

RESEARCH

Open Access

Oscillatory behaviour of a higher-order dynamic equation

Deniz Uçar^{1*} and Yaşar Bolat²

*Correspondence:

deniz.ucar@usak.edu.tr

¹ Department of Mathematics,
Faculty of Sciences and Arts, Usak
University, 1 Eylül Campus, Usak,
64200, Turkey

Full list of author information is
available at the end of the article

Abstract

In this paper we are concerned with the oscillation of solutions of a certain more general higher-order nonlinear neutral-type functional dynamic equation with oscillating coefficients. We obtain some sufficient criteria for oscillatory behaviour of its solutions.

MSC: 34N05

Keywords: time scale; higher-order nonlinear neutral dynamic equation; oscillating coefficient

1 Introduction

The calculus on time scales has been introduced in order to unify the theories of continuous and discrete processes and in order to extend those theories to a more general class of the so-called dynamic equations. In recent years there has been much research activity concerning the oscillation and non-oscillation of solutions of neutral dynamic equations on time scales.

In this paper we consider the higher-order nonlinear dynamic equation

$$\left[y(t) + P(t)y(\tau(t))\right]^{\Delta^n} + \sum_{i=1}^m Q_i(t)f_i(y(\phi_i(t))) = 0, \quad (1.1)$$

where $n \geq 2$, $P(t), Q_i(t) \in C_{rd} [t_0, \infty)_{\mathbb{T}}$ for $i = 1, 2, \dots, m$; $P(t)$ is an oscillating function ($P(t) : \mathbb{T} \rightarrow \mathbb{R}$), $Q_i(t)$ are positive real-valued functions for $i = 1, 2, \dots, m$; $\phi_i(t) \in C_{rd} [t_0, \infty)_{\mathbb{T}}$, $\phi_i^{\Delta}(t) > 0$, the variable delays $\tau, \phi_i : [t_0, \infty)_{\mathbb{T}} \rightarrow \mathbb{T}$ with $\tau(t), \phi_i(t) < t$ for all $t \in [t_0, \infty)_{\mathbb{T}}$, $\phi_i(t) \rightarrow \infty$ as $t \rightarrow \infty$ for $i = 1, 2, \dots, m$; $\tau(t) \rightarrow \infty$ as $t \rightarrow \infty$; $f_i(u) \in C(\mathbb{R}, \mathbb{R})$ are nondecreasing functions, $uf_i(u) > 0$ for $u \neq 0$ and $i = 1, 2, \dots, m$.

The purpose of the paper is to study oscillatory behaviour of solutions of equation (1.1). For the sake of convenience, the function $z(t)$ is defined by

$$z(t) = y(t) + P(t)y(\tau(t)). \quad (1.2)$$

2 Basic definitions and some auxiliary lemmas

A time scale \mathbb{T} is an arbitrary nonempty closed subset of the real numbers \mathbb{R} . For $t \in \mathbb{T}$, we define the *forward jump operator* $\sigma : \mathbb{T} \rightarrow \mathbb{T}$ by

$$\sigma(t) := \inf\{s \in \mathbb{T} : s > t\}$$

while the *backward jump operator* $\rho : \mathbb{T} \rightarrow \mathbb{T}$ is defined by

$$\rho(t) := \sup\{s \in \mathbb{T} : s < t\}.$$

If $\sigma(t) > t$, we say that t is *right-scattered*, while if $\rho(t) < t$, we say that t is *left-scattered*. Also, if $\sigma(t) = t$, then t is called *right-dense*, and if $\rho(t) = t$, then t is called *left-dense*. The *graininess function* $\mu : \mathbb{T} \rightarrow [0, \infty)$ is defined by

$$\mu(t) := \sigma(t) - t.$$

We introduce the set \mathbb{T}^κ which is derived from the time scale \mathbb{T} as follows. If \mathbb{T} has left-scattered maximum m , then $\mathbb{T}^\kappa = \mathbb{T} - \{m\}$, otherwise $\mathbb{T}^\kappa = \mathbb{T}$.

Definition 1 [1] The function $f : \mathbb{T} \rightarrow \mathbb{R}$ is called *rd-continuous* provided it is continuous at right-dense points in \mathbb{T} and its left-sided limits exist (finite) at left-dense points in \mathbb{T} .

Theorem 1 [1] Assume that $v : \mathbb{T} \rightarrow \mathbb{R}$ is strictly increasing and $\tilde{\mathbb{T}} := v(\mathbb{T})$ is a time scale. Let $w : \tilde{\mathbb{T}} \rightarrow \mathbb{R}$. If $v^\Delta(t)$ and $w^{\tilde{\Delta}}(v(t))$ exist for $t \in \mathbb{T}^\kappa$, then

$$(w \circ v)^\Delta = (w^{\tilde{\Delta}} \circ v)v^\Delta,$$

where we denote the derivative on $\tilde{\mathbb{T}}$ by $\tilde{\Delta}$.

Definition 2 [1] Let $f : \mathbb{T} \rightarrow \mathbb{R}$ be a function. If there exists a function $F : \mathbb{T} \rightarrow \mathbb{R}$ such that $F^\Delta(t) = f(t)$ for all $t \in \mathbb{T}^\kappa$, then F is said to be an antiderivative of f . We define the Cauchy integral by

$$\int_a^b f(\tau) \Delta(\tau) = F(b) - F(a) \quad \text{for } a, b \in \mathbb{T}.$$

Theorem 2 [2] Let u and v be continuous functions on $[a, b]$ that are Δ -differentiable on $[a, b]$. If u^Δ and v^Δ are integrable from a to b , then

$$\int_a^b u^\Delta(t)v(t)\Delta(t) + \int_a^b u^\sigma(t)v^\Delta(t)\Delta(t) = u(b)v(b) - u(a)v(a).$$

Let $\tilde{\mathbb{T}} = \mathbb{T} \cup \{\sup \mathbb{T}\} \cup \{\inf \mathbb{T}\}$. If $\infty \in \tilde{\mathbb{T}}$, we call ∞ left-dense, and $-\infty$ is called right-dense provided $-\infty \in \tilde{\mathbb{T}}$. For any left-dense $t_0 \in \tilde{\mathbb{T}}$ and any $\varepsilon > 0$, the set

$$L_\varepsilon(t_0) = \{t \in \mathbb{T} : 0 < t_0 - t < \varepsilon\}$$

is nonempty, and so is $L_\varepsilon(\infty) = \{t \in \mathbb{T} : t > \frac{1}{\varepsilon}\}$ if $\infty \in \tilde{\mathbb{T}}$.

Lemma 1 [3] Let $n \in \mathbb{N}$ and f be n -times differentiable on \mathbb{T} . Assume $\infty \in \tilde{\mathbb{T}}$. Suppose there exists $\varepsilon > 0$ such that

$$f(t) > 0, \quad \text{sgn}(f^{\Delta^n}(t)) \equiv s \in \{-1, +1\} \quad \text{for all } t \in L_\varepsilon(\infty)$$

and $f^{\Delta^n}(t) \neq 0$ on $L_\delta(\infty)$ for any $\delta > 0$. Then there exists $p \in [0, n] \cap \mathbb{N}_0$ such that $n + p$ is even for $s = 1$ and odd for $s = -1$ with

$$\begin{cases} (-1)^{p+j} f^{\Delta^j}(t) > 0 & \text{for all } t \in L_\varepsilon(\infty), j \in [p, n-1] \cap \mathbb{N}_0, \\ f^{\Delta^j}(t) > 0 & \text{for all } t \in L_{\delta_j}(\infty) \text{ (with } \delta_j \in (0, \varepsilon)), j \in [1, p-1] \cap \mathbb{N}_0. \end{cases}$$

Lemma 2 [3] Let f be n -times differentiable on \mathbb{T}^{κ^n} , $t \in \mathbb{T}$, and $\alpha \in \mathbb{T}^{\kappa^n}$. Then with the functions h_k defined as $h_n(t, s) = (-1)^n g_n(s, t)$,

$$h_0(r, s) \equiv 1 \quad \text{and} \quad h_{k+1}(r, s) = \int_s^r h_k(\tau, s) \Delta s \quad \text{for } k \in \mathbb{N}_0,$$

we have

$$f(t) = \sum_{k=0}^{n-1} h_k(t, \alpha) f^{\Delta^k}(\alpha) + \int_\alpha^{\rho^{n-1}(t)} h_{n-1}(t, \sigma(\tau)) f^{\Delta^n}(\tau) \Delta \tau.$$

Lemma 3 [3] Let f be n -times differentiable on \mathbb{T}^{κ^n} and $m \in \mathbb{N}$ with $m < n$. Then we have, for all $\alpha \in \mathbb{T}^{\kappa^{n-1+m}}$ and $t \in \mathbb{T}^{\kappa^m}$,

$$f^{\Delta^m}(t) = \sum_{k=0}^{n-m-1} h_k(t, \alpha) f^{\Delta^{k+m}}(\alpha) + \int_\alpha^{\rho^{n-m-1}(t)} h_{n-m-1}(t, \sigma(\tau)) f^{\Delta^n}(\tau) \Delta \tau.$$

Lemma 4 [3] Suppose f is n -times differentiable and g_k , $0 \leq k \leq n-1$, are differentiable at $t \in \mathbb{T}^{\kappa^n}$ with

$$g_{k+1}^\Delta(t) = g_k(\sigma(t)) \quad \text{for all } 0 \leq k \leq n-2.$$

Then we have

$$\left[\sum_{k=0}^{n-1} (-1)^k f^{\Delta^k} g_k \right]^\Delta = f g_0^\Delta + (-1)^{n-1} f^{\Delta^n} g_{n-1}^\sigma.$$

3 Main results

Lemma 5 Let f be n -times differentiable on \mathbb{T}^{κ^n} . If $f^\Delta > 0$, then for every λ , $0 < \lambda < 1$, we have

$$f(t) \geq \lambda (-1)^{n-1} g_{n-1}(\sigma(T^*), t) f^{\Delta^{n-1}}(t). \quad (3.1)$$

Proof Let p , $0 \leq p \leq n-1$, be the integer assigned to the function f as in Lemma 1. Because of $f^\Delta > 0$, we always have $p > 0$. Furthermore, let $T^* \geq T$ be assigned to f by Lemma 1. Then, by using the Taylor formula on time scales, for every $\rho^{n-1}(t) \geq T^*$, we obtain

$$f(t) \geq \int_{T^*}^{\rho^{n-1}(t)} (-1)^{n-1} g_{n-1}(\sigma(\tau), t) f^{\Delta^n}(\tau) \Delta \tau. \quad (3.2)$$

By using Theorem 2 and (3.2), we have

$$f(t) \geq (-1)^{n-1} g_{n-1}(\sigma(t), t) f^{\Delta^{n-1}}(t) - \int_{T^*}^{\rho^{n-1}(t)} (-1)^{n-1} g_{n-1}(\sigma(\tau), t) f^{\Delta^{n-1}}(\tau) \Delta \tau.$$

Since f is n -times differentiable on \mathbb{T}^{κ^n} and $m \in \mathbb{N}$ with $m < n$, we have with n and f substituted by $n - m$ and f^{Δ^m} , respectively

$$f^{\Delta^m}(t) \geq \int_{T^*}^{\rho^{n-m-1}(t)} (-1)^{n-m-1} g_{n-m-1}(\sigma(\tau), t) f^{\Delta^n}(\tau) \Delta \tau.$$

Also, for every $\rho^{n-1}(t)$, s with $\rho^{n-1}(t) \geq T^*$ and $T^* \leq s \leq t$, we have

$$f^{\Delta^m}(s) \geq (-1)^{n-m-1} g_{n-m-1}(\sigma(T^*), t) f^{\Delta^n}(t).$$

This is obvious for $m = n - 1$ and, when $m < n - 1$, it can be derived by applying the Taylor formula. Thus, for all $t \geq T^*$, we get

$$f(t) \geq (-1)^{n-1} g_{n-1}(\sigma(T^*), t) f^{\Delta^{n-1}}(t)$$

and therefore the proof of the lemma can be immediately completed. \square

The result of Lemma 5 is an extension of studies in [4] and [5]. In order that the reader sees how the results in [4] (1.8.14) and [5] (Lemma 2) follow from (3.1), it is at this point only necessary to know that in the case $\mathbb{T} = \mathbb{Z}$, we have $\rho(t) = t - 1$, $\sigma(t) = t + 1$ and

$$g_{n-1}(\sigma(T^*), t) = \frac{(t - T^* - 1)^{(n-1)}}{(n-1)!},$$

then we get the inequality in [4]

$$u(t) \geq \frac{1}{(n-1)!} (n - n_1)^{(n-1)} \Delta^{n-1} u(2^{n-m-1} n);$$

and in the case $\mathbb{T} = \mathbb{R}$, we have $\rho(t) = \sigma(t) = t$ and

$$g_{n-1}(\sigma(T^*), t) = \frac{(t - T^*)^{(n-1)}}{(n-1)!},$$

then we get the inequality in [5]

$$u(t) \geq \frac{\vartheta}{(n-1)!} (t)^{n-1} u^{n-1}(t).$$

For the cases $\mathbb{T} = \mathbb{Z}$ and $\mathbb{T} = \mathbb{R}$, some sufficient criterias for oscillatory behaviour of the solutions of the equation (1.1) were obtained by Bolat and Akin in [6] and [7], respectively. Furthermore, there might be other time scales that we cannot appreciate at this time due to our current lack of 'real-world' examples.

Theorem 3 Assume that n is odd and

$$(C1) \quad \lim_{t \rightarrow \infty} P(t) = 0,$$

$$(C2) \quad \int_{t_0}^{\infty} s^{n-1} \sum_{i=1}^m Q_i(s) \Delta s = \infty.$$

Then every bounded solution of equation (1.1) is either oscillatory or tends to zero as $t \rightarrow \infty$.

Proof Assume that equation (1.1) has a bounded non-oscillatory solution $y(t)$. Without loss of generality, assume that $y(t)$ is eventually positive (the proof is similar when $y(t)$ is eventually negative). That is, $y(t) > 0$, $y(\tau(t)) > 0$ and $y(\phi_i(t)) > 0$ for $t \geq t_1 \geq t_0$ and $i = 1, 2, \dots, m$. Assume further that $y(t)$ does not tend to zero as $t \rightarrow \infty$. By (1.1), (1.2), we have for $t \geq t_1$

$$z^{\Delta^n}(t) = - \sum_{i=1}^m Q_i(t) f_i(y(\phi_i(t))) < 0. \quad (3.3)$$

It follows that $z^{\Delta^j}(t)$ ($j \in [0, n-1] \cap \mathbb{N}_0$) is strictly monotone and eventually of constant sign. Since $P(t)$ is an oscillatory function, there exists a $t_2 \geq t_1$ such that if $t \geq t_2$, then $z(t) > 0$. Since $y(t)$ is bounded, by virtue of (C1) and (1.2), there is a $t_3 \geq t_2$ such that $z(t)$ is also bounded for $t \geq t_3$. Because n is odd and $z(t)$ is bounded, by Lemma 1, when $p = 0$ (otherwise $z(t)$ is not bounded), there exists $t_4 \geq t_3$ such that for $t \geq t_4$ we have $(-1)^j z^{\Delta^j}(t) > 0$, $j \in [0, n-1] \cap \mathbb{N}_0$.

In particular, since $z^{\Delta}(t) < 0$ for $t \geq t_4$, $z(t)$ is decreasing. Since $z(t)$ is bounded, we write $\lim_{t \rightarrow \infty} z(t) = L$ ($-\infty < L < \infty$). Assume that $0 \leq L < \infty$. Let $L > 0$. Then there exists a constant $c > 0$ and a $t_5 \geq t_4$ such that $z(t) > c > 0$ for $t \geq t_5$. Since $y(t)$ is bounded, $\lim_{t \rightarrow \infty} P(t)y(\tau(t)) = 0$ by (C1). Therefore, there exists a constant $c_1 > 0$ and a $t_6 \geq t_5$ such that $y(t) = z(t) - P(t)y(\tau(t)) > c_1 > 0$ for $t \geq t_6$. So that we can find a t_7 with $t_7 \geq t_6$ such that $y(\phi_i(t)) > c_1 > 0$ for $t \geq t_7$. From (3.3) we have

$$z^{\Delta^n}(t) = - \sum_{i=1}^m Q_i(t) f_i(c_1) < 0 \quad (3.4)$$

for $t \geq t_7$. If we multiply (3.4) by t^{n-1} and integrate it from t_7 to t , we obtain

$$F(t) - F(t_7) \leq -f(c_1) \int_{t_7}^t \sum_{i=1}^m Q_i(s) s^{n-1} \Delta s, \quad (3.5)$$

where

$$F(t) = \sum_{i=1}^{n-1} (-1)^{i+1} (t^{n-1})^{\Delta^i} z^{\Delta^{n-i}}(\sigma^i(t))$$

and

$$\sigma^i(t) = \sigma(\sigma^{i-1}(t)).$$

Since $(-1)^k z^{\Delta^k}(t) > 0$ for $k = 0, 1, 2, \dots, n-1$ and $t \geq t_4$, we have $F(t) > 0$ for $t \geq t_7$. From (3.5) we have

$$-F(t_7) \leq -f(c_1) \int_{t_7}^t \sum_{i=1}^m Q_i(s) s^{n-1} \Delta s.$$

By (C2) we obtain

$$-F(t_7) \leq -f(c_1) \int_{t_7}^t \sum_{i=1}^m Q_i(s) s^{n-1} \Delta s = -\infty$$

as $t \rightarrow \infty$. This is a contradiction. So, $L > 0$ is impossible. Therefore, $L = 0$ is the only possible case. That is, $\lim_{t \rightarrow \infty} z(t) = 0$. Since $y(t)$ is bounded, by (C1) we obtain

$$\lim_{t \rightarrow \infty} y(t) = \lim_{t \rightarrow \infty} z(t) - \lim_{t \rightarrow \infty} P(t)y(t) = 0$$

from (1.2).

Now let us consider the case of $y(t) < 0$ for $t \geq t_1$. By (1.1) and (1.2),

$$z^{\Delta^n}(t) = - \sum_{i=1}^m Q_i(t) f_i(y(\phi_i(t))) > 0$$

for $t \geq t_1$. That is, $z^{\Delta^n} > 0$. It follows that $z^{\Delta^j}(t)$ ($j \in [0, n-1] \cap \mathbb{N}_0$) is strictly monotone and eventually of constant sign. Since $P(t)$ is an oscillatory function, there exists a $t_2 \geq t_1$ such that if $t \geq t_2$, then $z(t) < 0$. Since $y(t)$ is bounded, by (C1) and (1.2), there is a $t_3 \geq t_2$ such that $z(t)$ is also bounded for $t \geq t_3$. Assume that $x(t) = -z(t)$. Then $x^{\Delta^n}(t) = -z^{\Delta^n}(t)$. Therefore, $x(t) > 0$ and $x^{\Delta^n}(t) < 0$ for $t \geq t_3$. Hence, we observe that $x(t)$ is bounded. Since n is odd, by Lemma 1, there exists a $t_4 \geq t_3$ and $p = 0$ (otherwise $x(t)$ is not bounded) such that $(-1)^j x^{\Delta^j}(t) > 0$, $j \in [0, n-1] \cap \mathbb{N}_0$ and $t \geq t_4$. That is, $(-1)^j z^{\Delta^j}(t) < 0$, $j \in [0, n-1] \cap \mathbb{N}_0$ and $t \geq t_4$. In particular, for $t \geq t_4$ we have $z^{\Delta}(t) > 0$. Therefore, $z(t)$ is increasing. So, we can assume that $\lim_{t \rightarrow \infty} z(t) = L$ ($-\infty < L \leq 0$). As in the proof of $y(t) > 0$, we may prove that $L = 0$. As for the rest, it is similar to the case of $y(t) > 0$. That is, $\lim_{t \rightarrow \infty} y(t) = 0$. This contradicts our assumption. Hence the proof is completed. \square

Theorem 4 Assume that n is even and (C1) holds. If the following condition is satisfied:

(C3) There is a function $\varphi(t)$ such that $\varphi(t) \in C_{rd}^1[t_0, \infty)_{\mathbb{T}}$. Moreover,

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t \varphi(s) \sum_{i=1}^m Q_i(s) \Delta s = \infty$$

and

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t \frac{[\varphi^{\Delta}(s)]^2}{\varphi(s) g_{n-2}^{\sigma}(\sigma(\phi_i(s)), \phi_i(s))} \Delta s < \infty$$

for $\varphi(t)$ and $i = 1, 2, \dots, m$. Then every bounded solution of equation (1.1) is oscillatory.

Proof Assume that equation (1.1) has a bounded non-oscillatory solution $y(t)$. Without loss of generality, assume that $y(t)$ is eventually positive (the proof is similar when $y(t)$ is eventually negative). That is, $y(t) > 0$, $y(\tau(t)) > 0$ and $y(\phi_i(t)) > 0$ for $t \geq t_1 \geq t_0$. By (1.1) and (1.2), we have (3.3) for $t \geq t_1$. Then $z^{\Delta^n}(t) < 0$. It follows that $z^{\Delta^j}(t)$ ($j \in [0, n-1] \cap \mathbb{N}_0$) is strictly monotone and eventually of constant sign. Since $P(t)$ is an oscillatory function, there exists a $t_2 \geq t_1$ such that for $t \geq t_2$, we have $z(t) > 0$. Since $y(t)$ is bounded, by (C1)

and (1.2), there is a $t_3 \geq t_2$, such that $z(t)$ is also bounded for $t \geq t_3$. Because n is even, by Lemma 1 when $p = 1$ (otherwise $z(t)$ is not bounded), there exists $t_4 \geq t_3$ such that for $t \geq t_4$ we have

$$(-1)^{i+1} z^{\Delta^i}(t) > 0, \quad j \in [0, n-1] \cap \mathbb{N}_0. \quad (3.6)$$

In particular, since $z^{\Delta}(t) > 0$ for $t \geq t_4$, $z(t)$ is increasing. Since $y(t)$ is bounded,

$$\lim_{t \rightarrow \infty} P(t)y(\tau(t)) = 0$$

by (C1). Let $\delta > 1$; i.e., there exists a $t_5 \geq t_4$ such that by (1.2)

$$y(t) = z(t) - P(t)y(\tau(t)) > \frac{1}{\delta} z(t) > 0$$

for $t \geq t_5$. We may find a $t_6 \geq t_5$ such that for $t \geq t_6$ and $i = 1, 2, \dots, m$,

$$y(\phi_i(t)) > \frac{1}{\delta} z(\phi_i(t)) > 0. \quad (3.7)$$

From (3.3), (3.7) and the properties of f , we have

$$\begin{aligned} z^{\Delta^n}(t) &\leq - \sum_{i=1}^m Q_i(t) f_i\left(\frac{1}{\delta} z(\phi_i(t))\right) \\ &= - \sum_{i=1}^m Q_i(t) \frac{f_i(\frac{1}{\delta} z(\phi_i(t)))}{z(\phi_i(t))} z(\phi_i(t)) \end{aligned} \quad (3.8)$$

for $t \geq t_6$. Since $z(t) > 0$ is bounded and increasing, $\lim_{t \rightarrow \infty} z(t) = L$ ($0 < L < \infty$). By the continuity of f , we have

$$\lim_{t \rightarrow \infty} \frac{f_i(\frac{1}{\delta} z(\phi_i(t)))}{z(\phi_i(t))} = \frac{f_i(\frac{L}{\delta})}{L} > 0.$$

Then there is a $t_7 \geq t_6$ such that for $t \geq t_7$, $i = 1, 2, \dots, m$, we have

$$\frac{f_i(\frac{1}{\delta} z(\phi_i(t)))}{z(\phi_i(t))} \geq \frac{f_i(\frac{L}{\delta})}{2L} = \alpha > 0. \quad (3.9)$$

By (3.8), (3.9),

$$z^{\Delta^n}(t) \leq -\alpha \sum_{i=1}^m Q_i(t) z(\phi_i(t)) \quad \text{for } t \geq t_7. \quad (3.10)$$

Set

$$w(t) = \frac{z^{\Delta^{n-1}}(t)}{z(\frac{1}{\delta} \phi_i(t))}. \quad (3.11)$$

We know from (3.6) that there is a $t_8 \geq t_7$ such that for a sufficiently large $t \geq t_8$, $w(t) > 0$.

Therefore, Δ -derivating (3.11) we obtain

$$\begin{aligned} w^\Delta(t) &= \frac{z^{\Delta^n}(t)}{z(\delta^{-1}\phi_i(t))} + z^{\Delta^{n-1}}(\sigma(t)) \left(\frac{1}{z(\delta^{-1}\phi_i(t))} \right)^\Delta \\ &= \frac{z^{\Delta^n}(t)}{z(\delta^{-1}\phi_i(t))} - \frac{\delta^{-1}\phi_i^\Delta(t) z^{\Delta^{n-1}}(\sigma(t)) z^\Delta(\delta^{-1}\phi_i(t))}{z(\delta^{-1}\phi_i(t)) z(\delta^{-1}\phi_i(\sigma(t)))} \end{aligned} \quad (3.12)$$

$$\begin{aligned} &\leq \frac{z^{\Delta^n}(t)}{z(\delta^{-1}\phi_i(t))} - \frac{\delta^{-1}\phi_i^\Delta(t) z^{\Delta^{n-1}}(\sigma(t)) z^\Delta(\delta^{-1}\phi_i(t))}{z^2(\delta^{-1}\phi_i(\sigma(t)))} \\ &= \frac{z^{\Delta^n}(t)}{z(\delta^{-1}\phi_i(t))} - \delta^{-1} w^\sigma(t) \frac{\phi_i^\Delta(t) z^\Delta(\delta^{-1}\phi_i(t))}{z(\delta^{-1}\phi_i(\sigma(t)))}. \end{aligned} \quad (3.13)$$

We know from (3.6) that there is a $t \geq t_9$ such that $z^\Delta(t) > 0$ and $z^{\Delta^{n-1}}(t) > 0$ for an even n . Since $z(t) > 0$ is increasing $z(\delta^{-1}\phi_i(\sigma(t))) \geq z(\delta^{-1}\phi_i(t))$ for $i = 1, 2, \dots, m$. Therefore, by Lemma 5,

$$z(\delta^{-1}\phi_i(t)) \geq \lambda(-1)^{n-1} g_{n-1}(\sigma(\phi_i(t)), \phi_i(t)) z^{\Delta^{n-1}}(\phi_i(t)). \quad (3.14)$$

Then by Δ -derivating (3.14) and using $g_{n-1}^\Delta(\sigma(t), t) = g_{n-2}^\sigma(\sigma(t), t)$, we get

$$\begin{aligned} [z(\delta^{-1}\phi_i(t))]^\Delta &\geq \lambda(-1)^{n-2} g_{n-1}^\Delta(\sigma(\phi_i(t)), \phi_i(t)) z^{\Delta^{n-1}}(\phi_i(t)) \\ &\geq \lambda(-1)^{n-2} g_{n-2}^\sigma(\sigma(\phi_i(t)), \phi_i(t)) z^{\Delta^{n-1}}(\phi_i(t)) \end{aligned}$$

by Lemma 2

$$z^\Delta(\delta^{-1}\phi_i(t)) \delta^{-1}\phi_i^\Delta(t) \geq \lambda(-1)^{n-2} g_{n-2}^\sigma(\sigma(\phi_i(t)), \phi_i(t)) z^{\Delta^{n-1}}(\phi_i(t)).$$

Since $\phi_i(t) \leq t$, we obtain

$$z^\Delta(\delta^{-1}\phi_i(t)) \geq \frac{\delta \lambda(-1)^{n-2} g_{n-2}^\sigma(\sigma(\phi_i(t)), \phi_i(t)) z^{\Delta^{n-1}}(t)}{\phi_i^\Delta(t)}. \quad (3.15)$$

Hence by (3.10), (3.14) and (3.15), we have

$$\begin{aligned} w^\Delta(t) &\leq \frac{-\alpha \sum_{i=1}^m Q_i(t) z(\phi_i(t))}{z(\delta^{-1}\phi_i(t))} \\ &\quad - \delta^{-1} w^\sigma(t) \frac{\delta \lambda(-1)^{n-2} g_{n-2}^\sigma(\sigma(\phi_i(t)), \phi_i(t)) z^{\Delta^{n-1}}(t)}{\phi_i^\Delta(t)} \frac{\phi_i^\Delta(t)}{z(\delta^{-1}\phi_i(\sigma(t)))} \\ &\leq \frac{-\alpha \sum_{i=1}^m Q_i(t) z(\phi_i(t))}{z(\delta^{-1}\phi_i(t))} \\ &\quad - \delta^{-1} w^\sigma(t) \frac{\delta \lambda(-1)^{n-2} g_{n-2}^\sigma(\sigma(\phi_i(t)), \phi_i(t)) \phi_i^\Delta(t)}{\phi_i^\Delta(t)} \frac{z^{\Delta^{n-1}}(\sigma(t))}{z(\delta^{-1}\phi_i(\sigma(t)))} \\ &\leq -\alpha \sum_{i=1}^m Q_i(t) - \lambda(-1)^{n-2} g_{n-2}^\sigma(\sigma(\phi_i(t)), \phi_i(t)) (w^\sigma(t))^2, \end{aligned}$$

and then

$$\alpha \sum_{i=1}^m Q_i(t) \leq -w^\Delta(t) - \lambda(-1)^{n-2} w^2(t) g_{n-2}^\sigma(\sigma(\phi_i(t)), \phi_i(t)) \quad (3.16)$$

for $t \geq t_{10}$. If we multiply (3.16) by $\varphi(t)$ and integrate it from t_{10} to t , we obtain by Theorem 2

$$\begin{aligned} \alpha \int_{t_{10}}^t \varphi(s) \sum_{i=1}^m Q_i(s) \Delta s &\leq - \int_{t_{10}}^t \varphi(s) w^\Delta(s) \Delta s \\ &\quad - \int_{t_{10}}^t \lambda(-1)^{n-2} \varphi(s) w^2(s) g_{n-2}^\sigma(\sigma(\phi_i(s)), \phi_i(s)) \Delta s \\ &\leq - \left[\varphi(t) w(t) - \varphi(t_{10}) w(t_{10}) - \int_{t_{10}}^t \varphi^\Delta(s) w^\sigma(t) \Delta s \right] \\ &\quad - \int_{t_{10}}^t \lambda(-1)^{n-2} \varphi(s) w^2(s) g_{n-2}^\sigma(\sigma(\phi_i(s)), \phi_i(s)) \Delta s \\ &\leq \varphi(t_{10}) w(t_{10}) + \int_{t_{10}}^t \varphi^\Delta(s) w^\sigma(t) \Delta s \\ &\quad - \lambda \int_{t_{10}}^t \varphi(s) w^2(s) g_{n-2}^\sigma(\sigma(\phi_i(s)), \phi_i(s)) \Delta s \\ &\leq \varphi(t_{10}) w(t_{10}) - \lambda \int_{t_{10}}^t \varphi(s) g_{n-2}^\sigma(\sigma(\phi_i(s)), \phi_i(s)) \\ &\quad \times \left[w(s) - \frac{\varphi^\Delta(s)}{2\lambda \varphi(s) g_{n-2}^\sigma(\sigma(\phi_i(s)), \phi_i(s))} \right]^2 \Delta s \\ &\quad + \int_{t_{10}}^t \frac{[\varphi^\Delta(s)]^2}{4\lambda \varphi(s) g_{n-2}^\sigma(\sigma(\phi_i(s)), \phi_i(s))} \Delta s \\ &\leq \varphi(t_{10}) w(t_{10}) + \int_{t_{10}}^t \frac{[\varphi^\Delta(s)]^2}{4\lambda \varphi(s) g_{n-2}^\sigma(\sigma(\phi_i(s)), \phi_i(s))} \Delta s. \end{aligned}$$

Therefore by (C3),

$$\begin{aligned} \infty &= \alpha \limsup_{t \rightarrow \infty} \int_{t_{10}}^t \varphi(s) \sum_{i=1}^m Q_i(s) \Delta s \\ &\leq \varphi(t_{10}) w(t_{10}) + \frac{1}{4\lambda} \limsup_{t \rightarrow \infty} \int_{t_{10}}^t \frac{[\varphi^\Delta(s)]^2}{\varphi(s) g_{n-2}^\sigma(\sigma(\phi_i(s)), \phi_i(s))} \Delta s \\ &< \infty. \end{aligned}$$

This is a contradiction.

Now let us consider the case of $y(t) < 0$ for $t \geq t_1$. By (1.1) and (1.2), we have

$$z^{\Delta^n}(t) = - \sum_{i=1}^m Q_i(t) f_i(y(\phi_i(t))) > 0$$

for $t \geq t_1$. That is, $z^{\Delta^n} > 0$. It follows that $z^{\Delta^j}(t)$ ($j \in [0, n-1] \cap \mathbb{N}_0$) is strictly monotone and eventually of constant sign. Since $P(t)$ is an oscillatory function, there exists a $t_2 \geq t_1$ such that $z(t) < 0$ for $t \geq t_2$. Since $y(t)$ is bounded, by (C1) and (1.2), there is a $t_3 \geq t_2$ such that $z(t)$ is also bounded for $t \geq t_3$. Assume that $x(t) = -z(t)$. Then $x^{\Delta^n}(t) = -z^{\Delta^n}(t)$. Therefore, $x(t) > 0$ and $x^{\Delta^n}(t) < 0$ for $t \geq t_3$. Hence, we observe that $x(t)$ is bounded. Since n is odd, by Lemma 1, there exists a $t_4 \geq t_3$ and $p = 1$ (otherwise $x(t)$ is not bounded) such that $(-1)^k x^{\Delta^k}(t) > 0$, $k \in [0, n-1] \cap \mathbb{N}_0$ and $t \geq t_4$. That is, $(-1)^k z^{\Delta^k}(t) < 0$, $k \in [0, n-1] \cap \mathbb{N}_0$ and $t \geq t_4$. In particular, for $t \geq t_4$ we have $z^{\Delta}(t) > 0$. Therefore, $z(t)$ is increasing. For the rest of the proof, we can proceed the proof similarly to the case of $y(t) > 0$. Hence, the proof is completed. \square

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

DU carried out the time scale studies, participated in the sequence alignment, drafted the manuscript, and have given final approval of the version to be published. YB carried out the preliminaries of the manuscript and participated in the sequence alignment. Each author have participated sufficiently in the work to take public responsibility for appropriate portions of the content. Authors read and approved the final manuscript.

Author details

¹Department of Mathematics, Faculty of Sciences and Arts, Usak University, 1 Eylül Campus, Usak, 64200, Turkey.

²Department of Mathematics, Faculty of Sciences and Literatures, Kastamonu University, Kastamonu, Turkey.

Received: 26 September 2012 Accepted: 30 January 2013 Published: 15 February 2013

References

1. Bohner, M, Peterson, A: Dynamic Equations on Time Scales. An Introduction with Applications. Birkhäuser, Boston (2001)
2. Bohner, M, Peterson, A: Advances in Dynamic Equations on Time Scales. Birkhäuser, Boston (2003)
3. Bohner, M, Agarwal, RP: Basic calculus on time scales and some of its applications. *Results Math.* **35**(1-2), 3-22 (1999)
4. Agarwall, RP: Difference Equations and Inequalities, Theory, Methods, and Applications. Dekker, New York (1992)
5. Philos, CG: A new criterion for the oscillatory and asymptotic behavior of delay differential equations. *Bull. Acad. Pol. Sci., Sér. Sci. Math.* **29**, 7-8 (1981)
6. Bolat, Y, Akin, Ö: Oscillatory behaviour of a higher order nonlinear neutral type functional difference equation with oscillating coefficients. *Appl. Math. Lett.* **17**, 1073-1078 (2004)
7. Bolat, Y, Akin, Ö: Oscillatory behaviour of a higher order nonlinear neutral delay type functional differential equation with oscillating coefficients. *Czechoslov. Math. J.* **55**(130), 893-900 (2005)

doi:10.1186/1029-242X-2013-52

Cite this article as: Uçar and Bolat: Oscillatory behaviour of a higher-order dynamic equation. *Journal of Inequalities and Applications* 2013 **2013**:52.

Submit your manuscript to a SpringerOpen[®] journal and benefit from:

- Convenient online submission
- Rigorous peer review
- Immediate publication on acceptance
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

Submit your next manuscript at ► springeropen.com