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The obstacle problem for conformal metrics on compact Riemannian manifolds

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Abstract

We prove a priori estimates up to their second order derivatives for solutions to the obstacle problem of curvature equations on Riemannian manifolds (M^n , g) arising from conformal deformation. With the a priori estimates the existence of a $C^{1,1}$ solution to the obstacle problem with Dirichlet boundary value is obtained by approximation.

Keywords: Obstacle problem; A priori estimates; Hessian equations; Viscosity solutions; Riemannian manifolds

1 Introduction

Let (M^n, g) be a compact Riemannian manifold of dimension $n \ge 3$ with smooth boundary ∂M , $\overline{M} := M \cup \partial M$. In conformal geometry, it is interesting to find a complete metric $\tilde{g} \in [g]$, the conformal class of g, with which the manifold has prescribed curvature. In general, such conformal deformation can be interpreted by certain partial differential equations. See [8, 13, 22, 25, 26] for more details.

In [8], Guan studied the existence of a complete conformal metric \tilde{g} of negative Ricci curvature on *M* satisfying

$$f(-\lambda(\tilde{g}^{-1}\operatorname{Ric}_{\tilde{g}})) = \psi \quad \text{in } M, \tag{1.1}$$

where $\operatorname{Ric}_{\tilde{g}}$ is the Ricci tensor of \tilde{g} , and $\lambda(\tilde{g}^{-1}\operatorname{Ric}_{\tilde{g}}) = (\lambda_1, \dots, \lambda_n)$ are the eigenvalues of $\tilde{g}^{-1}\operatorname{Ric}_{\tilde{g}}$. The transformation formula for the Ricci tensor under conformal deformation $\tilde{g} = e^{2u}g$ is given by

$$\frac{1}{n-2}\operatorname{Ric}_{\tilde{g}} = \frac{1}{n-2}\operatorname{Ric}_{g} - \nabla^{2}u - \left(\frac{\Delta u}{n-2} + |\nabla u|^{2}\right)g + du \otimes du,$$

where ∇u , $\nabla^2 u$, and Δu denote the gradient, Hessian, and Laplacian of u with respect to the metric g, respectively. When f is homogenous of degree one, it is easy to verify that equation (1.1) is equivalent to the following form:

$$f\left(\lambda\left(g^{-1}\left[\nabla^2 u + \frac{\Delta u}{n-2}g + |\nabla u|^2 g - du \otimes du - \frac{\operatorname{Ric}_g}{n-2}\right]\right)\right) = \frac{\psi(x)}{n-2}e^{2u}.$$
(1.2)

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In this paper, we study the obstacle problem of equation (1.2). More generally, let

$$T[u] := \nabla^2 u + s \, du \otimes du + \left(\gamma \, \Delta u - \frac{t}{2} |\nabla u|^2\right) g + \chi,$$

where χ is a smooth (0, 2) tensor, $\gamma > 0$ is a constant, and $s, t \in \mathbb{R}$. We consider the following equation:

$$\max\{u - h, -(f(\lambda(g^{-1}T[u])) - \psi[u])\} = 0 \quad \text{in } M$$
(1.3)

with the Dirichlet boundary condition

$$u = \varphi \quad \text{on } \partial M, \tag{1.4}$$

where $h \in C^3(\overline{M})$, $\varphi \in C^4(\partial M)$, $h > \varphi$ on ∂M , $\psi[u] = \psi(x, u)$ is a positive function in $C^3(\overline{M} \times \mathbb{R})$.

Equations as (1.1) and (1.3) are the Hessian equations, which were well studied by many authors such as [2, 7, 9–12, 23, 24]. Generally, $f \in C^2(\Gamma) \cap C^0(\overline{\Gamma})$ is a symmetric function of $\lambda \in \mathbb{R}^n$, defined in an open, convex, and symmetric cone $\Gamma \subsetneq \mathbb{R}^n$, with vertex at the origin, which contains the positive cone: $\Gamma_n^+ := \{\lambda \in \mathbb{R}^n : \text{each component } \lambda_i > 0\}$ and satisfies the following fundamental structure conditions:

$$f_i \equiv \frac{\partial f}{\partial \lambda_i} > 0 \quad \text{in } \Gamma, 1 \le i \le n,$$
(1.5)

$$f$$
 is a concave function, (1.6)

and

$$f > 0 \quad \text{in } \Gamma, \qquad f = 0 \quad \text{on } \partial \Gamma.$$
 (1.7)

Here, for convenience, we also assume that

$$f$$
 is homogeneous of degree one. (1.8)

We observe that by the concavity and homogeneity of f,

$$\sum f_i(\lambda) = f(\lambda) + \sum f_i(\lambda)(1 - \lambda_i) \ge f(1, \dots, 1) > 0 \quad \text{in } \Gamma.$$
(1.9)

Important classes of f are the elementary symmetric functions and their quotients, i.e.,

$$f(\lambda) = (\sigma_k)^{\frac{1}{k}}(\lambda) := \left(\sum_{1 \le i_1 < \dots < i_k \le n} \lambda_{i_1} \cdots \lambda_{i_k}\right)^{\frac{1}{k}}, \quad 1 \le k \le n,$$

and

$$f(\lambda) = \left(\frac{\sigma_k}{\sigma_l}\right)^{\frac{1}{k-l}}, \quad 0 \le l < k \le n.$$

Let *F* be defined by $F(r) = f(\lambda(r))$ for $r = \{r_{ij}\} \in S^{n \times n}$ with $\lambda(r) \in \Gamma$, where $S^{n \times n}$ is the set of $n \times n$ symmetric matrices. It is shown in [2] that (1.5) implies *F* is an elliptic operator and (1.6) ensures that *F* is concave.

A function $u \in C^2(M)$ is called *admissible* at $x \in M$ if $\lambda(g^{-1}T[u])(x) \in \Gamma$, and we call it *admissible* in M when it is admissible at each x in M. In this paper, we prove the existence of an admissible viscosity solution of (1.3) and (1.4) in $C^{1,1}(\overline{M})$ (see [1, 3] for the definition of viscosity solutions).

Many authors have studied various obstacle problems. In [6], Gerhardt considered a hypersurface bounded from below by an obstacle with prescribed mean curvature in \mathbb{R}^n . Lee [17] considered the obstacle problem for the Monge–Ampère equation (i.e., $f = (\sigma_n)^{\frac{1}{n}}$) for the case that $T[u] = D^2 u$, $\psi \equiv 1$, and $\varphi \equiv 0$, and proved the $C^{1,1}$ regularity of the viscosity solution in a strictly convex domain in \mathbb{R}^n . Xiong and Bao [27] extended the work of Lee to a nonconvex domain in \mathbb{R}^n with general ψ and φ under additional assumptions. Bao, Dong, and Jiao treated a class of obstacle problems in [1] assuming that $T[u] = \nabla^2 u + A(x, u, \nabla u)$, under a certain technical assumption. Because of the term $\gamma \Delta u$ ($\gamma > 0$), here we only need a minimal amount of assumptions. For other works, see [4, 14, 15, 18–21].

Our main result is the following theorem.

Theorem 1.1 Assume that (1.5)-(1.8) and either the following condition

$$\lim_{z \to +\infty} \psi(x, z) = +\infty, \quad \forall x \in \bar{M},$$
(1.10)

or

$$\frac{2s - nt}{1 + n\gamma} < 2\lambda_1 \tag{1.11}$$

hold, where λ_1 is the first eigenvalue of the problem

$$\begin{cases} \Delta u + \lambda (\operatorname{tr} \chi)^{+} u = 0 \quad on \, \bar{M}, \\ u = 0 \qquad on \, \partial M \end{cases}$$
(1.12)

 $(\lambda_1 = +\infty \text{ if tr } \chi \leq 0)$. Then there exists a viscosity solution $u \in C^{1,1}(\overline{M})$ to (1.3) and (1.4), if there exists a subsolution $u \in C^0(\overline{M}) \cap C^1(\overline{M}_{\delta})$ for some $\delta > 0$ such that

$$\begin{cases} f(\lambda(g^{-1}T[\underline{u}])) \ge \psi[\underline{u}], & in M, \\ \underline{u} = \varphi, & on \partial M, \\ \underline{u} \le h, & in M, \end{cases}$$
(1.13)

where $M_{\delta} = \{x \in M : \operatorname{dist}(x, \partial M) \leq \delta\}$. Moreover, we have that $u \in C^{3,\alpha}(E)$ for any $\alpha \in (0, 1)$, and $f(\lambda(g^{-1}T[u])) = \psi[u]$ in E, where $E := \{x \in M : u(x) < h(x)\}$.

Remark 1.2 (1.10), as well as (1.11), is used in Lemma 3.2 to derive an upper bound for *u*. Assumption (1.13) is just applied to derive a lower bound for *u* on *M* and $\nabla_{\nu} u$ on ∂M , where ν is the interior unit normal to ∂M .

Remark 1.3 We can construct some subsolutions of (1.2) satisfying (1.13) as in [15] following ideas from [2] and [7] since

$$|\nabla u|^2 g - du \otimes du$$

is positive definite and that we can obtain a priori upper bound of any admissible function (Lemma 3.2) under additional conditions that there exists a sufficiently large number R > 0 such that at each point $x \in \partial M$,

$$(\kappa_1, \dots, \kappa_{n-1}, R) \in \Gamma, \tag{1.14}$$

where $\kappa_1, \ldots, \kappa_{n-1}$ are the principal curvatures of ∂M with respect to the interior normal, and that for every C > 0 and every compact set K in Γ there is a number R = R(C, K) such that

$$f(R\lambda) \ge C \quad \text{for all } \lambda \in K.$$
 (1.15)

We use a penalization technique to prove the existence of viscosity solutions to (1.3) and (1.4). We shall consider the following singular perturbation problem:

$$\begin{cases} f(\lambda(g^{-1}T[u])) = \psi[u] + \beta_{\varepsilon}(u-h) & \text{in } M, \\ u = \varphi & \text{on } \partial M, \end{cases}$$
(1.16)

where the penalty function $\beta_{\varepsilon} \in C^2(\mathbb{R})$ satisfies

$$\begin{aligned} \beta_{\varepsilon}, \beta_{\varepsilon}', \beta_{\varepsilon}'' &\geq 0 \quad \text{on } \mathbb{R}, \beta_{\varepsilon}(z) = 0, \text{ whenever } z \leq 0; \\ \beta_{\varepsilon}(z) &\to \infty \quad \text{as } \varepsilon \to 0^{+}, \text{ whenever } z > 0. \end{aligned}$$
(1.17)

An example given in [27] is

$$\beta_{\varepsilon}(z) = \begin{cases} 0, & z \le 0, \\ z^3/\varepsilon, & z > 0, \end{cases}$$
(1.18)

for $\varepsilon \in (0, 1)$. Observe that \underline{u} is also a subsolution to (1.16). Let

 $\mathcal{U} = \{u_{\varepsilon} | u_{\varepsilon} \in C^4(\bar{M}) \text{ is an admissible solution of } (1.16) \text{ with } u_{\varepsilon} \geq \underline{u} \text{ on } \bar{M} \}.$

We aim to derive the uniform bound

$$|u_{\varepsilon}|_{C^{2}(\bar{M})} \le C \tag{1.19}$$

for $u_{\varepsilon} \in \mathcal{U}$, where *C* is independent of ε . After establishing (1.19), the equation (1.16) becomes uniformly elliptic by (1.7). By Evans–Krylov [5], [16] theorem, we can derive the $C^{2,\alpha}$ estimates (which may depend on ε) of u_{ε} . Higher estimates can be derived by

Schauder theory. Following the proof as in [8] or [1], we can prove there exists an admissible solution u_{ε} to (1.16). Then we can conclude by (1.19) that there exists a viscosity solution $u \in C^{1,1}(\overline{M})$ to (1.3) and (1.4), see [1, 27].

Thus, our main work is focused on the a priori estimates for admissible solutions up to their second order derivatives. In Sect. 2, we achieve the estimates for second order derivatives. Finally, we end this paper with gradient and C^0 estimates in Sect. 3.

2 Estimates for second order derivatives

In this section, we prove a priori estimates of second order derivatives for admissible solutions. From now on, we drop the subscript ε when there is no possible confusion.

Theorem 2.1 Assume that f satisfies (1.5)–(1.8) and $u \in C^4(\overline{M})$ is an admissible solution to (1.16). Then

$$\sup_{M} \left| \nabla^{2} u \right| \le C \Big(1 + \sup_{\partial M} \left| \nabla^{2} u \right| \Big), \tag{2.1}$$

where C depends on $|u|_{C^{1}(\overline{M})}$ and other known data.

Proof Set

$$W(x) = \max_{\xi \in T_x \mathcal{M}, |\xi|=1} (\nabla_{\xi \xi} u + s |\nabla_{\xi} u|^2) e^{\phi}, \quad x \in \overline{\mathcal{M}},$$

where ϕ is a function to be determined. Assume that W is achieved at an interior point $x_0 \in M$ and a unit direction $\xi \in T_{x_0}M$. Choose a smooth orthonormal local frame e_1, \ldots, e_n about x_0 such that $\xi = e_1$, $\nabla_i e_j(x_0) = 0$ and that $T_{ij}(x_0)$ is diagonal. We write $G = \nabla_{11}u + s|\nabla_1 u|^2$. Assume $G(x_0) > 0$ (otherwise we are done).

At the point x_0 , where the function $\log G + \phi$ (defined near x_0) attains its maximum, we have

$$\frac{\nabla_i G}{G} + \nabla_i \phi = 0, \quad i = 1, \dots, n,$$
(2.2)

and

$$\frac{\nabla_{ii}G}{G} - \left(\frac{\nabla_i G}{G}\right)^2 + \nabla_{ii}\phi \le 0.$$
(2.3)

By (2.3) we have

$$F^{ii}\left(\nabla_{ii}G + G\nabla_{ii}\phi - G|\nabla_i\phi|^2\right) \le 0$$
(2.4)

and

$$\Delta G + G\Delta \phi - G|\nabla \phi|^2 \le 0. \tag{2.5}$$

Since $\gamma > 0$, we obtain

$$F^{ii}\left(\nabla_{ii}G + \gamma \Delta G + G\nabla_{ii}\phi + \gamma G\Delta\phi - G|\nabla_i\phi|^2 - \gamma G|\nabla\phi|^2\right) \le 0.$$
(2.6)

By calculation, we get

$$\nabla_i G = \nabla_{i11} u + 2s \nabla_1 u \nabla_{i1} u, \tag{2.7}$$

and

$$\nabla_{ii}G = \nabla_{ii11}u + 2s(|\nabla_{i1}u|^2 + \nabla_1u\nabla_{ii1}u).$$

$$(2.8)$$

Recall the formula for interchanging order of covariant derivatives

$$\nabla_{ijk}\nu - \nabla_{kij}\nu = R^l_{kij}\nabla_l\nu, \tag{2.9}$$

and

$$\nabla_{ijkl}\nu - \nabla_{klij}\nu = R^m_{ljk}\nabla_{im}\nu + \nabla_i R^m_{ljk}\nabla_m\nu + R^m_{lik}\nabla_{jm}\nu + R^m_{jik}\nabla_{lm}\nu + R^m_{jil}\nabla_{km}\nu + \nabla_k R^m_{jil}\nabla_m\nu.$$
(2.10)

It follows from (2.10)

$$\nabla_{ii}G \ge \nabla_{11ii}u + 2s(|\nabla_{i1}u|^2 + \nabla_1u\nabla_{1ii}u) - C(1+G),$$
(2.11)

and

$$\nabla_{ii}G + \gamma \Delta G \ge \nabla_{11ii}u + 2s(|\nabla_{i1}u|^2 + \nabla_1 u \nabla_{1ii}u) + \gamma \nabla_{11}(\Delta u) + 2s\gamma(|\nabla_{i1}u|^2 + \nabla_1 u \nabla_1(\Delta u)) - C(1+G).$$
(2.12)

Differentiating equation (1.16) once at x_0 , we obtain for $1 \le k \le n$,

$$\nabla_k F = F^{ii} \nabla_k T_{ii} = \psi_{x_k} + \psi_z \nabla_k u + \nabla_k \beta_\varepsilon (u - h).$$
(2.13)

It is easy to see that

$$F^{ii}\nabla_{1}(\nabla_{ii}u + \gamma\Delta u) = F^{ii}\nabla_{1}\left(T_{ii}[u] - s|\nabla_{i}u|^{2} + \frac{t}{2}|\nabla u|^{2} - \chi_{ii}\right)$$

$$\geq \nabla_{1}F - 2sF^{ii}\nabla_{i}u\nabla_{1i}u + t\nabla_{k}u\nabla_{1k}u\sum_{i}F^{ii} - \sum_{i}F^{ii} \qquad (2.14)$$

and that

$$F^{ii} \nabla_{11} (\nabla_{ii} u + \gamma \Delta u) = F^{ii} \nabla_{11} \left(T_{ii} [u] - s |\nabla_i u|^2 + \frac{t}{2} |\nabla u|^2 - \chi_{ii} \right)$$

$$\geq F^{ii} \nabla_{11} T_{ii} [u] - 2s F^{ii} (\nabla_i u \nabla_{11i} u + |\nabla_{1i} u|^2)$$

$$+ t \sum_k (\nabla_k u \nabla_{11k} u + |\nabla_{1k} u|^2) \sum_i F^{ii} - C \sum_i F^{ii}.$$
(2.15)

With (2.9) we see

$$2s\nabla_{i}u\nabla_{11i}u \leq 2s\nabla_{i}u(\nabla_{i}G - 2s\nabla_{1}u\nabla_{i1}u) + C$$

$$\leq -4s^{2}\nabla_{i}u\nabla_{1}u\nabla_{i1}u + C(1 + G|\nabla\phi|), \qquad (2.16)$$

and similarly

$$t\nabla_k u\nabla_{11k} u \ge -2st\nabla_k u\nabla_1 u\nabla_{k1} u - C(1+G|\nabla\phi|).$$
(2.17)

With (2.12), (2.14)–(2.17), and the concavity of *F*, we derive

$$F^{ii}(\nabla_{ii}G + \gamma \Delta G) \ge \nabla_{11}F + 2s\nabla_{1}u\nabla_{1}F + (2s\gamma + t)\sum_{k} |\nabla_{1k}u|^{2}\sum F^{ii}$$
$$-C\left(G + G|\nabla\phi| + \sum_{j,k} |\nabla_{jk}u|\right)$$
$$\ge \nabla_{11}F + 2s\nabla_{1}u\nabla_{1}F - C\left(G^{2} + G|\nabla\phi|\right).$$
(2.18)

By (1.9) and $\beta_{\varepsilon}'' > 0$ it follows from (2.6) and (2.18) that

$$F^{ii}(\nabla_{ii}\phi - |\nabla_i\phi|^2) + \gamma \left(\Delta\phi - |\nabla\phi|^2\right) \sum F^{ii}$$

$$\leq C\left(G + |\nabla\phi|\right) \sum F^{ii} + \left(\frac{C}{G} - 1\right) \beta'_{\varepsilon}(u - h).$$
(2.19)

Let

$$\phi := \eta(w) = \left(1 - \frac{w}{2a}\right)^{-1/2}, \quad w = \frac{|\nabla u|^2}{2},$$

where $a > \sup_M w$ is a constant to be determined. We have

$$1 \leq \eta < \sqrt{2}, \quad \eta' = \frac{\eta^3}{4a}, \qquad \eta'' = \frac{3\eta'^2}{\eta}$$

and

$$\nabla_{ii}\phi - |\nabla_i\phi|^2 = \eta'\nabla_{ii}w + (\eta'' - \eta'^2)|\nabla_iw|^2 \ge \eta'\nabla_{ii}w.$$
(2.20)

Next, by (2.14)

$$F^{ii}(\nabla_{ii}w + \gamma \Delta w)$$

$$= F^{ii}\left(\sum_{l} |\nabla_{il}u|^{2} + \gamma \sum_{k,l} |\nabla_{kl}u|^{2}\right) + F^{ii}\nabla_{l}u\left(\nabla_{iil}u + \gamma \Delta(\nabla_{l}u)\right)$$

$$\geq F^{ii}\nabla_{l}u\left(\nabla_{lii}u + \gamma \sum_{k} \nabla_{lkk}u\right) + \left(\gamma G^{2} - CG\right)\sum F^{ii}$$

$$\geq -C\beta'_{\varepsilon}(u - h) + \left(\gamma G^{2} - CG\right)\sum F^{ii}.$$
(2.21)

Combining (2.19), (2.20), (2.21), and $|\nabla \phi| \le C\eta' G$, we have

$$\eta'(\gamma G^2 - CG) \sum F^{ii} \le C(G + \eta'G) \sum F^{ii} + \left(\frac{C}{G} - 1 + C\eta'\right) \beta_{\varepsilon}'(u - h).$$

$$(2.22)$$

We could assume that $G \ge 2C$. When a > 2C, the coefficient of $\beta'_{\varepsilon}(u - h)$ is negative. Then we can derive $G \le \frac{4aC}{v}$.

To derive the boundary estimates for $\nabla^2 u$, we note that $\operatorname{tr}(sdu \otimes du - \frac{t}{2}|\nabla u|^2 g + \chi) \leq C$ on \overline{M} , where *C* is independent of ε , though it may depend on $|u|_{C^1(\overline{M})}$. As in [1, 4], let *H* be the solution to

$$\begin{cases} (1+n\gamma)\Delta H+C=0 & \text{in } M, \\ H=\varphi & \text{on } \partial M. \end{cases}$$

Then we have $u \le H$ in M by the maximum principle and $\beta_{\varepsilon}(u - h) \equiv 0$ in $M_{\delta} = \{x \in M : \text{dist}(x, \partial M) \le \delta\}$, where δ is sufficiently small. Thus,

$$\begin{cases} f(\lambda(g^{-1}T[u])) = \psi[u] & \text{in } M_{\delta}, \\ u = \varphi & \text{on } \partial M. \end{cases}$$
(2.23)

By the same arguments of Sect. 4 in [8], we obtain that

$$\sup_{\partial M} |\nabla^2 u| \le C, \tag{2.24}$$

where *C* depends on $|u|_{C^1(\overline{M})}$ and other known data.

Combining (2.1) and (2.24), we therefore get the full estimates for second order derivatives.

3 Gradient estimates, maximum principle, and existence

For the gradient estimates, we have the following theorem.

Theorem 3.1 Assume that (1.5)–(1.8) hold. Let $u \in C^3(\overline{M})$ be an admissible solution to (1.16). Then

$$\sup_{M} |\nabla u| \le C \Big(1 + \sup_{\partial M} |\nabla u| \Big), \tag{3.1}$$

where C depends on $|u|_{C^0(\overline{M})}$ and other known data.

Proof Suppose that we^{ϕ} , where $w = \frac{|\nabla u|^2}{2}$ and $\phi = \phi(u)$ to be determined satisfying that $\phi'(u) > 0$, achieves a maximum at an interior point $x_0 \in M$. As before, we choose a smooth orthonormal local frame e_1, \ldots, e_n about x_0 such that $\nabla_{e_i} e_j = 0$ at x_0 and $\{T_{ij}(x_0)\}$ is diagonal. Differentiating we^{ϕ} at x_0 twice, we have

$$\nabla_i w + w \nabla_i \phi = 0 \tag{3.2}$$

and

$$\nabla_{ii}w - w(\nabla_i\phi)^2 + w\nabla_{ii}\phi \le 0. \tag{3.3}$$

Differentiating *w*, we see

$$\nabla_i w = \sum_k \nabla_k u \nabla_{ik} u, \qquad \nabla_{ii} w = \sum_k (\nabla_{ik} u)^2 + \sum_k \nabla_k u \nabla_{iik} u.$$

Using (3.2) it follows from (3.3) that

$$F^{ii}\left(\delta_{kl} - \frac{\nabla_k u \nabla_l u}{2w}\right) \nabla_{ik} u \nabla_{il} u + F^{ii} \nabla_k u \nabla_{iik} u - w F^{ii}\left(\frac{(\nabla_i \phi)^2}{2} - \nabla_{ii} \phi\right) \le 0$$
(3.4)

and

$$\sum_{i,k,l} \left(\delta_{kl} - \frac{\nabla_k u \nabla_l u}{2w} \right) \nabla_{ik} u \nabla_{il} u + \nabla_k u \Delta(\nabla_k u) - \frac{w}{2} |\nabla \phi|^2 + w \Delta \phi \le 0.$$
(3.5)

Note that the first term in (3.4) and (3.5) is nonnegative. Multiply $\gamma \sum F^{ii}$ to (3.5) and add what we got to (3.4). Thus, by (2.9) we obtain

$$F^{ii}\nabla_{k}u(\nabla_{kii}u + \gamma\nabla_{k}\Delta u) - \frac{w}{2}F^{ii}(|\nabla_{i}\phi|^{2} + \gamma|\nabla\phi|^{2}) + wF^{ii}(\nabla_{ii}\phi + \gamma\Delta\phi) \le C|\nabla u|^{2}\sum F^{ii}.$$
(3.6)

Now we compute the first term in (3.6). Firstly, we have

$$abla_i \phi = \phi' \nabla_i u, \qquad \nabla_{ii} \phi = \phi' \nabla_{ii} u + \phi'' (\nabla_i u)^2.$$

Using (3.2), we easily get that

$$F^{ii}\nabla_{k}u(\nabla_{kii}u + \gamma\nabla_{k}\Delta u)$$

$$= F^{ii}\nabla_{k}u\nabla_{k}\left(T_{ii} - s|\nabla_{i}u|^{2} + \frac{t}{2}|\nabla u|^{2} - \chi_{ii}\right)$$

$$= \nabla_{k}u\nabla_{k}(\psi + \beta_{\varepsilon}) + w\phi'F^{ii}(2s|\nabla_{i}u|^{2} - t|\nabla u|^{2}) - F^{ii}\nabla_{k}u\nabla_{k}\chi_{ii}.$$
(3.7)

By the homogeneity of *F*, we also get

$$F^{ii}(\nabla_{ii}\phi + \gamma \Delta \phi) = \phi'' F^{ii}(|\nabla_{i}u|^{2} + \gamma |\nabla u|^{2}) + \phi' F^{ii}\left(T_{ii} - s|\nabla_{i}u|^{2} + \frac{t}{2}|\nabla u|^{2} - \chi_{ii}\right) = \phi'' F^{ii}(|\nabla_{i}u|^{2} + \gamma |\nabla u|^{2}) + \phi'\left(F - sF^{ii}|\nabla_{i}u|^{2} + \frac{t}{2}F^{ii}|\nabla u|^{2} - F^{ii}\chi_{ii}\right).$$
(3.8)

According to (3.7) and (3.8), it follows from (3.6)

$$\begin{split} \gamma |\nabla u|^{2} \left(\phi'' - \frac{1}{2} (\phi')^{2} - \frac{t}{2\gamma} \phi' \right) \sum F^{ii} + \left(\phi'' - \frac{1}{2} (\phi')^{2} + s\phi' \right) F^{ii} (\nabla_{i} u)^{2} \\ \leq -\phi' (\psi + \beta_{\varepsilon} - F^{ii} \chi_{ii}) + C \sum F^{ii} - \frac{\nabla_{k} u \nabla_{k} (\psi + \beta_{\varepsilon})}{w} \\ \leq - \left(\phi' \beta_{\varepsilon} + \frac{\nabla_{k} u \nabla_{k} (u - h) \beta_{\varepsilon}'}{w} \right) + C \sum F^{ii} + C. \end{split}$$
(3.9)

Let

$$\phi(u) = v^{-a}, \qquad v = 1 - u + \sup_{M} u.$$

We have

$$\phi'(u) = av^{-a-1}, \qquad \phi''(u) = \frac{(a+1)\phi'}{v},$$

and

$$\phi'' - \frac{1}{2} (\phi')^2 = \phi' \left(\frac{a+1}{\nu} - \frac{a\nu^{-a}}{2\nu} \right) \ge \frac{\phi'a}{2\nu} > 0$$

since $\nu^{-a} \leq 1$. When $|\nabla u(x_0)|$ is sufficiently large, we see $\nabla_k u \nabla_k (u-h) > 0$. Hence we have that the first term on the right-hand side of (3.9) is negative as β_{ε} , $\beta'_{\varepsilon} > 0$. From (3.9) and (1.9) when *a* is sufficiently large, we then obtain that

$$\frac{\phi' a\gamma |\nabla u|^2}{4\nu} \le C,\tag{3.10}$$

from which we conclude that (3.1) holds.

In order to prove (1.19), it remains to bound $\sup_M |u| + \sup_{\partial M} |\nabla u|$. We quote two lemmas in [8], the ingredients of whose proofs are the maximum principle.

Lemma 3.2 If either (1.10) or (1.11) holds, then any admissible solution u of (1.16) admits the a priori bound

$$\sup_{M} u \le c_0. \tag{3.11}$$

Lemma 3.3 If u is admissible such that tr $T[u] \ge 0$ and $|u|_{C^0(M)} \le \mu$, then

$$\sup_{\partial M} \nabla_{\nu} u \le c_1(\mu), \tag{3.12}$$

where v is the interior unit normal to ∂M .

Now with the above two lemmas and the fact $\nabla_{\nu} u \ge \nabla_{\nu} \underline{u}$ on ∂M when $u \in \mathcal{U}$, we then have the following.

Theorem 3.4 *Suppose that* (1.5)–(1.8), *and either* (1.10) *or* (1.11) *hold. Then, for* $u \in U$, (1.19) *holds.*

Therefore, the uniform estimates (1.19) ensure that there exist a subsequence $\{u_{\varepsilon_k}\}$ of $\{u_{\varepsilon}\}$ and a function $u \in C^{1,1}(\overline{M})$ such that $u_{\varepsilon_k} \to u$ in M as $\varepsilon_k \to 0$. It is easy to verify that u satisfies (1.3) and (1.4) and $u \in C^{3,\alpha}(E)$ for any $\alpha \in (0, 1)$. Consequently, Theorem 1.1 is established.

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Competing interests

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Authors' contributions

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