

RESEARCH

Open Access



# Nonlinear problem with subcritical exponent in Sobolev space

Iqbal H Jebriil\*

\*Correspondence:  
iqbal501@hotmail.com  
Department of Mathematics, Taibah  
University, 344 Almadinah  
Almunawwarah, Saudi Arabia

## Abstract

Using Brouwer's fixed point theorem, we prove the existence of solutions for some nonlinear problem with subcritical Sobolev exponent in  $S_+^4$ .

**MSC:** Primary 46E35; 47H10; secondary 35J60

**Keywords:** Sobolev spaces; subcritical exponent; nonlinear problem

## 1 Introduction and the main result

The exponent Lebesgue space  $L^p(\Omega)$  is defined by

$$L^p(\Omega) = \left\{ u \in L_{\text{loc}}^1(\Omega) : \int_{\Omega} |u(x)|^p dx < \infty \right\}.$$

This space is endowed with the norm

$$\|u\|_{L^p(\Omega)} = \inf \left\{ \lambda > 0 : \int_{\Omega} \left| \frac{u(x)}{\lambda} \right|^p dx \leq 1 \right\}.$$

The Sobolev space  $W^{1,p}(\Omega)$  is defined by

$$W^{1,p}(\Omega) = \left\{ u \in W_{\text{loc}}^{1,1}(\Omega) : u \in L^p(\Omega) \text{ and } |\nabla u| \in L^p(\Omega) \right\}.$$

The corresponding norm for this space is

$$\|u\|_{W^{1,p}(\Omega)} = \|u\|_{L^p(\Omega)} + \|\nabla u\|_{L^p(\Omega)}.$$

Define  $W_0^1(\Omega) = H_0^1(\Omega)$  as the closure of  $C_c^\infty(\Omega)$  with respect to the  $W^{1,p}(\Omega)$  norm which is a Hilbert space [1].

We consider the problem of the scalar curvature on the standard four dimensional half sphere under minimal boundary conditions (S):

$$(S) \quad \begin{cases} L_g u := -\Delta_g u + 2u = Ku^3, & u > 0 \text{ in } S_+^4, \\ \frac{\partial u}{\partial \nu} = 0 & \text{on } \partial S_+^4, \end{cases}$$

where  $S_+^4 = \{x \in \mathbb{R}^5 / |x| = 1, x_5 > 0\}$ ,  $g$  is the standard metric, and  $K$  is a  $C^3$  positive Morse function on  $\overline{S_+^4}$ .

The scalar curvature problem on  $S^n$  and also on  $S_+^n$  was the subject of several works in recent years, we can cite for example [2–12].

Recall that the embedding of  $H^1(S_+^4)$  into  $L^4(S_+^4)$  is noncompact. For this reason, we have focused our study on the family of subcritical problems  $(S_\varepsilon)$

$$(S_\varepsilon) \quad \begin{cases} -\Delta_g u + 2u = Ku^{3-\varepsilon}, & u > 0 \quad \text{in } S_+^4, \\ \frac{\partial u}{\partial \nu} = 0 & \text{on } \partial S_+^4, \end{cases}$$

where  $\varepsilon$  is a small positive parameter.

Note that the solutions of problem  $(S)$  can be the limit as  $\varepsilon \rightarrow 0$  of some solutions  $(u_\varepsilon)$  for  $(S_\varepsilon)$ .

Djadli *et al.* [13] studied this problem in the case of the three dimensional half sphere. Assuming that the critical points of  $K_1$  verify  $(\partial K / \partial \nu)(a_i) > 0$  they demonstrated that there exist solutions  $(u_\varepsilon)$  concentrated at the points  $(a_1, \dots, a_p)$ . Moreover, in [14], we established the existence of another type of solutions  $(u_\varepsilon)$  of  $(S_\varepsilon)$  such that is concentrated at two points  $a_1 \in \partial S_+^4$  and  $a_2 \in S_+^4$ .

In this work, we aim to construct some positive solutions of  $(S_\varepsilon)$  which are concentrated at two different points of the boundary. To state our result, we will give the following notations. For  $a \in \overline{S_+^4}$  and  $\lambda > 0$ , let

$$\delta_{(a,\lambda)}(x) = c_0 \frac{\lambda}{(\lambda^2 + 1 + (1 - \lambda^2) \cos d(a, x))}, \tag{1}$$

where  $d$  is the geodesic distance on  $(\overline{S_+^4}, g)$  and  $c_0$  is chosen so that  $\delta_{(a,\lambda)}$  is the family of solutions of the following problem:

$$-\Delta u + 2u = u^3, \quad u > 0, \quad \text{in } S^4.$$

The space  $H^1(S_+^4)$  is equipped with the norm  $\| \cdot \|$  and its corresponding inner product  $\langle \cdot, \cdot \rangle$ :

$$\|f\|^2 = \int_{S_+^4} |\nabla f|^2 + 2 \int_{S_+^4} f^2, \quad \text{and} \quad \langle f, g \rangle = \int_{S_+^4} \nabla f \nabla g + 2 \int_{S_+^4} fg, \quad f, g \in H^1(S_+^4).$$

**Theorem 1** *Let  $z_1$  and  $z_2$  be a nondegenerate critical points of  $K_1 = K|_{\partial S_+^4}$  with  $(\partial K / \partial \nu)(z_i) > 0$ ,  $i = 1, 2$ . Then there exists  $\varepsilon_0 > 0$  such that, for each  $\varepsilon \in (0, \varepsilon_0)$ , problem  $(S_\varepsilon)$  has a solution  $(u_\varepsilon)$  of the form*

$$u_\varepsilon = \alpha_1 \delta_{(x_1, \lambda_1)} + \alpha_2 \delta_{(x_2, \lambda_2)} + v,$$

where, as  $\varepsilon \rightarrow 0$ ,  $\alpha_i \rightarrow K(z_i)^{-1/2}$ ;  $\|v\| \rightarrow 0$ ;  $x_i \rightarrow z_i$ ;  $x_i \in \partial S_+^4$ ;  $\lambda_i \rightarrow +\infty$ ;  $\lambda_1 = c\lambda_2(1 + o(1))$ .

The rest of this work is summarized as follows. In Section 2, we present a classical preliminaries and we perform a useful estimations of functional  $(I_\varepsilon)$  associated to the problem  $(S_\varepsilon)$  for  $(\varepsilon > 0)$  and its gradient. Section 3 is devoted to the construction of solutions and the proof of our result.

### 2 Useful estimations

We introduce the structure variational associated to the problem  $(S_\varepsilon)$  for  $\varepsilon > 0$

$$I_\varepsilon(u) = \frac{1}{2} \int_{S_+^4} |\nabla u|^2 + \int_{S_+^4} u^2 - \frac{1}{4-\varepsilon} \int_{S_+^4} K|u|^{4-\varepsilon}, \quad u \in H^1(S_+^4). \tag{2}$$

It is well known that there is an equivalence between the existence of solutions for  $(S_\varepsilon)$  and the positive critical point of  $I_\varepsilon$ . Moreover, in order to reduce our problem to  $\mathbb{R}_+^4$  we will perform some stereographic projection. We denote  $D^{1,2}(\mathbb{R}_+^4)$  for the completion of  $C_c^\infty(\mathbb{R}_+^4)$  with respect to the Dirichlet norm. Recall that an isometry  $\iota : H^1(S_+^4) \rightarrow D^{1,2}(\mathbb{R}_+^4)$  is induced by the stereographic projection  $\pi_a$  about a point  $a \in \partial S_+^4$  following the formula

$$(\iota\phi)(y) = \left( \frac{2}{1+|x|^2} \right) \phi(\pi_a^{-1}(y)), \quad \phi \in H^1(S_+^4), y \in \mathbb{R}_+^4. \tag{3}$$

For every  $\phi \in H^1(S_+^4)$ , one can check that the following holds true:

$$\int_{S_+^4} (|\nabla\phi|^2 + 2\phi^2) = \int_{\mathbb{R}_+^4} |\nabla(\iota\phi)|^2 \quad \text{and} \quad \int_{S_+^4} |\phi|^4 = \int_{\mathbb{R}_+^4} |\iota\phi|^4.$$

Furthermore, using (3) with  $\pi_{-a}$ , it is easy to see that  $\iota\delta_{(a,\lambda)}$  is given by

$$\iota\delta_{(a,\lambda)} = \frac{c_0\lambda}{1 + \lambda^2|x-a|^2}.$$

$\delta_{(a,\lambda)}$  will be written instead of  $\iota\delta_{(a,\lambda)}$  in the sequel.

Let

$$M_\varepsilon = \left\{ m = (\alpha, \lambda, x, \nu) \in \mathbb{R}^2 \times (\mathbb{R}_+^*)^2 \times (\partial S_+^4)^2 \times H^1(S_+^4) : \nu \in E_{(x,\lambda)}, \|\nu\| < \nu_0; \right. \\ \left. \left| \frac{\alpha_i^2 K(x_i)}{\alpha_j^2 K(x_j)} - 1 \right| < \nu_0, \lambda_i > \frac{1}{\nu_0}, \varepsilon \log \lambda_i < \nu_0, \forall i; c_0 < \frac{\lambda_1}{\lambda_2} < c_0^{-1}; |x_1 - x_2| > d_0; \right. \\ \left. \left| -2c_3 \frac{\partial K}{\partial \nu}(x_i) \frac{1}{\lambda_i} + \frac{\varepsilon K(x_i) S_4}{8} \right| < \varepsilon^{1+\frac{\sigma}{2}} \right\},$$

where  $\nu_0$  is a small positive constant,  $\sigma, c_0, d_0$  are some suitable positive constants, and

$$E_{(x,\lambda)} = \left\{ w \in H^1(S_+^4) / \langle w, \varphi \rangle = 0 \quad \forall \varphi \in \text{Span} \left\{ \delta_i, \frac{\partial \delta_i}{\partial \lambda_i}, \frac{\partial \delta_i}{\partial x_i^j}, i = 1, 2; j \leq 4 \right\} \right\}.$$

Here,  $x_i^j$  denotes the  $j$ th component of  $x_i$ . Also

$$\Psi_\varepsilon : M_\varepsilon \rightarrow \mathbb{R}; \quad m = (\alpha, \lambda, x, \nu) \mapsto I_\varepsilon(\alpha_1 \delta_{(x_1, \lambda_1)} + \alpha_2 \delta_{(x_2, \lambda_2)} + \nu). \tag{4}$$

In the sequel, we will write  $\delta_i$  instead of  $\delta_{(x_i, \lambda_i)}$  and  $u = \alpha_1 \delta_1 + \alpha_2 \delta_2 + \nu$  for the sake of simplicity.

In the remainder of this section, we will give expansions of the gradient of the functional  $I_\varepsilon$  associated to  $(S_\varepsilon)$  for  $\varepsilon > 0$ . Thus estimations are needed in Section 3. We need to recall

that [15] proved the following remark when  $n = 3$ , but the same argument is available for the dimension 4.

**Remark 2** For  $\varepsilon > 0$  and  $\delta_{(a,\lambda)}$  defined in (1), we have

$$\delta_{(a,\lambda)}^{-\varepsilon}(x) = 1 - \varepsilon \log \delta_{(a,\lambda)} + O(\varepsilon^2 \log^2 \lambda) \quad \text{in } S_+^4.$$

Now, explicit computations, using Remark 2, yield the following propositions.

**Proposition 3** Let  $(\alpha, \lambda, x, \nu) \in M_\varepsilon$ . Then, for  $u = \alpha_1 \delta_{(x_1, \lambda_1)} + \alpha_2 \delta_{(x_2, \lambda_2)} + \nu$ , we have the following expansion:

$$\langle \nabla I_\varepsilon(u), \delta_i \rangle = \frac{\alpha_i S_4}{2} (1 - \alpha_i^{2-\varepsilon} K(x_i)) + O\left(\varepsilon \log \lambda_i + \frac{1}{\lambda_i} + \varepsilon_{12} + \|\nu\|^2\right),$$

where

$$\varepsilon_{ij} = \frac{1}{\frac{\lambda_i}{\lambda_j} + \frac{\lambda_j}{\lambda_i} + \lambda_i \lambda_j |a_i - a_j|^2},$$

$$S_4 = 64 \int_{\mathbb{R}^4} \frac{dx}{(1 + |x|^2)^4}.$$

*Proof* We have

$$\langle \nabla I_\varepsilon(u), h \rangle = \int_{S_+^4} \nabla u \nabla h + 2 \int_{S_+^4} u h - \int_{S_+^4} K u^{3-\varepsilon} h. \tag{5}$$

A computation similar to the one performed in [16] shows that, for  $i = 1, 2$ ,

$$\|\delta_i\|^2 = \int_{\mathbb{R}^4} |\nabla \delta_i|^2 = \frac{S_4}{2} \tag{6}$$

and

$$\int_{S_+^4} \nabla \delta_i \nabla \delta_j + 2 \int_{S_+^4} \delta_i \delta_j = \int_{\mathbb{R}^4} \nabla \delta_i \nabla \delta_j = \int_{\mathbb{R}^4} \delta_i^3 \delta_j = O(\varepsilon_{12}). \tag{7}$$

For the other integral, we write

$$\int_{S_+^4} K u^{3-\varepsilon} \delta_i = \int_{S_+^4} K (\alpha_1 \delta_1 + \alpha_2 \delta_2)^{3-\varepsilon} \delta_i + O(\varepsilon_{12}^2 \log \varepsilon_{12}^{-1} + |\nu|^2). \tag{8}$$

We also write

$$\begin{aligned} \int_{S_+^4} K (\alpha_1 \delta_1 + \alpha_2 \delta_2)^{3-\varepsilon} \delta_i &= \alpha_i^{3-\varepsilon} \int_{S_+^4} K \delta_i^{4-\varepsilon} + \alpha_j^{3-\varepsilon} \int_{S_+^4} K \delta_j^{3-\varepsilon} \delta_i \\ &\quad + (3 - \varepsilon) \alpha_i^{2-\varepsilon} \alpha_j \int_{S_+^4} K \delta_i^{3-\varepsilon} \delta_j + O(\varepsilon_{12}^2 \log \varepsilon_{12}^{-1}). \end{aligned} \tag{9}$$

Expansions of  $K$  around  $x_i$  and  $x_j$  give

$$\int_{S_+^4} K \delta_i^{4-\varepsilon} = \int_{\mathbb{R}_+^4} K \delta_i^{4-\varepsilon} = K(x_i) \frac{S_4}{2} + O\left(\varepsilon \log \lambda_i + \frac{1}{\lambda_i}\right), \tag{10}$$

$$\int_{S_+^4} K \delta_j^{3-\varepsilon} \delta_i = \int_{\mathbb{R}_+^4} K \delta_j^{3-\varepsilon} \delta_i = O(\varepsilon \log \lambda_i + \varepsilon_{12}), \tag{11}$$

$$\int_{S_+^4} K \delta_i^{3-\varepsilon} \delta_j = \int_{\mathbb{R}_+^4} K \delta_i^{3-\varepsilon} \delta_j = O(\varepsilon \log \lambda_i + \varepsilon_{12}). \tag{12}$$

Combining (5)-(12), we derive our proposition. □

**Proposition 4** *Let  $(\alpha, \lambda, x, v) \in M_\varepsilon$ . Then, for  $u = \alpha_1 \delta_{(x_1, \lambda_1)} + \alpha_2 \delta_{(x_2, \lambda_2)} + v$ , we have*

$$\begin{aligned} \left\langle \nabla I_\varepsilon(u), \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} \right\rangle &= \alpha_j (1 - \alpha_j^{2-\varepsilon} K(x_j) - \alpha_i^{2-\varepsilon} K(x_i)) c_2 \lambda_i \frac{\partial \varepsilon_{12}}{\partial \lambda_i} + \alpha_i^{3-\varepsilon} \frac{\varepsilon S_4 K(x_i)}{8} \\ &\quad + \alpha_i^{3-\varepsilon} \frac{2c_3}{\lambda_i} \frac{\partial K}{\partial v}(x_i) + O\left(\|v\|^2 + \frac{1}{\lambda_i^2} + \varepsilon^2 \log \lambda_i + \frac{\varepsilon \log \lambda_i}{\lambda_i}\right) \\ &\quad + O\left(\varepsilon \varepsilon_{12} (\log \varepsilon_{12}^{-1})^{1/2} + \varepsilon_{12}^2 \log \varepsilon_{12}^{-1} + \frac{\varepsilon_{12}}{\lambda_j} (\log \varepsilon_{12}^{-1})^{1/2}\right), \end{aligned}$$

where

$$S_4 = 64 \int_{\mathbb{R}^4} \frac{dx}{(1 + |x|^2)^4}, \quad c_2 = 64 \int_{\mathbb{R}^4} \frac{dx}{(1 + |x|^2)^3}, \quad c_3 = 64 \int_{\mathbb{R}_+^4} \frac{x_4(|x|^2 - 1)}{(1 + |x|^2)^5} dx.$$

*Proof* Observe that (see [16])

$$\int_{\mathbb{R}_+^4} \nabla \delta_i \nabla \left( \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} \right) = \int_{\mathbb{R}_+^4} \delta_i^3 \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} = 0, \tag{13}$$

$$\int_{\mathbb{R}_+^4} \nabla \delta_j \nabla \left( \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} \right) = \int_{\mathbb{R}_+^4} \delta_j^3 \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} = \frac{1}{2} c_2 \lambda_i \frac{\partial \varepsilon_{12}}{\partial \lambda_i} + O(\varepsilon_{12}^2 \log(\varepsilon_{12}^{-1})). \tag{14}$$

For the other part, we have the expansions of  $K$  around  $x_i$  and using Remark 2,

$$\int_{\mathbb{R}_+^4} K \delta_i^{3-\varepsilon} \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} = -\frac{\varepsilon S_4 K(x_i)}{8} - \frac{2c_3}{\lambda_i} \nabla K(x_i) e_4 + O\left(\varepsilon^2 \log \lambda_i + \frac{1}{\lambda_i^2} + \frac{\varepsilon}{\lambda_i}\right), \tag{15}$$

$$\begin{aligned} \int_{\mathbb{R}_+^4} K P \delta_j^{3-\varepsilon} \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} &= K(x_j) \frac{1}{2} c_2 \lambda_i \frac{\partial \varepsilon_{12}}{\partial \lambda_i} + O\left(\varepsilon \varepsilon_{12} (\log(\varepsilon_{12}^{-1}))^{\frac{1}{2}} + \frac{1}{\lambda_j^2}\right) \\ &\quad + O(\varepsilon_{12}^2 \log(\varepsilon_{12}^{-1})), \end{aligned} \tag{16}$$

$$\begin{aligned} (3 - \varepsilon) \int_{\mathbb{R}_+^4} K \delta_i^{2-\varepsilon} \delta_j \lambda_i \frac{\partial \delta_i}{\partial \lambda_i} &= K(x_i) \frac{1}{2} c_2 \lambda_i \frac{\partial \varepsilon_{12}}{\partial \lambda_i} + O(\varepsilon \varepsilon_{12} (\log(\varepsilon_{12}^{-1}))^{\frac{1}{2}}) \\ &\quad + O\left(\varepsilon_{12}^2 \log(\varepsilon_{12}^{-1}) + \frac{\varepsilon_{12}}{\lambda_j} (\log(\varepsilon_{12}^{-1}))^{\frac{1}{2}}\right). \end{aligned} \tag{17}$$

Combining (5), (13), (14), (15), (16), and (17), the proof follows. □

**Proposition 5** *Let  $(\alpha, \lambda, x, v) \in M_\varepsilon$ . Then, for  $u = \alpha_1 \delta_{(x_1, \lambda_1)} + \alpha_2 \delta_{(x_2, \lambda_2)} + v$ , we have the following expansion:*

$$\begin{aligned} \left\langle \nabla I_\varepsilon(u), \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} \right\rangle &= \left( \alpha_i c_4 (1 - \alpha_i^{2-\varepsilon} K(x_i)) + \alpha_i^{3-\varepsilon} K(x_i) \varepsilon (c_4 \log \lambda_i + c_7) \right. \\ &\quad \left. + 2 \alpha_i^{3-\varepsilon} \frac{c_5}{\lambda_i} \frac{\partial K}{\partial v}(x_i) \right) e_4 + \alpha_j \left( 1 - \sum \alpha_i^{2-\varepsilon} K(x_i) \right) \frac{c_2}{\lambda_i} \frac{\partial \varepsilon_{12}}{\partial x_i} \\ &\quad - 2 \alpha_i^{3-\varepsilon} c_5 \frac{\nabla_T K(x_i)}{\lambda_i} + O \left( \|v\|^2 + \lambda_j |x_1 - x_2| \varepsilon_{12}^{\frac{5}{2}} + \frac{\varepsilon \log \lambda_i}{\lambda_i} |\nabla_T K(x_i)| \right) \\ &\quad + O \left( \varepsilon \varepsilon_{12} (\log \varepsilon_{12}^{-1})^{\frac{1}{2}} + \varepsilon_{12}^2 \log \varepsilon_{12}^{-1} + \frac{\varepsilon_{12}}{\lambda_j} (\log \varepsilon_{12}^{-1})^{\frac{1}{2}} + \frac{1}{\lambda_i^2} + \varepsilon^2 \log^2 \lambda_i \right), \end{aligned}$$

where

$$c_4 = 132 \int_{\mathbb{R}_+^4} \frac{x_4}{(1 + |x|^2)^5} dx, \quad c_5 = 16 \int_{\mathbb{R}^4} \frac{x_4^2}{(1 + |x|^2)^5} dx.$$

*Proof* We have

$$\int_{\mathbb{R}_+^4} \nabla \delta_i \nabla \left( \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} \right) = \int_{\mathbb{R}_+^4} \delta_i^3 \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} = c_4 e_4, \tag{18}$$

$$\int_{\mathbb{R}_+^4} \nabla \delta_j \nabla \left( \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} \right) = \int_{\mathbb{R}_+^4} \delta_j^3 \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} = \frac{1}{2} \frac{c_2}{\lambda_i} \frac{\partial \varepsilon_{12}}{\partial x_i} + O \left( \varepsilon_{12}^2 \log(\varepsilon_{12}^{-1}) + \varepsilon_{12}^{\frac{5}{2}} \lambda_j |x_1 - x_2| \right). \tag{19}$$

For the other part

$$\begin{aligned} \int_{\mathbb{R}_+^4} K \delta_i^{3-\varepsilon} \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} &= K(x_i) c_4 e_4 + 2 \frac{c_5}{\lambda_i} \nabla K(x_i) - \varepsilon \log \lambda_i K(x_i) c_4 e_4 \\ &\quad - \varepsilon K(x_i) c_7 e_4 + O \left( \frac{1}{\lambda_i^2} + \varepsilon^2 \log^2 \lambda_i \right), \end{aligned} \tag{20}$$

$$\begin{aligned} \int_{\mathbb{R}_+^4} K \delta_j^{3-\varepsilon} \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} &= K(x_j) \frac{1}{2} c_2 \frac{1}{\lambda_i} \frac{\partial \varepsilon_{12}}{\partial x_i} + O \left( \varepsilon_{12}^{\frac{5}{2}} \lambda_j |x_1 - x_2| \right) \\ &\quad + O \left( \varepsilon_{12}^2 \log(\varepsilon_{12}^{-1}) + \frac{1}{\lambda_j} \varepsilon_{12} (\log(\varepsilon_{12}^{-1}))^{\frac{1}{2}} \right), \end{aligned} \tag{21}$$

$$\begin{aligned} (3 - \varepsilon) \int_{\mathbb{R}_+^4} K \delta_i^{2-\varepsilon} \delta_j \frac{1}{\lambda_i} \frac{\partial \delta_i}{\partial x_i} &= K(x_i) \frac{1}{2} c_2 \frac{1}{\lambda_i} \frac{\partial \varepsilon_{12}}{\partial x_i} + O \left( \varepsilon_{12}^{\frac{5}{2}} \lambda_j |x_1 - x_2| \right) \\ &\quad + O \left( \varepsilon_{12}^2 \log(\varepsilon_{12}^{-1}) + \frac{1}{\lambda_i} \varepsilon_{12} (\log(\varepsilon_{12}^{-1}))^{\frac{1}{2}} \right). \end{aligned} \tag{22}$$

Using (5), (18)-(22), our proposition follows. □

### 3 Construction of the solution

The method of this type of theorem was followed first by Bahri, Li and Rey [17] when they studied an approximation problem of the Yamabe-type problem on domains. Many authors used this idea to construct some solutions to other problems. The method becomes standard. Here we will follow the idea of [17] and take account of the new estimates since

we have an equation different from the one studied in [17]. From the idea of [17], using the coefficients of Euler-Lagrange, we obtain

**Proposition 6** *Let A point  $m = (\alpha, \lambda, x, v) \in M_\varepsilon$  is a critical point of the function  $\Psi_\varepsilon$  if and only if  $u = \alpha_1\delta_1 + \alpha_2\delta_2 + v$  is a critical point of functional  $I_\varepsilon$ , which means the existence of some  $(A, B, C) \in \mathbb{R}^2 \times \mathbb{R}^2 \times (\mathbb{R}^4)^2$  with the following:*

$$(E_{\alpha_i}) \frac{\partial \Psi_\varepsilon}{\partial \alpha_i} = 0, \quad \forall i = 1, 2, \tag{23}$$

$$(E_{\lambda_i}) \frac{\partial \Psi_\varepsilon}{\partial \lambda_i} = B_i \left\langle \frac{\partial^2 \delta_i}{\partial \lambda_i^2}, v \right\rangle + \sum_{j=1}^4 C_{ij} \left\langle \frac{\partial^2 \delta_i}{\partial x_i^j \partial \lambda_i}, v \right\rangle, \quad \forall i = 1, 2, \tag{24}$$

$$(E_{x_i}) \frac{\partial \Psi_\varepsilon}{\partial x_i} = B_i \left\langle \frac{\partial^2 \delta_i}{\partial \lambda_i \partial x_i}, v \right\rangle + \sum_{j=1}^4 C_{ij} \left\langle \frac{\partial^2 \delta_i}{\partial x_i^j \partial x_i}, v \right\rangle, \quad \forall i = 1, 2, \tag{25}$$

$$(E_v) \frac{\partial \Psi_\varepsilon}{\partial v} = \sum_{i=1,2} \left( A_i \delta_i + B_i \frac{\partial \delta_i}{\partial \lambda_i} + \sum_{j=1}^4 C_{ij} \frac{\partial \delta_i}{\partial x_i^j} \right). \tag{26}$$

Now, by a careful study of equation  $(E_v)$ , we get the following.

**Proposition 7** [12] *For any  $(\varepsilon, \alpha, \lambda, x)$  with  $(\alpha, \lambda, x, 0) \in M_\varepsilon$ , there exists a smooth map which associates  $\bar{v} \in E_{(x,\lambda)}$  with  $\|\bar{v}\| < v_0$  and equation (26) in the previous proposition is verified for some  $(A, B, C) \in \mathbb{R}^2 \times \mathbb{R}^2 \times (\mathbb{R}^4)^2$ . Such a  $\bar{v}$  is unique, minimizes  $\Psi_\varepsilon(\alpha, \lambda, x, v)$  with respect to  $v$  in  $\{v \in E_{(x,\lambda)} / \|v\| < v_0\}$ , and*

$$\|\bar{v}\| = O\left(\varepsilon + \frac{1}{\lambda_1} + \frac{1}{\lambda_2} + \varepsilon_{12}(\log \varepsilon_{12}^{-1})^{1/2}\right). \tag{27}$$

*Proof of Theorem 1* Once  $\bar{v}$  is defined by Proposition 7, we estimate the corresponding numbers  $A, B, C$  by taking the scalar product in  $H^1(S_+^4)$  of  $(E_v)$  with  $\delta_i, \partial \delta_i / \partial \lambda_i, \partial \delta_i / \partial x_i$  for  $i = 1, 2$ , respectively. So we get the following coefficients of a quasi-diagonal system:

$$\begin{aligned} \int_{\mathbb{R}_+^4} |\nabla \delta_i|^2 &= \frac{S_4}{2}; & \int_{\mathbb{R}_+^4} \nabla \delta_1 \nabla \delta_2 &= O\left(\frac{1}{\lambda_2 \lambda_1}\right); & \int_{\mathbb{R}_+^4} \nabla \delta_i \nabla \frac{\partial \delta_i}{\partial \lambda_i} &= 0; \\ \int_{\mathbb{R}_+^4} \nabla \delta_1 \nabla \frac{\partial \delta_2}{\partial \lambda_2} &= O\left(\frac{1}{\lambda_1 \lambda_2^2}\right), & \int_{\mathbb{R}_+^4} \nabla \delta_2 \nabla \frac{\partial \delta_1}{\partial \lambda_1} &= O\left(\frac{1}{\lambda_1^2 \lambda_2}\right); & \int_{\mathbb{R}_+^4} \left| \nabla \frac{\partial \delta_i}{\partial \lambda_i} \right|^2 &= \frac{\Gamma_1}{2\lambda_i^2}; \\ \int_{\mathbb{R}_+^4} \nabla \frac{\partial \delta_1}{\partial \lambda_1} \nabla \frac{\partial \delta_2}{\partial \lambda_2} &= O\left(\frac{1}{\lambda_1^2 \lambda_2^2}\right), & \int_{\mathbb{R}_+^4} \left| \nabla \frac{\partial \delta_i}{\partial x_i} \right|^2 &= \frac{\Gamma_2}{2} \lambda_i^2; & \int_{\mathbb{R}_+^4} \nabla \delta_i \nabla \frac{\partial \delta_i}{\partial x_i} &= O(\lambda_i); \\ \int_{\mathbb{R}_+^4} \nabla \delta_1 \nabla \frac{\partial \delta_2}{\partial x_2} &= O\left(\frac{1}{\lambda_1}\right), & \int_{\mathbb{R}_+^4} \nabla \delta_2 \nabla \frac{\partial \delta_1}{\partial x_1} &= O\left(\frac{1}{\lambda_2}\right); \\ \int_{\mathbb{R}_+^4} \nabla \frac{\partial \delta_1}{\partial x_1} \nabla \frac{\partial \delta_2}{\partial x_2} &= \frac{n+2}{n-2} \int_{\mathbb{R}_+^4} \delta_2^{\frac{4}{n-2}} \nabla \frac{\partial \delta_2}{\partial x_2} \frac{\partial \delta_1}{\partial x_1} &= O\left(\frac{1}{\lambda_1}\right), \end{aligned}$$

with  $|x_1 - x_2| \geq c > 0$  and  $\Gamma_1, \Gamma_2$  are positive constants.

We have also

$$\left\langle \frac{\partial \Psi_\varepsilon}{\partial v}, \delta_i \right\rangle = \frac{\partial \Psi_\varepsilon}{\partial \alpha_i}; \quad \left\langle \frac{\partial \Psi_\varepsilon}{\partial v}, \frac{\partial \delta_i}{\partial \lambda_i} \right\rangle = \frac{1}{\alpha_i} \frac{\partial \Psi_\varepsilon}{\partial \lambda_i}; \quad \left\langle \frac{\partial \Psi_\varepsilon}{\partial v}, \frac{\partial \delta_i}{\partial x_i} \right\rangle = \frac{1}{\alpha_i} \frac{\partial \Psi_\varepsilon}{\partial x_i}.$$

Using Propositions 3, some computations yield

$$\frac{\partial \Psi_\varepsilon}{\partial \alpha_i} = -S_4 \beta_i + V_{\alpha_i}(\varepsilon, \alpha, \lambda, x), \tag{28}$$

with  $\beta_i = \alpha_i - 1/K(z_i)^{\frac{1}{2}}$  and

$$V_{\alpha_i} = O\left(\beta_i^2 + \varepsilon \log \lambda_i + \frac{1}{\lambda_i} + |x_i - z_i|^2\right). \tag{29}$$

In the same way, using Propositions 4, we get

$$\frac{\partial \Psi_\varepsilon}{\partial \lambda_i} = \frac{1}{K(z_i)} \left( \frac{2c_3}{\lambda_i^2} \frac{\partial K}{\partial v}(x_i) + \frac{\varepsilon K(x_i) S_4}{8\lambda_i} \right) + V_{\lambda_i}(\varepsilon, \alpha, \lambda, x), \tag{30}$$

where  $c_2$  and  $c_3$  are defined in Proposition 4 and

$$V_{\lambda_i} = O\left[\frac{1}{\lambda_i} \left( \frac{1}{\lambda_i^2} + \varepsilon^2 \log \lambda_i + \frac{\varepsilon \log \lambda_i}{\lambda_i} \right) + (|\beta| + \varepsilon + |x_i - z_i|^2) \left( \frac{\varepsilon}{\lambda_i} + \frac{1}{\lambda_i^2} \right)\right]. \tag{31}$$

Lastly, using Propositions 5, we have

$$\frac{\partial \Psi_\varepsilon}{\partial x_i} = -2c_5 \nabla_T K(x_i) + V_{x_i}(\varepsilon, \alpha, \lambda, x), \tag{32}$$

where

$$V_{x_i} = O\left(\frac{1}{\lambda_i} + (|\beta| + \varepsilon \log \lambda_i + |x_i - z_i|^2) |x_i - z_i|\right). \tag{33}$$

From these estimates, we deduce

$$\begin{aligned} \frac{\partial \Psi_\varepsilon}{\partial \alpha_i} &= O\left(|\beta| + \varepsilon \log \lambda_i + \frac{1}{\lambda_i} + |x_i - z_i|^2\right), \\ \frac{\partial \Psi_\varepsilon}{\partial \lambda_i} &= O\left(\frac{\varepsilon^{1+\sigma/2}}{\lambda_i}\right); \quad \frac{\partial \Psi_\varepsilon}{\partial x_i} = O\left(|x_i - z_i| + \frac{1}{\lambda_i}\right). \end{aligned}$$

By solving the system in  $A$ ,  $B$ , and  $C$ , we find

$$\begin{cases} A_i = O(|\beta| + \varepsilon \log \lambda_i + \frac{1}{\lambda_i} + |x_i - z_i|^2), \\ B_i = O(\varepsilon^{1+\sigma/2} \lambda_i); \quad C_i = O\left(\frac{|x_i - z_i|}{\lambda_i^2} + \frac{1}{\lambda_i^3}\right). \end{cases} \tag{34}$$

Now, we can evaluate the right hand side in  $(E_{\lambda_i})$  and  $(E_{x_i})$ ,

$$B_i \left\langle \frac{\partial^2 \delta_i}{\partial \lambda_i^2}, \bar{v} \right\rangle + \sum_{j=1}^4 C_{ij} \left\langle \frac{\partial^2 \delta_i}{\partial x_i^j \partial \lambda_i}, \bar{v} \right\rangle = O\left(\left(\frac{\varepsilon^{1+\sigma/2}}{\lambda_i} + \frac{|x_i - z_i|}{\lambda_i^2} + \frac{1}{\lambda_i^3}\right) \|\bar{v}\|\right), \tag{35}$$

$$B_i \left\langle \frac{\partial^2 \delta_i}{\partial \lambda_i \partial x_i}, \bar{v} \right\rangle + \sum_{j=1}^4 C_{ij} \left\langle \frac{\partial^2 \delta_i}{\partial x_i^j \partial x_i}, \bar{v} \right\rangle = O\left(\left(\varepsilon^{1+\sigma/2} \lambda_i + |x_i - z_i| + \frac{1}{\lambda_i}\right) \|\bar{v}\|\right), \tag{36}$$

where

$$\left\| \frac{\partial^2 P\delta_i}{\partial \lambda_i^2} \right\| = O\left(\frac{1}{\lambda_i^2}\right); \quad \left\| \frac{\partial^2 P\delta_i}{\partial x_i \partial \lambda_i} \right\| = O(1); \quad \left\| \frac{\partial^2 P\delta_i}{\partial x_i^2} \right\| = O(\lambda_i^2).$$

Now, we consider a point  $(z_1, z_2) \in \partial S_+^4 \times \partial S_+^4$  such that  $z_1$  and  $z_2$  are nondegenerate critical points of  $K_1$ . We set

$$\frac{1}{\lambda_i} = \varepsilon \frac{S_4}{16c_3} K(z_i) \left( \frac{\partial K}{\partial v}(z_i) \right)^{-1} (1 + \zeta_i); \quad x_i = z_i + \xi_i,$$

where  $\zeta_i \in \mathbb{R}$  and  $(\xi_1, \xi_2) \in \mathbb{R}^3 \times \mathbb{R}^3$  are assumed to be small.

Using (28) and these changes of variables,  $(E_{\alpha_i})$  becomes

$$\beta_i = V_{\alpha_i}(\varepsilon, \beta, \zeta, \xi) = O(\beta^2 + \varepsilon |\log \varepsilon| + |\xi|^2). \tag{37}$$

Also, we use (30), we have

$$\begin{aligned} & \frac{2c_3}{\lambda_i^2} \frac{\partial K}{\partial v}(z_i + \xi_i) + \frac{\varepsilon K(z_i + \xi_i) S_4}{8\lambda_i} \\ &= \frac{\varepsilon^2 S_4^2 K(z_i)^2}{128c_3} \left( \frac{\partial K}{\partial v}(z_i) \right)^{-2} (1 + 2\zeta_i) \left( -\frac{\partial K}{\partial v}(z_i) + D^2 K(z_i)(e_4, \xi_i) \right) \\ & \quad + \frac{\varepsilon^2 S_4^2 K(z_i)^2}{128c_3} \left( \frac{\partial K}{\partial v}(z_i) \right)^{-1} (1 + \zeta_i) + O(\varepsilon^2(\zeta_i^2 + |\xi_i|^2)) \\ &= -\frac{\varepsilon^2 S_4^2 K(z_i)^2}{128c_3} \left( \frac{\partial K}{\partial v}(z_i) \right)^{-1} \zeta_i \\ & \quad + \frac{\varepsilon^2 S_4^2 K(z_i)^2}{128c_3} \left( \frac{\partial K}{\partial v}(z_i) \right)^{-2} D^2 K(z_i)(e_4, \xi_i) \\ & \quad + O(\varepsilon^2(\zeta_i^2 + |\xi_i|^2)). \end{aligned}$$

Combining this with (31), then  $(E_{\lambda_i})$  becomes

$$\begin{aligned} -\zeta_i + \left( \frac{\partial K}{\partial v}(z_i) \right)^{-1} D^2 K_1(z_i)(e_4, \xi_i) &= V_{\lambda_i}(\varepsilon, \beta, \zeta, \xi) \\ &= O(\varepsilon |\log \varepsilon| + |\beta|^2 + \zeta_i^2 + |\xi|^2). \end{aligned} \tag{38}$$

Using (32), (33), and (36),  $(E_{x_i})$  is equivalent to

$$D^2 K_1(z_i) \xi_i = V_{x_i}(\varepsilon, \beta, \zeta, \xi) = O(\varepsilon^{1/2} + |\beta|^2 + |\zeta|^2 + |\xi|^2). \tag{39}$$

Observe that the functions  $V_{\alpha_i}$ ,  $V_{\lambda_i}$ , and  $V_{x_i}$  are smooth.

We can also write the system as

$$\begin{cases} \beta = V(\varepsilon, \beta, \zeta, \xi), \\ L(\zeta, \xi) = W(\varepsilon, \beta, \zeta, \xi), \end{cases} \tag{40}$$

where  $L$  is a fixed linear operator on  $\mathbb{R}^8$  defined by

$$L(\zeta, \xi) = \left( -\zeta_1 + \left( \frac{\partial K}{\partial v}(z_1) \right)^{-1} D^2 K_1(z_1)(e_4, \xi_1); -\zeta_2 + \left( \frac{\partial K}{\partial v}(z_2) \right)^{-1} D^2 K_1(z_2)(e_4, \xi_2); \right. \\ \left. D^2 K_1(z_1)\xi_1; D^2 K_1(z_2)\xi_2 \right),$$

and  $V, W$  are smooth functions satisfying

$$\begin{cases} V(\varepsilon, \beta, \zeta, \xi) = O(\varepsilon^{1/2} + |\beta|^2 + |\xi|^2), \\ W(\varepsilon, \beta, \zeta, \xi) = O(\varepsilon^{\frac{1}{2}} + |\beta|^2 + |\zeta|^2 + |\xi|^2). \end{cases}$$

Now, by an easy computation, we see that the determinant of the linear operator  $L$  is not 0. Hence  $L$  is invertible, and according to Brouwer’s fixed point theorem, there exists a solution  $(\beta^\varepsilon, \zeta^\varepsilon, \xi^\varepsilon)$  of (40) for  $\varepsilon$  small enough, such that

$$|\beta^\varepsilon| = O(\varepsilon^{1/2}); \quad |\zeta^\varepsilon| = O(\varepsilon^{1/2}); \quad |\xi^\varepsilon| = O(\varepsilon^{1/2}).$$

Hence, we have constructed  $m^\varepsilon = (\alpha_1^\varepsilon, \alpha_2^\varepsilon, \lambda_1^\varepsilon, \lambda_2^\varepsilon, \chi_1^\varepsilon, \chi_2^\varepsilon)$  such that  $u_\varepsilon := \sum \alpha_i^\varepsilon \delta_{(\alpha_i^\varepsilon, \lambda_i^\varepsilon)} + \bar{v}_\varepsilon$ , verifies (23)-(27). From Proposition 6,  $u_\varepsilon$  is a critical point of  $I_\varepsilon$ , which implies that  $u_\varepsilon$  verify

$$-\Delta u_\varepsilon + 2u_\varepsilon = K|u_\varepsilon|^{2-\varepsilon} u_\varepsilon \quad \text{in } S_+^4, \quad \partial u_\varepsilon / \partial v = 0 \quad \text{on } \partial S_+^4. \tag{41}$$

We multiply equation (41) by  $u_\varepsilon^- = \max(0, -u_\varepsilon)$  and we integrate on  $S_+^4$ , we get

$$\int_{S_+^4} |\nabla u_\varepsilon^-|^2 + 2 \int_{S_+^4} (u_\varepsilon^-)^2 = \int_{S_+^4} K(u_\varepsilon^-)^{4-\varepsilon}. \tag{42}$$

We know also from the Sobolev embedding theorem that

$$|u_\varepsilon^-|_{4-\varepsilon}^2 := \left( \int_{S_+^4} K(u_\varepsilon^-)^{4-\varepsilon} \right)^{\frac{2}{4-\varepsilon}} \leq C \|u_\varepsilon^-\|^2. \tag{43}$$

Equations (42) and (43) imply that either  $u_\varepsilon^- \equiv 0$ , or  $|u_\varepsilon^-|_{4-\varepsilon}$  is far away from zero. Since  $m^\varepsilon \in M^\varepsilon$ , we have  $\|\bar{v}_\varepsilon\| < \nu_0$ , where  $\nu_0$  is a small positive constant (see the definition of  $M_\varepsilon$ ). This implies that  $|u_\varepsilon^-|_{4-\varepsilon}$  is very small. Thus,  $u_\varepsilon^- \equiv 0$  for  $\varepsilon$  small enough. Then  $u_\varepsilon$  is a non-negative function which satisfies (41). Finally, the maximum principle completes the proof of our theorem. □

#### 4 Conclusion

Thus it has been concluded that under some assumptions on the function  $K$ , there exist solutions of the nonlinear problem  $(S_\varepsilon)$  which are concentrated at two different points of the boundary.

#### Competing interests

The author declares to have no competing interests.

**Acknowledgements**

I would like to thank Deanship of Scientific Research at Taibah University for the financial support of this research project.

Received: 28 July 2016 Accepted: 14 November 2016 Published online: 25 November 2016

**References**

1. Diening, L, Harjulehto, P, Hasto, P, Ruzicka, M: Lebesgue and Sobolev Spaces with Variable Exponents. Lecture Notes in Mathematics, vol. 2011. Springer, Heidelberg (2011) MR2790542
2. Ambrosetti, A, Garcia Azorero, J, Peral, A: Perturbation of  $\Delta u + u^{\frac{n+2}{n-2}} = 0$ , the scalar curvature problem in  $\mathbb{R}^n$  and related topics. *J. Funct. Anal.* **165**, 117-149 (1999)
3. Bahri, A, Coron, JM: The scalar curvature problem on the standard three dimensional spheres. *J. Funct. Anal.* **95**, 106-172 (1991)
4. Bianchi, G, Pan, XB: Yamabe equations on half spheres. *Nonlinear Anal.* **37**, 161-186 (1999)
5. Chang, SA, Yang, P: A perturbation result in prescribing scalar curvature on  $S^n$ . *Duke Math. J.* **64**, 27-69 (1991)
6. Cherrier, P: Problèmes de Neumann non linéaires sur les variétés riemanniennes. *J. Funct. Anal.* **57**, 154-207 (1984)
7. Escobar, J: Conformal deformation of Riemannian metric to scalar flat metric with constant mean curvature on the boundary. *Ann. Math.* **136**, 1-50 (1992)
8. Escobar, J, Schoen, R: Conformal metrics with prescribed scalar curvature. *Invent. Math.* **86**, 243-254 (1986)
9. Han, ZC, Li, YY: The existence of conformal metrics with constant scalar curvature and constant boundary mean curvature. *Commun. Anal. Geom.* **8**, 809-869 (2000)
10. Hebey, E: The isometry concentration method in the case of a nonlinear problem with Sobolev critical exponent on compact manifolds with boundary. *Bull. Sci. Math.* **116**, 35-51 (1992)
11. Li, YY: Prescribing scalar curvature on  $S^n$  and related topics, Part I. *J. Differ. Equ.* **120**, 319-410 (1995); Part II. Existence and compactness. *Comm. Pure Appl. Math.* **49** 437-477 (1996).
12. Ould Bouh, K: Blowing up of sign-changing solutions to a subcritical problem. *Manuscr. Math.* **146**, 265-279 (2015)
13. Djadli, Z, Malchiodi, A, Ould Ahmedou, M: Prescribing the scalar and the boundary mean curvature on the three dimensional half sphere. *J. Geom. Anal.* **13**, 233-267 (2003)
14. Ben Ayed, M, Ghouli, R, Ould Bouh, K: Existence of conformal metrics with prescribed scalar curvature on the four dimensional half sphere. *Nonlinear Differ. Equ. Appl.* **19**, 629-662 (2012)
15. Rey, O: The topological impact of critical points at infinity in a variational problem with lack of compactness: the dimension 3. *Adv. Differ. Equ.* **4**, 581-616 (1999)
16. Bahri, A: An invariant for Yamabe-type flows with applications to scalar curvature problems in high dimension. A celebration of J. F. Nash jr. *Duke Math. J.* **81**, 323-466 (1996)
17. Bahri, A, Li, YY, Rey, O: On a variational problem with lack of compactness: The topological effect of the critical points at infinity. *Calc. Var. Partial Differ. Equ.* **3**, 67-94 (1995)

Submit your manuscript to a SpringerOpen® journal and benefit from:

- Convenient online submission
- Rigorous peer review
- Immediate publication on acceptance
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

---

Submit your next manuscript at ► [springeropen.com](http://springeropen.com)

---