, L.: *Convex Functions and Their Applications, a Contemporary Approach*. CMS Books in Mathematics, vol. 23. Springer, New York (2006)
12. Nikodem, K., Wasowicz, S.: A sandwich theorem and Hyers–Ulam stability of affine functions. *Aequationes Math.* **49**, 160–164 (1995)
13. Olbryś, A.: On separation by  $h$ -convex functions. *Tatra Mt. Math. Publ.* **62**, 105–111 (2015)

**Submit your manuscript to a SpringerOpen<sup>®</sup> journal and benefit from:**

- Convenient online submission
- Rigorous peer review
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

---

Submit your next manuscript at ► [springeropen.com](https://www.springeropen.com)