RESEARCH Open Access

CrossMark

Strong convergence theorems for a class of split feasibility problems and fixed point problem in Hilbert spaces

Jinhua Zhu¹, Jinfang Tang¹ and Shih-sen Chang^{2*}

*Correspondence: changss2013@163.com 2Center for General Education, China Medical University, Taichung, Taiwan Full list of author information is available at the end of the article

Abstract

In this paper we consider a class of split feasibility problem by focusing on the solution sets of two important problems in the setting of Hilbert spaces. One of them is the set of zero points of the sum of two monotone operators and the other is the set of fixed points of mappings. By using the modified forward–backward splitting method, we propose a viscosity iterative algorithm. Under suitable conditions, some strong convergence theorems of the sequence generated by the algorithm to a common solution of the problem are proved. At the end of the paper, some applications and the constructed algorithm are also discussed.

MSC: 26A18; 47H04; 47H05; 47H10

Keywords: Split feasibility; Maximal monotone operators; Inverse strongly monotone operator; Fixed point problems; Strong convergence theorems

1 Introduction

Many applications of the split feasibility problem (SFP), which was first introduced by Censor and Elfving [1], have appeared in various fields of science and technology, such as in signal processing, medical image reconstruction and intensity-modulated radiation therapy (for more information, see [2, 3] and the references therein). In fact, Censor and Elfving [1] studied SFP in a finite-dimensional space, by considering the problem of finding a point

$$x^* \in C$$
 such that $Ax^* \in Q$, (1.1)

where *C* and *Q* are nonempty closed convex subsets of \mathbb{R}^n , and *A* is an $n \times n$ matrix. They introduced an iterative method for solving SFP.

On the other hand, variational inclusion problems are being used as mathematical programming models to study a large number of optimization problems arising in finance, economics, network, transportation and engineering science. The formal form of a variational inclusion problem is the problem of finding $x^* \in H$ such that

$$0 \in Bx^*, \tag{1.2}$$



where $B: H \to 2^H$ is a set-valued operator. If B is a maximal monotone operator, the elements in the solution set of problem (1.2) are called the zeros of this maximal monotone operator. This problem was introduced by Martinet [4], and later it has been studied by many authors. It is well known that the popular iteration method that was used for solving problem (1.2) is the following proximal point algorithm: for a given $x \in H$,

$$x_{n+1} = J_{\lambda_n}^B x_n, \quad \forall n \in \mathbb{N},$$

where $\{\lambda_n\} \subset (0, \infty)$ and $J_{\lambda_n}^B = (I + \lambda_n B)^{-1}$ is the resolvent of the considered maximal monotone operator B corresponding to λ_n (see, also [5–9] for more details).

In view of SFP and the fixed point problem, very recently, Montira et al. [10] considered the problem of finding a point $x^* \in H$ such

$$0 \in Ax^* + Bx^* \quad \text{and} \quad Lx^* \in F(T), \tag{1.3}$$

where $A: H_1 \to H_1$ is a monotone operator, and $B: H_1 \to 2^{H_1}$ is a maximal monotone operator, $L: H_1 \to H_2$ is a bounded linear operator and $T: H_2 \to H_2$ is a nonexpansive mapping.

They considered the following iterative algorithm: for any $x_0 \in H_1$,

$$x_{n+1} = J_{\lambda_n}^B ((I - \lambda_n A) - \gamma_n L^* (I - T) L) x_n, \quad \forall n \in \mathbb{N},$$

$$(1.4)$$

where $\{\lambda_n\}$ and $\{\gamma_n\}$ satisfy some suitable control conditions, and $J_{\lambda_n}^B$ is the resolvent of a maximal monotone operator B associated to λ_n , and proved that sequence (1.4) weakly converges to a point $x^* \in \Omega_{L,T}^{A+B}$, where $\Omega_{L,T}^{A+B}$ is the solution set of problem (1.3).

Motivated by the work of Montira et al. [10] and the research in this direction, the purpose of this paper is to study the following split feasibility problem and fixed point problem: find $x^* \in H$ such that

$$0 \in Ax^* + Bx^*, \quad Lx^* \in F(T) \quad \text{and} \quad x^* \in F(S),$$
 (1.5)

where A, B, L are the same as in (1.3) and $S: H_1 \to H_1$ is a nonexpansive mapping. By using a modified forward–backward splitting method, we propose a viscosity iterative algorithm (see (3.4) below). Under suitable conditions, some strong convergence theorems of the sequence generated by the algorithm to a zero of the sum of two monotone operators and fixed point of mappings are proved. At the end of the paper, some applications and the constructed algorithm are also discussed. The results presented in the paper extend and improve the main results of Montira et al. [10], Byrne et al. [11], Takahashi et al. [12] and Passty [13].

2 Preliminaries

Throughout this paper, we denote by \mathbb{N} the set of positive integers, and by \mathbb{R} the set of real numbers. Let H be a real Hilbert space with the inner product $\langle \cdot, \cdot \rangle$ and norm $\| \cdot \|$, respectively. When $\{x_n\}$ is a sequence in H, we denote the weak convergence of $\{x_n\}$ to x in H by $x_n \rightharpoonup x$.

Let $T: H \to H$ be a mapping. We say that T is a Lipschitz mapping if there exists an L > 0 such that

$$||Tx - Ty|| \le L||x - y||, \quad \forall x, y \in H.$$

The number L, associated with T, is called a Lipschitz constant. If L = 1,we say that T is a nonexpansive mapping, that is,

$$||Tx - Ty|| \le ||x - y||, \quad \forall x, y \in H.$$

We say that *T* is firmly nonexpansive if

$$\langle Tx - Ty, x - y \rangle \ge ||Tx - Ty||^2, \quad \forall x, y \in H.$$

A mapping $T: H \to H$ is said to be an averaged mapping if it can be written as the average of the identity I and a nonexpansive mapping, that is,

$$T = (1 - \alpha)I + \alpha S,\tag{2.1}$$

where $\alpha \in (0,1)$ and $S: H \to H$ is a nonexpansive mapping [14]. More precisely, when (2.1) holds, we say that T is α -averaged. It should be observed that a mapping is firmly nonexpansive if and only if it is a $\frac{1}{2}$ -averaged mapping.

Let $A : H \to H$ be a single-valued mapping. For a positive real number β , we say that A is β -inverse strongly monotone (β -ism) if

$$\langle Ax - Ay, x - y \rangle > \beta \|Ax - Ay\|^2, \quad \forall x, y \in H.$$

We now collect some important conclusions and properties, which will be needed in proving our main results.

Lemma 2.1 ([15, 16]) *The following conclusions hold:*

- (i) The composition of finitely many averaged mappings is averaged. In particular, if T_i is α_i -averaged, where $\alpha_i \in (0,1)$ for i=1,2, then the composition T_1T_2 is α -averaged, where $\alpha = \alpha_1 + \alpha_2 \alpha_1\alpha_2$.
- (ii) If A is β -ism and $\gamma \in (0, \beta]$, then $T := I \gamma A$ is firmly nonexpansive.
- (iii) A mapping $T: H \to H$ is nonexpansive if and only if I T is $\frac{1}{2}$ -ism.
- (iv) If A is β -ism, then, for $\gamma > 0$, γA is $\frac{\beta}{\gamma}$ -ism.
- (v) T is averaged if and only if the complement I-T is β -ism for some $\beta > \frac{1}{2}$. Indeed, for $\alpha \in (0,1)$, T is α -averaged if and only if I-T is $\frac{1}{2\alpha}$ -ism.

Lemma 2.2 ([17]) Let $T = (1 - \alpha)A + \alpha N$ for some $\alpha \in (0, 1)$. If A is β -averaged and N is nonexpansive then T is $\alpha + (1 - \alpha)\beta$ -averaged.

Let $B: H \to 2^H$ be a set-valued mapping. The effective domain of B is denoted by D(B), that is, $D(B) = \{x \in H : Bx \neq \emptyset\}$. Recall that B is said to be monotone if

$$\langle x - y, u - v \rangle \ge 0$$
, $\forall x, y \in D(B), u \in Bx, v \in By$.

A monotone mapping B is said to be maximal if its graph is not properly contained in the graph of any other monotone operator. For a maximal monotone operator $B: H \to 2^H$ and r > 0, its resolvent J_r^B is defined by

$$J_r^B := (I + rB)^{-1} : H \to D(B).$$

It is well known that, if B is a maximal monotone operator and r is a positive number, then the resolvent J_r^B is single-valued and firmly nonexpansive, and $F(J_r^B) = B^{-1}0 \equiv \{x \in H : 0 \in A\}$ Bx}, $\forall r > 0$ (see [12, 18, 19]).

Lemma 2.3 ([20]) Let H be a Hilbert space and let B be a maximal monotone operator on H. Then for all s, t > 0 and $x \in H$,

$$\frac{s-t}{s}\langle J_s x - J_t x, J_s x - x \rangle \ge \|J_s x - J_t x\|^2;$$

$$||J_s x - J_t x|| \le (|s - t|/s) ||x - J_s x||.$$

Lemma 2.4 ([12]) Let H_1 and H_2 be Hilbert spaces. Let $L: H_1 \rightarrow H_2$ be a nonzero bounded linear operator and $T: H_2 \to H_2$ be a nonexpansive mapping. If $B: H_1 \to 2^{H_1}$ is a maximal monotone operator, then

- (i) $L^*(I-T)L$ is $\frac{1}{2\|L\|^2}$ -ism, (ii) For $0 < r < \frac{1}{\|L\|}$,
- (iia) $I rL^*(I T)L$ is $r||L||^2$ -averaged,
- (iib) $J_{\lambda}^{B}(I rL^{*}(I T)L)$ is $\frac{1+r\|L\|^{2}}{2}$ -averaged, for $\lambda > 0$, (iii) If $r = \|L\|^{-2}$, then $I rL^{*}(I T)L$ is nonexpansive.

Lemma 2.5 ([21]) Let $B: H \to 2^H$ be a maximal monotone operator with the resolvent $J_{\lambda}^{B} = (I + \lambda B)^{-1}$ for $\lambda > 0$. Then we have the following resolvent identity:

$$J_{\lambda}^{B}x = J_{\mu}^{B} \left(\frac{\mu}{\lambda}x + \left(1 - \frac{\mu}{\lambda}\right)J_{\lambda}^{B}x\right),\,$$

for all $\mu > 0$ and $x \in H$.

Lemma 2.6 ([22]) Let C be a closed convex subset of a Hilbert space H and let T be a nonexpansive mapping of C into itself. Then U := I - T is demiclosed, i.e., $x_n \rightharpoonup x_0$ and $Ux_n \rightarrow y_0$ imply $Ux_0 = y_0$.

Lemma 2.7 ([10]) Let H_1 and H_2 be Hilbert spaces. Let $A: H_1 \to H_1$ be a β -ism, $B: H_1 \to H_2$ 2^{H_1} a maximal monotone operator, $T: H_2 \to H_2$ a nonexpansive mapping and $L: H_1 \to H_2$ a bounded linear operator. If $\Omega_{L,T}^{A+B} \neq \emptyset$, then the following are equivalent:

- (i) $z \in \Omega_{IT}^{A+B}$,
- (ii) $z = J_{\lambda}^{B}((I_{\lambda} A) \gamma L^{*}(I T)L)z$,
- (iii) $0 \in L^*(I T)Lz + (A + B)z$,

where $\lambda, \gamma > 0$ and $z \in H_1$.

Lemma 2.8 ([23]) Let $\{a_n\}$ be a sequence of nonnegative real numbers such that

$$a_{n+1} \leq (1-\beta_n)a_n + \delta_n, \quad \forall n \geq 0,$$

where $\{\beta_n\}$ is a sequence in (0,1) and $\{\delta_n\}$ is a sequence in \mathbb{R} such that

- (i) $\sum_{n=1}^{\infty} \beta_n = \infty$;
- (ii) $\limsup_{n\to\infty} \frac{\delta_n}{\beta_n} \le 0$ or $\sum_{n=1}^{\infty} |\delta_n| < \infty$.

3 Main results

We are now in a position to give the main result of this paper.

Lemma 3.1 Let H_1 and H_2 be two real Hilbert spaces. Let $A: H_1 \to H_1$ be a β -ism, B: $H_1 \rightarrow 2^{H_1}$ be a maximal monotone operator, $T: H_2 \rightarrow H_2$ be a nonexpansive mapping, and $L: H_1 \to H_2$ be a bounded linear operator. Let $S: H_1 \to H_1$ be a nonexpansive mapping such that $F(S) \cap \Omega_{I,T}^{A+B} \neq \emptyset$, where

$$\Omega_{L,T}^{A+B} := \left\{ x \in (A+B)^{-1}(0) \cap L^{-1}F(T) \right\} \tag{3.1}$$

is the set of solutions of problem (1.3). Let $f: H_1 \to H_1$ be a contraction mapping with a contractive constant $\alpha \in (0,1)$. For any $t \in (0,1]$, let $W_t : H_1 \to H_1$ be the mapping defined by

$$W_t x = t f(x) + (1 - t) S \left[J_{\lambda_n}^B \left((I - \lambda_n A) - \gamma_n L^* (I - T) L \right) x \right], \quad \forall x \in H_1,$$

$$(3.2)$$

where L^* is the adjoint of L and the sequences λ_n and γ_n satisfy the following control conditions

- (i) $0 < a \le \lambda_n \le b_1 < \frac{\beta}{2}$, (ii) $0 < a \le \gamma_n \le b_2 < \frac{1}{2\|L\|^2}$, for some $a, b_1, b_2 \in \mathbb{R}$.

Then W_t is a contraction mapping with a contractive constant $[1-t(1-\alpha)]$. Therefore W_t has a unique fixed point for each $t \in (0,1)$.

Proof Note that, for each $n \in \mathbb{N}$, we have

$$(I - \lambda_n A) - \gamma_n L^*(I - L)L = \frac{1}{2}(I - 2\lambda_n A) + \frac{1}{2}(I - 2\gamma_n L^*(I - T)L).$$

Also, by condition (i) and Lemma 2.1(ii), we know that $I - 2\lambda_n A$ is a firmly nonexpansive mapping, and this implies that $I - 2\lambda_n A$ must be a nonexpansive mapping. On the other hand, by Lemma 2.4(iia), we know that $I - 2\gamma_n L^*(I - T)L$ is $2\gamma_n ||L||^2$ -averaged. Thus, by condition (ii) and Lemma 2.2, we see that $(I - \lambda_n A) - \gamma_n L^*(I - T)L$ is $\frac{1+2\gamma_n \|L\|^2}{2}$ -averaged. Set

$$T_n := J_{\lambda_n}^B \left((I - \lambda_n A) - \gamma_n L^* (I - T) L \right), \quad \forall n \ge 1.$$
(3.3)

Since $J_{\lambda_n}^B$ is $\frac{1}{2}$ -averaged, by Lemma 2.1(i) we see that T_n is $\frac{3+2\gamma_n\|L\|^2}{4}$ -averaged and hence it is nonexpansive. Further, for any $x, y \in H_1$, we obtain

$$||W_t x - W_t y|| = ||tf(x) + (1 - t)ST_n x - tf(y) - (1 - t)ST_n y||$$

$$\leq t||f(x) - f(y)|| + (1 - t)||ST_n x - ST_n y||$$

$$\leq t\alpha \|x - y\| + (1 - t)\|x - y\|$$

= $(1 - t(1 - \alpha))\|x - y\|$.

Since $0 < 1 - t(1 - \alpha) < 1$, it follows that W_t is a contraction mapping. Therefore, by Banach contraction principle, W_t has a unique fixed point x_t in H_1 .

Theorem 3.2 Let H_1 , H_2 , A, B, T, L, S, f be the same as in Lemma 3.1. For any given $x_0 \in H_1$, let $\{u_n\}$ and $\{x_n\}$ be the sequences generated by

$$\begin{cases} u_n = J_{\lambda_n}^B((I - \lambda_n A) - \gamma_n L^*(I - T)L)x_n, \\ x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n)Su_n, \end{cases} \quad \forall n \ge 0,$$

$$(3.4)$$

where $\{\alpha_n\}$ is a sequence in (0,1) such that $\lim_{n\to\infty}\alpha_n=0$, $\sum_{n=0}^{\infty}\alpha_n=\infty$ and $\sum_{n=1}^{\infty}|\alpha_n-\alpha_{n-1}|<\infty$ and L^* is the adjoint of L.

If $F(S) \cap \Omega_{I,T}^{A+B} \neq \emptyset$ and the sequences $\{\lambda_n\}$ and $\{\gamma_n\}$ satisfy the following conditions:

- (i) $0 < a \le \lambda_n \le b_1 < \frac{\beta}{2}$, and $\sum_{n=1}^{\infty} |\lambda_n \lambda_{n-1}| < \infty$,
- (ii) $0 < a \le \gamma_n \le b_2 < \frac{1}{2\|L\|^2}$, and $\sum_{n=1}^{\infty} |\gamma_n \gamma_{n-1}| < \infty$, for some $a, b_1, b_2 \in \mathbb{R}$, then the sequences $\{u_n\}$ and $\{x_n\}$ both converge strongly to $z \in F(S) \cap \Omega_{L,T}^{A+B}$, where $z = P_{F(S) \cap \Omega_{L,T}^{A+B}}f(z)$, i.e., z is a solution of problem (1.5).

Proof Take

$$T_n := J_{\lambda_n}^B ((I - \lambda_n A) - \gamma_n L^*(I - T)L),$$

for each $n \in \mathbb{N}$. By Lemma 2.7, we have $\Omega_{L,T}^{A+B} = F(T_n)$, for all $n \in \mathbb{N}$. Thus, for each $n \in \mathbb{N}$, we can write $x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n) ST_n x_n$. By the proof of Lemma 3.1, we see that T_n is $\frac{3+2\gamma_n\|L\|^2}{4}$ -averaged. Thus, for each $n \in \mathbb{N}$, we can write

$$T_n = (1 - \xi_n)I + \xi_n V_n,$$

where $\xi_n = \frac{3+2\gamma_n\|L\|^2}{4}$ and V_n is a nonexpansive mapping. Consequently, we also have $\Omega_{LT}^{A+B} = F(T_n) = F(V_n)$, for all $n \in \mathbb{N}$. Using this fact, for each $p \in F(S) \cap \Omega_{LT}^{A+B}$, we see that

$$\|u_{n} - p\|^{2} = \|T_{n}x_{n} - p\|^{2}$$

$$= \|(1 - \xi_{n})x_{n} + \xi_{n}V_{n}x_{n} - p\|^{2}$$

$$= \|(1 - \xi_{n})(x_{n} - p) + \xi_{n}(V_{n}x_{n} - p)\|^{2}$$

$$= (1 - \xi_{n})\|x_{n} - p\|^{2} + \xi_{n}\|V_{n}x_{n} - p\|^{2} - \xi_{n}(1 - \xi_{n})\|x_{n} - V_{n}x_{n}\|^{2}$$

$$\leq \|x_{n} - p\|^{2} - \xi_{n}(1 - \xi_{n})\|x_{n} - V_{n}x_{n}\|^{2}$$
(3.5)

for each $n \in \mathbb{N}$. Since $I - T_n = \xi_n (I - V_n)$, in view of (3.5) we get

$$||u_n - p||^2 \le ||x_n - p||^2 - (1 - \xi_n)||x_n - T_n x_n||^2, \tag{3.6}$$

for each $n \in \mathbb{N}$. Since $\xi_n = \frac{3+2\gamma_n \|L\|^2}{4} \in (\frac{3}{4}, 1)$, we obtain

$$||u_n - p||^2 < ||x_n - p||^2. (3.7)$$

Next, we estimate

$$||x_{n+1} - p|| = ||\alpha_n f(x_n) + (1 - \alpha_n) S u_n - p||$$

$$\leq \alpha_n ||f(x_n) - p|| + (1 - \alpha_n) ||S u_n - p||$$

$$\leq \alpha_n (||f(x_n) - f(p)|| + ||f(p) - p||) + (1 - \alpha_n) ||u_n - p||$$

$$\leq \alpha_n \alpha ||x_n - p|| + \alpha_n ||f(p) - p|| + (1 - \alpha_n) ||x_n - p||$$

$$\leq (1 - \alpha_n (1 - \alpha)) ||x_n - p|| + \alpha_n ||f(p) - p||$$

$$\leq \max \left\{ ||x_n - p||, \frac{||f(p) - p||}{1 - \alpha} \right\}.$$

By induction, we can prove that

$$||x_{n+1} - p|| \le \max \left\{ ||x_0 - p||, \frac{||f(p) - p||}{1 - \alpha} \right\}, \quad \forall n \ge 0.$$
 (3.8)

Hence $\{x_n\}$ is bounded and so are $\{u_n\}$, $\{f(x_n)\}$ and $\{Su_n\}$.

Next, we show that

$$\lim_{n \to \infty} \|x_{n+1} - x_n\| = 0. \tag{3.9}$$

In fact, it follows from (3.4) that

$$||x_{n+1} - x_n|| = ||\alpha_n f(x_n) + (1 - \alpha_n) S u_n - (\alpha_{n-1} f(x_{n-1}) + (1 - \alpha_{n-1}) S u_{n-1})||$$

$$= ||\alpha_n f(x_n) - \alpha_n f(x_{n-1}) + \alpha_n f(x_{n-1}) - \alpha_{n-1} f(x_{n-1}) + (1 - \alpha_n) S u_n$$

$$- (1 - \alpha_n) S u_{n-1} + (1 - \alpha_n) S u_{n-1} - (1 - \alpha_{n-1}) S u_{n-1}||$$

$$\leq \alpha_n \alpha ||x_n - x_{n-1}|| + (1 - \alpha_n) ||S u_n - S u_{n-1}|| + 2|\alpha_n - \alpha_{n-1}|K$$

$$\leq \alpha_n \alpha ||x_n - x_{n-1}|| + (1 - \alpha_n) ||u_n - u_{n-1}|| + 2|\alpha_n - \alpha_{n-1}|K, \tag{3.10}$$

where $K := \sup\{\|f(x_n)\| + \|Su_n\| : n \in \mathbb{N}\}.$

Put

$$y_n = ((I - \lambda_n A) - \gamma_n L^* (I - T) L) x_n$$
 and
 $u_n = T_n x_n = J_{\lambda_n}^B y_n$.

Since $J_{\lambda_n}^B((I-\lambda_n A)-\gamma_n L^*(I-T)L)$ is nonexpansive, it follows from Lemma 2.3 that

$$\|u_{n+1} - u_n\| = \|J_{\lambda_{n+1}}^B y_{n+1} - J_{\lambda_n}^B y_n\|$$

$$\leq \|J_{\lambda_{n+1}}^B y_{n+1} - J_{\lambda_{n+1}}^B ((I - \lambda_{n+1} A) - \gamma_{n+1} L^* (I - T) L) x_n\|$$

$$+ \|J_{\lambda_{n+1}}^{B}((I-\lambda_{n+1}A) - \gamma_{n+1}L^{*}(I-T)L)x_{n} - J_{\lambda_{n}}^{B}y_{n}\|$$

$$\leq \|x_{n+1} - x_{n}\| + \|J_{\lambda_{n+1}}^{B}((I-\lambda_{n+1}A) - \gamma_{n+1}L^{*}(I-T)L)x_{n} - J_{\lambda_{n}}^{B}y_{n}\|$$

$$\leq \|J_{\lambda_{n+1}}^{B}((I-\lambda_{n+1}A) - \gamma_{n+1}L^{*}(I-T)L)x_{n} - J_{\lambda_{n+1}}^{B}((I-\lambda_{n}A) - \gamma_{n}L^{*}(I-T)L)x_{n}\|$$

$$+ \|J_{\lambda_{n+1}}^{B}y_{n} - J_{\lambda_{n}}^{B}y_{n}\| + \|x_{n+1} - x_{n}\|$$

$$\leq \|((I-\lambda_{n+1}A) - \gamma_{n+1}L^{*}(I-T)L)x_{n} - ((I-\lambda_{n}A) - \gamma_{n}L^{*}(I-T)L)x_{n}\|$$

$$+ \|J_{\lambda_{n+1}}^{B}y_{n} - J_{\lambda_{n}}^{B}y_{n}\| + \|x_{n+1} - x_{n}\|$$

$$\leq |\lambda_{n+1} - \lambda_{n}| \|Ax_{n}\| + |\gamma_{n+1} - \gamma_{n}| \|L^{*}(I-T)Lx_{n}\|$$

$$+ \frac{|\lambda_{n+1} - \lambda_{n}|}{a} \|J_{\lambda_{n+1}}^{B}y_{n} - y_{n}\| + \|x_{n+1} - x_{n}\|$$

$$\leq \|x_{n+1} - x_{n}\| + M_{1}|\lambda_{n+1} - \lambda_{n}| + M_{2}|\gamma_{n+1} - \gamma_{n}|,$$

$$(3.11)$$

where M_1 and M_2 are constants defined by

$$M_{1} = \sup_{n} \left(\|Ax_{n}\| + \frac{1}{a} \|J_{\lambda_{n+1}}^{B} y_{n} - y_{n}\| \right),$$

$$M_{2} = \sup_{n} \|L^{*}(I - T)Lx_{n}\|.$$

Therefore it follows from (3.10) and (3.11) that

$$||x_{n+1} - x_n|| \le (1 - \alpha_n (1 - \alpha)) ||x_n - x_{n-1}|| + M_1 |\lambda_{n+1} - \lambda_n| + M_2 |\gamma_{n+1} - \gamma_n| + 2|\alpha_n - \alpha_{n-1}|K.$$

Take

$$\beta_n := \alpha_n (1 - \alpha)$$
 and
$$\delta_n := M_1 |\lambda_{n+1} - \lambda_n| + M_2 |\gamma_{n+1} - \gamma_n| + 2|\alpha_n - \alpha_{n-1}|K.$$

It follows from Lemma 2.8 that

$$\lim_{n \to \infty} \|x_{n+1} - x_n\| = 0. \tag{3.12}$$

Now, we write

$$x_{n+1} - x_n = \alpha_n f(x_n) + (1 - \alpha_n) S u_n - x_n$$

= $\alpha_n (f(x_n) - x_n) + (1 - \alpha_n) (S u_n - x_n).$

Since $||x_{n+1} - x_n|| \to 0$ and $\alpha_n \to 0$ as $n \to \infty$, we obtain

$$\lim_{n \to \infty} \|Su_n - x_n\| = 0. \tag{3.13}$$

Next, we prove that

$$\lim_{n \to \infty} ||x_n - u_n|| = \lim_{n \to \infty} ||x_n - T_n x_n|| = 0.$$

In fact, it follows from (3.4) and (3.6) That

$$||x_{n+1} - p||^2 = ||\alpha_n f(x_n) + (1 - \alpha_n) S u_n - p||^2$$

$$\leq \alpha_n ||f(x_n) - p||^2 + (1 - \alpha_n) ||S u_n - p||^2$$

$$\leq \alpha_n ||f(x_n) - p||^2 + (1 - \alpha_n) ||u_n - p||^2$$

$$\leq \alpha_n ||f(x_n) - p||^2 + (1 - \alpha_n) (||x_n - p||^2 - (1 - \xi_n) ||x_n - T_n x_n||^2)$$

$$\leq \alpha_n ||f(x_n) - p||^2 + ||x_n - p||^2 - (1 - \xi_n) ||x_n - T_n x_n||^2.$$

Hence, we obtain

$$(1 - \xi_n) \|x_n - T_n x_n\|^2 \le \alpha_n \|f(x_n) - p\|^2 + (\|x_n - p\|^2 - \|x_{n+1} - p\|^2)$$

$$\le \alpha_n \|f(x_n) - p\|^2 + (\|x_n - p\| + \|x_{n+1} - p\|) \|x_n - x_{n+1}\|.$$

Since $\alpha_n \to 0$ as $n \to \infty$, and $\xi_n = \frac{3+2\gamma_n\|L\|^2}{4} \in (\frac{3}{4}, 1)$, from (3.12) we obtain

$$\lim_{n \to \infty} \|u_n - x_n\| = \|x_n - T_n x_n\| = 0. \tag{3.14}$$

Therefore we have

$$||Su_n - u_n|| \le ||Su_n - x_n|| + ||x_n - u_n|| \to 0, \quad \text{as } n \to \infty.$$
 (3.15)

On the other hand, since $\{x_n\}$ is bounded, let $\{x_{n_j}\}$ be any subsequence of $\{x_n\}$ with $x_{n_j} \to \hat{x}$. Also, we assume that $\lambda_{n_j} \to \hat{\lambda} \in (0, \frac{\beta}{2})$ and $\gamma_{n_j} \to \hat{\gamma} \in (0, \frac{1}{2\|L\|^2})$. Letting

$$\hat{T} = J_{\hat{\lambda}}^B \big((I - \hat{\lambda} A) - \hat{\gamma} L^* (I - T) L \big),$$

we know that \hat{T} is $\frac{3+2\hat{\gamma}\|L\|^2}{4}$ -averaged and $F(\hat{T}) = \Omega_{L,T}^{A+B}$. Hence, for each $j \in \mathbb{N}$ we have

$$||x_{n_{j}} - \hat{T}x_{n_{j}}|| \leq ||x_{n_{j}} - u_{n_{j}}|| + ||T_{n_{j}}x_{n_{j}} - \hat{T}x_{n_{j}}||$$

$$\leq ||x_{n_{j}} - u_{n_{j}}|| + ||J_{\lambda_{n_{j}}}^{B}z_{j} - J_{\hat{\lambda}}^{B}z_{j}|| + ||J_{\hat{\lambda}}^{B}z_{j} - \hat{T}x_{n_{j}}||,$$
(3.16)

where $z_j = ((I - \lambda_{n_j} A) - \gamma_{n_i} L^*(I - T)L)x_{n_i}$. Now, we estimate the last term in (3.16). We have

$$\begin{aligned} \|J_{\hat{\lambda}}^{B}z_{j} - \hat{T}x_{n_{j}}\| &= \|J_{\hat{\lambda}}^{B}((I - \lambda_{n_{j}}A) - \gamma_{n_{j}}L^{*}(I - T)L)x_{n_{j}} - J_{\hat{\lambda}}^{B}((I - \hat{\lambda}A) - \hat{\gamma}L^{*}(I - T)L)x_{n_{j}}\| \\ &\leq \|((I - \lambda_{n_{j}}A) - \gamma_{n_{j}}L^{*}(I - T)L)x_{n_{j}} - ((I - \hat{\lambda}A) - \hat{\gamma}L^{*}(I - T)L)x_{n_{j}}\| \\ &\leq \|(\lambda_{n_{j}} - \hat{\lambda})Ax_{n_{j}}\| + \|(\gamma_{n_{j}} - \hat{\gamma})L^{*}(I - T)Lx_{n_{j}}\| \\ &\leq \|\lambda_{n_{i}} - \hat{\lambda}\|Ax_{n_{i}}\| + 2\|\gamma_{n_{i}} - \hat{\gamma}\|L^{*}\|\|L\|\|x_{n_{i}} - p\| \end{aligned}$$

for each $j \in \mathbb{N}$. This implies that

$$\lim_{i \to \infty} \|J_{\hat{\lambda}}^B z_j - \hat{T} x_{n_j}\| = 0. \tag{3.17}$$

Next, we estimate the second term in (3.16). By Lemma 2.5, we have

$$\begin{split} \|J_{\lambda_{n_{j}}}^{B}z_{j} - J_{\hat{\lambda}}^{B}z_{j}\| &= \left\|J_{\hat{\lambda}}^{B}\left(\frac{\hat{\lambda}}{\lambda_{n_{j}}}z_{j} + \left(1 - \frac{\hat{\lambda}}{\lambda_{n_{j}}}\right)J_{\lambda_{n_{j}}}^{B}z_{j}\right) - J_{\hat{\lambda}}^{B}z_{j}\right\| \\ &\leq \left\|\frac{\hat{\lambda}}{\lambda_{n_{j}}}z_{j} + \left(1 - \frac{\hat{\lambda}}{\lambda_{n_{j}}}\right)J_{\lambda_{n_{j}}}^{B}z_{j} - z_{j}\right\| \\ &= \left\|\left(1 - \frac{\hat{\lambda}}{\lambda_{n_{j}}}\right)J_{\lambda_{n_{j}}}^{B}z_{j} - \left(1 - \frac{\hat{\lambda}}{\lambda_{n_{j}}}\right)z_{j}\right\| \\ &= \left\|\left(1 - \frac{\hat{\lambda}}{\lambda_{n_{j}}}\right)\left(J_{\lambda_{n_{j}}}^{B}z_{j} - z_{j}\right)\right\| \\ &= \left\|1 - \frac{\hat{\lambda}}{\lambda_{n_{j}}}\right\|J_{\lambda_{n_{j}}}^{B}z_{j} - z_{j}\right\|, \quad \forall j \geq 1. \end{split}$$

$$(3.18)$$

Also for each $j \in \mathbb{N}$ we have

$$\begin{aligned} \|J_{\lambda_{n_{j}}}^{B}z_{j}-z_{j}\| &= \|T_{n_{j}}x_{n_{j}}-z_{j}\| \\ &= \|u_{n_{j}}-x_{n_{j}}+\lambda_{n_{j}}Ax_{n_{j}}+\gamma_{n_{j}}L^{*}(I-T)Lx_{n_{j}}\| \\ &\leq \|u_{n_{j}}-x_{n_{j}}\|+\lambda_{n_{j}}\|Ax_{n_{j}}\|+\gamma_{n_{j}}\|L^{*}(I-T)Lx_{n_{j}}\| \\ &\leq \|u_{n_{i}}-x_{n_{i}}\|+\lambda_{n_{i}}\|Ax_{n_{i}}\|+2\gamma_{n_{i}}\|L^{*}\|\|L\|\|x_{n_{i}}-p\|. \end{aligned}$$

This shows that $\{\|(J_{\lambda_{n_i}}^B z_j - z_j)\|\}$ is a bounded sequence. This, together with (3.18), implies

$$\lim_{i \to \infty} \left\| J_{\lambda_{n_i}}^B z_j - J_{\hat{\lambda}}^B z_j \right\| = 0. \tag{3.19}$$

Substituting (3.14), (3.17) and (3.19) into (3.16), we get

$$\lim_{j \to \infty} \|x_{n_j} - \hat{T}x_{n_j}\| = 0. \tag{3.20}$$

Thus, by Lemma 2.6, it follows that $\hat{x} \in F(\hat{T}) = \Omega_{L,T}^{A+B}$.

Furthermore, it follows from (3.13) and (3.14) that $\{u_n\}$, $\{x_n\}$ and $\{S(u_n)\}$ have the same asymptotical behavior, so $\{u_n\}$ also converges weakly to \hat{x} . Since S is nonexpansive, by (3.13) and Lemma 2.6, we obtain that $\hat{x} \in F(S)$. Thus $\hat{x} \in \Omega_{L,T}^{A+B} \cap F(S)$.

Next, we claim that

$$\lim \sup_{n \to \infty} \langle f(z) - z, x_n - z \rangle \le 0, \tag{3.21}$$

where $z = P_{F(S) \cap \Omega_{L,T}^{A+B}} f(z)$.

Indeed, we have

$$\limsup_{n \to \infty} \langle f(z) - z, x_n - z \rangle = \limsup_{n \to \infty} \langle f(z) - z, Su_n - z \rangle$$

$$\leq \limsup_{n \to \infty} \langle f(z) - z, u_n - z \rangle$$

$$= \langle f(z) - z, \hat{x} - z \rangle$$

$$\leq 0, \tag{3.22}$$

since $z = P_{F(S) \cap \Omega_{L,T}^{A+B}} f(z)$.

Finally, we show that $x_n \to z$. Indeed, we have

$$||x_{n+1} - z||^{2} = \langle \alpha_{n} f(x_{n}) + (1 - \alpha_{n}) S u_{n} - z, x_{n+1} - z \rangle$$

$$= \alpha_{n} \langle f(x_{n}) - z, x_{n+1} - z \rangle + (1 - \alpha_{n}) \langle S u_{n} - z, x_{n+1} - z \rangle$$

$$\leq \alpha_{n} \langle f(x_{n}) - z, x_{n+1} - z \rangle + (1 - \alpha_{n}) \langle u_{n} - z, x_{n+1} - z \rangle$$

$$\leq \alpha_{n} \langle f(x_{n}) - f(z), x_{n+1} - z \rangle + \alpha_{n} \langle f(z) - z, x_{n+1} - z \rangle$$

$$+ (1 - \alpha_{n}) \langle x_{n} - z, x_{n+1} - z \rangle$$

$$\leq \frac{\alpha_{n}}{2} \{ ||f(x) - f(z)||^{2} + ||x_{n+1} - z||^{2} \} + \alpha_{n} \langle f(z) - z, x_{n+1} - z \rangle$$

$$+ \frac{(1 - \alpha_{n})}{2} \{ ||x_{n} - z||^{2} + ||x_{n+1} - z||^{2} \}$$

$$\leq \frac{1}{2} (1 - \alpha_{n} (1 - \alpha^{2})) ||x_{n} - z||^{2} + \frac{(1 - \alpha_{n})}{2} ||x_{n+1} - z||^{2}$$

$$+ \frac{\alpha_{n}}{2} ||x_{n+1} - z||^{2} + \alpha_{n} \langle f(z) - z, x_{n+1} - z \rangle,$$

which implies that

$$||x_{n+1}-z||^2 \le (1-\alpha_n(1-\alpha^2))||x_n-z||^2 + 2\alpha_n\langle f(z)-z,x_{n+1}-z\rangle.$$

Now, by using (3.22) and Lemma 2.8, we deduce that $x_n \to z$. Further it follows from $||u_n - x_n|| \to 0$, $u_n \rightharpoonup \hat{x} \in F(S) \cap \Omega_{L,T}^{A+B}$ and $x_n \to z$ as $n \to \infty$, that $z = \hat{x}$. This completes the proof.

If A := 0, the zero operator, then the following result can be obtained from Theorem 3.2 immediately.

Corollary 3.3 Let H_1 and H_2 be Hilbert spaces. Let $B: H_1 \to 2^{H_1}$ be a maximal monotone operator, $T: H_2 \to H_2$ a nonexpansive mapping and $L: H_1 \to H_2$ a bounded linear operator. Let $S: H_1 \to H_1$ be a nonexpansive mapping such that $\Gamma = F(S) \cap B^{-1}(0) \cap L^{-1}(F(T)) \neq \emptyset$. Let $f: H_1 \to H_1$ be a contraction mapping with a contractive constant $\alpha \in (0,1)$. For any given $x_0 \in H_1$, let $\{u_n\}$ and $\{x_n\}$ be the sequences generated by

$$\begin{cases} u_n = J_{\lambda_n}^B((I - \gamma_n L^*(I - T)L)x_n, \\ x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n)Su_n, \end{cases} \quad \forall n \ge 0.$$
 (3.23)

If the sequences $\{\alpha_n\}$, $\{\lambda_n\}$ and $\{\gamma_n\}$ satisfy all the conditions in Theorem 3.2, then the sequences $\{u_n\}$ and $\{x_n\}$ both converge strongly to $z = P_{\Gamma}f(z)$ which is a solution of problem (1.5) with A = 0.

If $H_1 = H_2$, L = I, then by applying Theorem 3.2, we can obtain the following result.

Corollary 3.4 Let H_1 be Hilbert spaces. Let $A: H_1 \to H_1$ be a β -ism and $B: H_1 \to 2^{H_1}$ be a maximal monotone operator. Let $S: H_1 \to H_1$ be a nonexpansive mapping such that $\Gamma_1 = F(S) \cap (A+B)^{-1} \cap F(T) \neq \emptyset$. Let $f: H_1 \to H_1$ be a contraction mapping with constant $\alpha \in (0,1)$. For any $x_0 \in H_1$ arbitrarily, let the iterative sequences $\{u_n\}$ and $\{x_n\}$ be generated by

$$x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n) S J_{\lambda_n}^B \left((I - \lambda_n A) - \gamma_n (I - T) \right) x_n. \tag{3.24}$$

If the sequences $\{\alpha_n\}$, $\{\lambda_n\}$ and $\{\gamma_n\}$ satisfy all the conditions in Theorem 3.2, then the sequences $\{u_n\}$ and $\{x_n\}$ both converge strongly to $z \in \Gamma_1$, where $z = P_{\Gamma_1} f(z)$.

4 Applications

In this section, we will utilize the results presented in the paper to study variational inequality problems, convex minimization problem and split common fixed point problem in Hilbert spaces.

4.1 Application to variational inequality problem

Let *C* be a nonempty closed and convex subset of a Hilbert space *H*. Recall that the normal cone to *C* at $u \in C$ is defined by

$$N_C(u) = \big\{ z \in H : \langle z, y - u \rangle \le 0, \forall y \in C \big\}.$$

It is well known that N_C is a maximal monotone operator. In the case $B := N_C : H \to 2^H$ we can verify that the problem of finding $x^* \in H$ such that $0 \in Ax^* + Bx^*$ is reduced to the problem of finding $x^* \in C$ such that

$$\langle Ax^*, x - x^* \rangle \ge 0, \quad \forall x \in C.$$
 (4.1)

In the sequel, we denote by VIP(C,A) the solution set of problem (4.1). In this case, we also have $J_{\lambda}^{B} = P_{C}$ (the metric projection of H onto C). By the above consideration, problem (1.5) is reduced to finding

$$x^* \in VIP(C, A)$$
 such that $Lx^* \in F(T)$ and $x^* \in F(S)$. (4.2)

Therefore, the following convergence theorem can be immediately obtained from Theorem 3.2.

Theorem 4.1 Let H_1 and H_2 be Hilbert spaces. Let $A: H_1 \to H_1$ be a β -ism operator, $T: H_2 \to H_2$ a nonexpansive mapping and $L: H_1 \to H_2$ a bounded linear operator. Let $S: H_1 \to H_1$ be a nonexpansive mapping such that $F(S) \cap \Omega_{L,T}^{A,C} \neq \emptyset$, where

$$\Omega_{L,T}^{A,C} := \text{VIP}(C,A) \cap L^{-1}(F(T)).$$

Let $f: H_1 \to H_1$ be a contraction mapping with a contractive constant $\alpha \in (0,1)$. For any given $x_0 \in H_1$, let the sequences $\{u_n\}$ and $\{x_n\}$ be generated by

$$\begin{cases} u_n = P_C((I - \lambda_n A) - \gamma_n L^*(I - T)L)x_n, \\ x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n)Su_n, \end{cases}$$
(4.3)

where $\{\alpha_n\}$ is a sequence in (0,1) such that $\lim_{n\to\infty}\alpha_n=0$, $\sum_{n=0}^\infty\alpha_n=\infty$, $\sum_{n=1}^\infty|\alpha_n-\alpha_{n-1}|<\infty$, L^* is the adjoint of L, and the sequences $\{\lambda_n\}$ and $\{\gamma_n\}$ satisfy conditions (i)–(ii) in Theorem 3.2. Then the sequences $\{u_n\}$ and $\{x_n\}$ both converge strongly to $z=P_{F(S)\cap\Omega_{L,T}^{A,C}}f(z)$, which is a solution of problem (4.2).

4.2 Application to convex minimization problem

Let $g: H \to R$ be a convex function, which is also Fréchet differentiable. Let C be a given closed convex subset of H. In this case, by setting $A := \nabla g$, the gradient of g, and $B = N_C$, the problem of finding $x^* \in (A + B)^{-1}0$ is equivalent to finding a point $x^* \in C$ such that

$$\langle \nabla g(x^*), x - x^* \rangle \ge 0, \quad \forall x \in C.$$
 (4.4)

Note that (4.4) is equivalent to the following minimization problem: find $x^* \in C$ such that

$$x^* \in \arg\min_{x \in C} g(x).$$

Thus, in this situation, problem (1.5) is reduced to the problem of finding

$$x^* \in \arg\min_{x \in C} g(x)$$
 such that $Lx^* \in F(T)$ and $x^* \in F(S)$. (4.5)

Denote by

$$\Omega_{L,T}^{g,C} := \arg\min_{x \in C} g(x) \cap L^{-1}(F(T)).$$

Then, by using Theorem 3.2, we can obtain the following result.

Theorem 4.2 Let H_1 and H_2 be Hilbert spaces and let C be a nonempty closed convex subset of H_1 . Let $g: H_1 \to \mathbb{R}$ be a convex and Fréchet differentiable function, ∇g be β -Lipschitz, $T: H_2 \to H_2$ be a nonexpansive mapping, and let $L: H_1 \to H_2$ be a bounded linear operator. Let $S: H_1 \to H_1$ be a nonexpansive mapping such that $F(S) \cap \Omega_{L,T}^{g,C} \neq \emptyset$. Let $f: H_1 \to H_1$ be a contraction mapping with a contractive constant $\alpha \in (0,1)$. For any given $x_0 \in H_1$, let $\{u_n\}$ and $\{x_n\}$ be the sequences generated by

$$\begin{cases} u_n = P_C((I - \lambda_n \nabla g) - \gamma_n L^*(I - T)L)x_n, \\ x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n)Su_n, \end{cases} \quad \forall n \ge 0.$$

$$(4.6)$$

If the sequences $\{\alpha_n\}$, $\{\lambda_n\}$ and $\{\gamma_n\}$ satisfy all the conditions in Theorem 3.2, then the sequences $\{u_n\}$ and $\{x_n\}$ both converge strongly to $z \in F(S) \cap \Omega_{L,T}^{g,C}$, where $z = P_{F(S) \cap \Omega_{L,T}^{g,C}}(z)$, which is a solution of problem (4.5).

Proof Note that if $g: H \to \mathbb{R}$ is convex and $\nabla g: H \to H$ is β -Lipschitz continuous for $\beta > 0$ then ∇g is $\frac{1}{\beta}$ -ism (see [24]). Thus, the required result can be obtained immediately from Theorem 3.2.

4.3 Application to split common fixed point problem

Let $V: H_1 \to H_1$ be a nonexpansive mapping. Then, by Lemma 2.1(iii), we know that A:=I-V is $\frac{1}{2}$ -ism. Furthermore, $Ax^*=0$ if and only if $x^*\in F(V)$. Hence problem (1.5) can be reduced to the problem of finding

$$x^* \in F(V)$$
 such that $Lx^* \in F(T)$ and $x^* \in F(S)$, (4.7)

where $T: H_2 \to H_2$, $L: H_1 \to H_2$ and $S: H_1 \to H_1$ are mappings as in Theorem 3.2.

This problem is called the split common fixed point problem (SCFP), and was studied by many authors (see [25-28], for example). By using Theorem 3.2, we can obtain the following result.

Theorem 4.3 Let H_1 and H_2 be Hilbert spaces. Let $V: H_1 \to H_1$ and $T: H_2 \to H_2$ be nonexpansive mappings and $L: H_1 \to H_2$ a bounded linear operator. Let $S: H_1 \to H_1$ be a nonexpansive mapping such that $F(S) \cap \Omega_{L,T}^V \neq \emptyset$, where

$$\Omega_{L,T}^{V} := F(V) \cap L^{-1}(F(S)).$$

Let $f: H_1 \to H_1$ be a contraction mapping with a contractive constant $\alpha \in (0,1)$. For any given $x_0 \in H_1$, let be $\{u_n\}$ and $\{x_n\}$ be the iterative sequences generated by

$$\begin{cases} u_n = (I - \lambda_n)x_n + \lambda_n V x_n - \gamma_n L^*(I - T)L x_n, \\ x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n)S u_n, \end{cases} \quad \forall n \ge 0,$$

$$(4.8)$$

where the sequences $\{\alpha_n\}$, $\{\lambda_n\}$ and $\{\gamma_n\}$ satisfy all the conditions in Theorem 3.2. Then the sequences $\{u_n\}$ and $\{x_n\}$ both converge strongly to a point $z = P_{F(S) \cap \Omega_{L,T}^V} f(z)$, which is a solution of problem (4.7).

Proof We consider B := 0, the zero operator. The required result follows from the fact that the zero operator is monotone and continuous, hence it is maximal monotone. Moreover, in this case, we see that J_{λ}^{B} is the identity operator on H_{1} , for each $\lambda > 0$. Thus algorithm (3.4) reduces to (4.8), by setting A := I - V and B := 0.

Acknowledgements

The authors would like to express their thanks to the Editor and the Referees for their helpful comments.

Funding

The first author was supported by Scientific Research Fund of Sichuan Provincial Department of Science and Technology (2015JY0165), the second author was supported by Scientific Research Fund of Sichuan Provincial Education Department (16ZA0331) and the third author was supported by The Natural Science Foundation of China Medical University, Taichung, Taiwan.

Availability of data and materials

Not applicable.

Competing interests

None of the authors have any competing interests in the manuscript.

Authors' contributions

All authors contributed equally and significantly in writing this article. All authors read and approved the final manuscript.

Author details

¹Department of Mathematics, Yibin University, Yibin, China. ²Center for General Education, China Medical University, Taichung, Taiwan.

Publisher's Note

Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

Received: 6 July 2018 Accepted: 14 October 2018 Published online: 23 October 2018

References

- Censor, Y., Elfving, T.: A multiprojection algorithm using Bregman projections in product space. Numer. Algorithms 8, 221–239 (1994)
- Byrne, C.: Iterative oblique projection onto convex sets and the split feasibility problem. Inverse Probl. 18, 441–453
 (2002)
- 3. Censor, Y., Bortfeld, T., Martin, B., Trofimov, A.: A unified approach for inversion problems in intensity-modulated radiation therapy. Phys. Med. Biol. **51**, 2353–2365 (2006)
- Martinet, B.: Régularisation dinéquations variationnelles par approximations successives. Rev. Fr. Inform. Rech. Opér. 3, 154–158 (1970)
- 5. Bruck, R.E., Reich, S.: Nonexpansive projections and resolvents of accretive operators in Banach spaces. Houst. J. Math. 3. 459–470 (1977)
- 6. Eckstein, J., Bertsckas, D.P.: On the Douglas–Rachford splitting method and the proximal point algorithm for maximal monotone operators. Math. Program. 55, 293–318 (1992)
- 7. Marino, G., Xu, H.K.: Convergence of generalized proximal point algorithm. Commun. Pure Appl. Anal. 3, 791–808 (2004)
- 8. Xu, H.K.: Iterative algorithms for nonlinear operators. J. Lond. Math. Soc. 66, 240–256 (2002)
- 9. Yao, Y., Noor, M.A.: On convergence criteria of generalized proximal point algorithms. J. Comput. Appl. Math. 217, 46–55 (2008)
- Montira, S., Narin, P., Suthep, S.: Weak convergence theorems for split feasibility problems on zeros of the sum of monotone operators and fixed point sets in Hilbert spaces. Fixed Point Theory Appl. 2017, Article ID 6 (2017)
- 11. Byrne, C., Censor, Y., Gibali, A., Reich, S.: Weak and strong convergence of algorithms for the split common null point problem. J. Nonlinear Convex Anal. 13, 759–775 (2012)
- Takahashi, W., Xu, H.K., Yao, J.C.: Iterative methods for generalized split feasibility problems in Hilbert spaces. Set-Valued Var. Anal. 23, 205–221 (2015)
- 13. Passty, G.B.: Ergodic convergence to a zero of the sum of monotone operators in Hilbert space. J. Math. Anal. Appl. 72, 383–390 (1979)
- 14. Baillon, J.B., Bruck, R.E., Reich, S.: On the asymptotic behavior of nonexpansive mappings and semigroups in Banach spaces. Houst. J. Math. 4, 1–9 (1978)
- 15. Boikanyo, O.A.: The viscosity approximation forward-backward splitting method for zeros of the sum of monotone operators. Abstr. Appl. Anal. 2016, Article ID 2371857 (2016)
- 16. Xu, H.K.: Averaged mappings and the gradient-projection algorithm. J. Optim. Theory Appl. 150, 360–378 (2011)
- Byrne, C.: A unified treatment of some iterative algorithms in signal processing and image reconstruction. Inverse Probl. 20, 103–120 (2004)
- 18. Goebel, K., Reich, S.: Uniform Convexity, Hyperbolic Geometry, and Nonexpansive Mappings. Dekker, New York (1984)
- 19. Takahashi, W.: Introduction to Nonlinear and Convex Analysis. Yokohama Publishers, Yokohama (2009)
- 20. Takahashi, S., Takahashi, W., Toyoda, M.: Strong convergence theorems for maximal monotone operators with nonlinear mappings in Hilbert spaces. J. Optim. Theory Appl. 147, 27–41 (2010)
- 21. Barbu, V.: Nonlinear Semigroups and Differential Equations in Banach Spaces. Noordhoff, Leiden (1976)
- 22. Takahashi, W.: Nonlinear Functional Analysis: Fixed Point Theory and Its Applications. Yokohama Publishers, Yokohama (2000)
- 23. Xu, H.K.: Viscosity approximation methods for nonexpansive mapping. J. Math. Anal. Appl. 298, 279–291 (2004)
- Baillon, J.B., Haddad, G.: Quelques propriétés des opérateurs angle-bornés et n-cycliquement monotones. Isr. J. Math. 26(2), 137–150 (1977)
- Cui, H., Wang, F.: Iterative methods for the split common fixed point problem in Hilbert spaces. Fixed Point Theory Appl. 2014, Article ID 78 (2014)
- Moudafi, A.: A note on the split common fixed-point problem for quasi-nonexpansive operators. Nonlinear Anal., Theory Methods Appl. 74, 4083–4087 (2011)
- Shimizu, T., Takahashi, W.: Strong convergence to common fixed points of families of nonexpansive mappings.
 J. Math. Anal. Appl. 211, 71–83 (1997)
- 28. Zhao, J., He, S.: Strong convergence of the viscosity approximation process for the split common fixed-point problem of quasi-nonexpansive mappings. J. Appl. Math. 2012, Article ID 438023 (2012)