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Compact matrix operators on a new sequence space related to ℓ_p spaces

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Abstract

In this paper, we derive some identities or estimates for the operator norms and the Hausdorff measures of noncompactness of certain matrix operators on the sequence space $\ell_p(r, s, t; B^{(m)})$ which is related to ℓ_p spaces. By applying the Hausdorff measure of noncompactness, we obtain the necessary and sufficient conditions for such operators to be compact. Further, we study some geometric properties of this space.

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1 Background, notation, and preliminaries

Let *w* denote the space of all complex sequences $x = (x_k)_{k=0}^{\infty}$. By ℓ_{∞} , *c*, *c*₀, and ϕ we denote the sets of all bounded, convergent, null, and finite sequences, respectively. We write *cs* for the set of all convergent series and

$$\ell_p = \left\{ x \in \omega : \sum_{k=0}^{\infty} |x_k|^p < \infty \right\} \quad \text{for } 1 \le p < \infty.$$

By *e* and $e^{(n)}$ (n = 0, 1, ...), we denote the sequences with $e_k = 1$ for all k, and $e_n^{(n)} = 1$ and $e_k^{(n)} = 0$ for $k \neq n$, respectively. For any sequence $x = (x_k)_{k=0}^{\infty}$, let

$$x^{[m]} = \sum_{k=0}^m x_k e^{(k)}$$

be its *m*-section.

Let *x* and *y* be sequences, *X* and *Y* be subsets of ω and $A = (a_{nk})_{n,k=0}^{\infty}$ be an infinite matrix of complex numbers. We write $xy = (x_k y_k)_{k=0}^{\infty}$,

$$Z = x^{-1} * Y = \{x \in \omega : xz \in Y\}, \qquad x^{\beta} = x^{-1} * cs,$$
$$X^{\beta} = \bigcap_{x \in X} x^{-1} * cs = \begin{cases} a \in \omega : \sum_{k=0}^{\infty} a_k x_k \text{ converges for all } x \in X \end{cases}$$

for the β -dual of *X*. Note that $\ell_{\infty}^{\beta} = c^{\beta} = c_0^{\beta} = \ell_1$, $\ell_1^{\beta} = \ell_{\infty}$ and $\ell_p^{\beta} = \ell_q$.

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By $A_n = (a_{nk})_{k=0}^{\infty}$ and $A^k = (a_{nk})_{n=0}^{\infty}$ we denote the sequences in the *n*th row and the *k*th column of *A*, and we write

$$A_n(x) = \sum_{k=0}^{\infty} a_{nk} x_k \quad (n = 0, 1, ...)$$
(1.1)

and $A(x) = (A_n(x))_{n=0}^{\infty}$, provided $A_n \in X^{\beta}$ for all *n*. The set $X_A = X(A) = \{z \in \omega : A(z) \in X\}$ is called the matrix domain of *A* in *X*. Finally (X, Y) denotes the class of all matrices *A* that map *X* into *Y*, that is for which $A_n \in X^{\beta}$ for all *n* and $A(x) \in Y$ for all $x \in X$, or equivalently $A \in (X, Y)$ if and only if $X \subset X_A$.

The theory of *BK* spaces is the most powerful tool in the characterization of matrix transformations between sequence spaces.

A sequence space *X* is called a *BK* space if it is a Banach space with continuous coordinates $p_n : X \to \mathbb{C}$ $(n \in \mathbb{N})$, where \mathbb{C} denotes the complex field and $p_n(x) = x_n$ for all $x = (x_k) \in X$ and every $n \in \mathbb{N}$. A *BK* space $X \supset \phi$ is said to have *AK* if every sequence $x = (x_k) \in X$ has a unique representation $x = \sum_{k=0}^{\infty} x_k e^{(k)}$.

The sequence spaces ℓ_{∞} , c, and c_0 are BK spaces with the same sup-norm given by $||x||_{\ell_{\infty}} = \sup_k |x_k|$, where the supremum is taken over all $k \in \mathbb{N}$. Further, the space ℓ_p is a BK space with the usual ℓ_p -norm defined by $||x||_{\ell_p} = (\sum_{k=0}^{\infty} |x_k|^p)^{1/p}$, where $1 \le p < \infty$. Moreover, the BK spaces c_0 and ℓ_p $(1 \le p < \infty)$ have AK [1], Examples 1.13, 1.20.

Let *X* and *Y* be Banach spaces. Then $\mathcal{B}(X, Y)$ is the set of all bounded linear operators $L: X \to Y$, a Banach space with the operator norm defined as usual by

 $||L|| = \sup\{||L(x)|| / ||x|| \le 1\} \quad (L \in \mathcal{B}(X, Y)).$

If $Y = \mathbb{C}$ then we write X^* for the space of all continuous linear functionals on X with the norm defined by

$$||f|| = \sup\{|f(x)| : ||x|| \le 1\} \quad (f \in X^*).$$

If $X \subset w$ is a normed space and $a \in w$ then we write

$$\|a\|^* = \|a\|_X^* = \sup\left\{\left|\sum_{k=0}^{\infty} a_k x_k\right| : \|x\| \le 1\right\},\tag{1.2}$$

provided the expression on the right-hand side exists and is finite which is the case whenever $X \supset \phi$ is a *BK* space and $a \in X^{\beta}$ [2], p.35.

For any subset *X* of *w*, the matrix domain of an infinite matrix *A* in *X* is defined by

 $X_A = \{x \in w : Ax \in X\}.$

An infinite matrix $T = (t_{nk})$ is called a triangle if $t_{nn} \neq 0$ and $t_{nk} = 0$ for all k > n ($n \in \mathbb{N}$). The study of matrix domains of triangles in sequence spaces has a special importance due to the various properties which they have. For example, if X is a BK space then X_T is also a BK space with the norm given by $||x||_{X_T} = ||Tx||_X$ for all $x \in X_T$ [1], Theorem 4.3.12.

The following known results are fundamental for our investigation [2], Theorem 4.3.12.

Lemma 1.1

- (a) Let X denote any of the spaces c₀, c, ℓ_∞, ℓ₁ or ℓ_p. Then we have ||a||^{*}_X = ||a||_{X^β} for all a ∈ X^β, where || · ||_{X^β} is the natural norm on the dual space X^β.
- (b) Let X and Y be BK spaces. Then every matrix $A \in (X, Y)$ defines an operator $L_A \in B(X, Y)$ by $L_A(x) = Ax$ for all $x \in X$; we denote this by $(X, Y) \subset B(X, Y)$.
- (c) Let $X \supset \phi$ be a BK space and Y be any of the spaces c_0 , c or ℓ_{∞} . If $A \in (X, Y)$, then

 $||L_A|| = ||A||_{(X,\ell_{\infty})} = \sup_n ||A_n||_X^* < \infty.$

Also, let \mathcal{F} be the collection of all non-empty and finite subsets of $\mathbb{N} = \{0, 1, 2, ...\}$, throughout. Then we have the following result.

Lemma 1.2 Let $X \supset \phi$ be a BK space. If $A \in (X, \ell_1)$, then

 $||A||_{(X,\ell_1)} \le ||L_A|| \le 4 \cdot ||A||_{(X,\ell_1)}$,

where $||A||_{(X,\ell_1)} = \sup_{N \in \mathcal{F}} ||\sum_{n \in N} A_n||_X^* < \infty$.

For the reader's convenience, we list a few well-known definitions and results concerning the Hausdorff measure of noncompactness which can be found in [3, 4], and [2].

Let *S* and *M* be subsets of a metric space (X, d) and $\varepsilon > 0$. Then *S* is called an ε -net of *M* in *X* if for every $x \in M$ there exists $s \in S$ such that $d(x, s) < \varepsilon$. Further, if the set *S* is finite, then the ε -net *S* of *M* is called a *finite* ε -net of *M*, and we say that *M* has a finite ε -net in *X*. A subset *M* of a metric space *X* is said to be *totally bounded* if it has a finite ε -net for every $\varepsilon > 0$. If *X* is complete, then *M* is totally bounded if and only if *M* is relatively compact (its closure \overline{M} is a compact set). Let *X* and *Y* be Banach spaces. A linear operator $L : X \to Y$ is called compact if D(L) = X for the domain of *L* and, for every bounded sequence $(x_n)_{n=0}^{\infty}$ in *X*, the sequence $(L(x_n))_{n=0}^{\infty}$ has a convergent subsequence in *Y*.

By \mathcal{M}_X , we denote the collection of all bounded subsets of a metric space (X, d). If $Q \in \mathcal{M}_X$, then the *Hausdorff measure of noncompactness* of Q, is defined by

 $\chi(Q) = \inf\{\varepsilon > 0 : Q \text{ has a finite } \varepsilon \text{-net in } X\}.$

The function $\chi : \mathcal{M}_X \to [0, \infty)$ is called the *Hausdorff measure of noncompactness*.

It is well known that if Q, Q_1 , and Q_2 are bounded subsets of a metric space X, then we have

 $\chi(Q) = 0 \quad \text{if and only if} \quad Q \text{ is totally bounded,}$ $Q_1 \subset Q_2 \quad \text{implies} \quad \chi(Q_1) \leq \chi(Q_2),$ $\chi(Q) = \chi(\overline{Q}) \quad \text{for the closure } \overline{Q} \text{ of } Q,$ $\chi(Q_1 \cup Q_2) = \max(\chi(Q_1), \chi(Q_2)),$ $\chi(Q_1 \cap Q_2) \leq \min(\chi(Q_1), \chi(Q_2)).$

Further, if X is a normed space then we also have

$$\chi(Q_1 + Q_2) \le \chi(Q_1) + \chi(Q_2),$$

$$\chi(\alpha Q) = |\alpha|\chi(Q) \text{ for all } \alpha \in \mathbb{C}.$$

Let *X* and *Y* be Banach spaces and $L \in \mathcal{B}(X, Y)$. Then the *Hausdorff measure of noncompactness* of the operator *L*, denoted by $||L||_X$, is defined by

$$\|L\|_{\chi} = \chi \left(L(S_{\chi}) \right), \tag{1.3}$$

where $S = \{x \in X : ||x|| \le 1\}$ is the unit ball in *X*. Also we have

L is compact if and only if
$$||L||_{\chi} = 0.$$
 (1.4)

Now we shall point out the well-known result of Goldenštein, Gohberg, and Markus [5], Theorem 1, concerning the Hausdorff measure of noncompactness in Banach spaces. The Hausdorff measure of noncompactness of a bounded subset of the *BK* space ℓ_p ($1 \le p < \infty$) is given by the following result.

Lemma 1.3 Let X be a BK space with AK and monotone norm, $Q \in \mathcal{M}_X$, and $P_n : X \mapsto X$ $(n \in \mathbb{N})$ be the operator (projection) defined by $P_n(x_1, x_2, ...) = x^{[n]} = (x_1, x_2, ..., x_n, 0, 0, ...)$ for all $x = (x_1, x_2, ...) \in X$. Then

$$\chi(Q) = \lim_{n \to \infty} \left(\sup_{x \in Q} \left\| (I - P_n) x \right\| \right).$$

For some recent related work on this topic, we refer to [5-28], and [29]. For some applications in differential and integral equations, we refer to [4, 30-33], and [34].

2 Results and discussion

Throughout this paper, let $r, t \in U$ and $s \in U_o$, where

$$\mathcal{U} = \left\{ u = (u_k) \in w : u_k \neq 0 \text{ for all } k \right\} \text{ and } \mathcal{U}_o = \left\{ u = (u_k) \in w : u_0 \neq 0 \right\}.$$

For any sequence $x = (x_n) \in w$, we define the sequence $\bar{x} = (\bar{x}_n)$ of generalized means of x by

$$\bar{x}_n = \frac{1}{r_n} \sum_{k=0}^n s_{n-k} t_k x_k \quad (n \in \mathbb{N}).$$
(2.1)

Further, we define the infinite matrix $\overline{A}(r, s, t)$ of generalized means by

$$\left(\bar{A}(r,s,t)\right)_{nk} = \begin{cases} s_{n-k}t_k/r_n & (0 \le k \le n), \\ 0 & (k > n) \end{cases}$$
(2.2)

for all $n, k \in \mathbb{N}$. Then, by using the notation of (1.1), it follows by (2.1) that \bar{x} is the $\bar{A}(r, s, t)$ -transform of x, that is, $\bar{x} = (\bar{A}(r, s, t))x$ for all $x \in w$.

Moreover, it is obvious by (2.2) that $\bar{A}(r, s, t)$ is a triangle. Thus, it has a unique inverse $(\bar{A}(r, s, t))^{-1}$ which is also a triangle. More precisely, we put $D_0^{(s)} = 1/s_0$ and

$$D_n^{(s)} = \frac{1}{s_0^{n+1}} \begin{vmatrix} s_1 & s_0 & 0 & 0 & \cdots & 0 \\ s_2 & s_1 & s_0 & 0 & \cdots & 0 \\ s_3 & s_2 & s_1 & s_0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ s_{n-1} & s_{n-2} & s_{n-3} & s_{n-4} & \cdots & s_0 \\ s_n & s_{n-1} & s_{n-2} & s_{n-3} & \cdots & s_1 \end{vmatrix}$$
 $(n = 1, 2, 3, \ldots).$

Then the entries of $(\bar{A}(r, s, t))^{-1}$ are given by

$$\left(\bar{A}(r,s,t)\right)_{nk}^{-1} = \begin{cases} \left(-1\right)^{n-k} D_{n-k}^{(s)} r_k / t_n & (0 \le k \le n), \\ 0 & (k > n) \end{cases}$$
(2.3)

for all $n, k \in \mathbb{N}$, that is, $(\overline{A}(r, s, t))^{-1} = \overline{A}(t, s', r)$, where $s' = (s'_n)$ such that $s'_n = (-1)^n D_n^{(s)}$ for all $n \in \mathbb{N}$ [35], p.990. Therefore, we have by (2.1) that

$$x_n = \frac{1}{t_n} \sum_{k=0}^n (-1)^{n-k} D_{n-k}^{(s)} r_k \bar{x}_k \quad (n \in \mathbb{N}).$$
(2.4)

For an arbitrary subset *X* of *w*, the set *X*(*r*, *s*, *t*) has recently been introduced in [35] as the matrix domain of the triangle $\overline{A}(r, s, t)$ in *X*, that is,

$$X(r,s,t) = \left\{ x = (x_k) \in w : y = \left(\frac{1}{r_n} \sum_{k=0}^n s_{n-k} t_k x_k \right)_{n=0}^\infty \in X \right\}.$$

It is obvious that X(r, s, t) is a sequence space whenever X is a sequence space, and we call it the sequence space of generalized means. Further, if X is a BK space then $\overline{X} = X(r, s, t)$ is also a BK space with the norm given by

$$\|x\|_{\bar{X}} = \|y\|_{X} \quad (x \in \bar{X}). \tag{2.5}$$

Recently, Maji and Srivastava [36] have defined and studied the sequence space $X(r, s, t; B^{(m)})$ for $X \in \{\ell_{\infty}, c, c_0\}$ which is obtained by combining the generalized means and the *m*th order generalized difference operator $B^{(m)}(u, v)$. They characterized some compact operators on the spaces $X(r, s, t; B^{(m)})$ for $X \in \{\ell_{\infty}, c, c_0\}$ by using the Hausdorff measure of noncompactness. In this paper, we derive some identities or estimates for the operator norms and the Hausdorff measures of noncompactness of certain matrix operators on the sequence space $\ell_p(r, s, t; B^{(m)})$. By applying the Hausdorff measure of noncompactness, we obtain the necessary and sufficient conditions for such operators to be compact. Further, we study some geometric properties of this space.

The generalized difference matrix of order *m* denoted as $B^{(m)} = B^{(m)}(u, v) = (b_{nk}^{(m)}), u, v \neq 0$ (see [12]) is defined as

$$b_{nk}^{(m)} = \begin{cases} \binom{m}{n-k} u^{m-n+k} v^{n-k} & (\max\{0, n-m\} \le k \le n), \\ 0 & (0 \le k < \max\{0, n-m\}), \\ 0 & (k > n). \end{cases}$$

The sequence spaces $X(r, s, t; B^{(m)})$ for $X \in \{\ell_{\infty}, c, c_0\}$ are defined as follows:

$$X(r, s, t; B^{(m)}) = \{x = (x_k) \in w : ((\bar{A}(r, s, t) \cdot B^{(m)})x)_{n=0}^{\infty} \in X\}.$$

By using the matrix domain, we can write

$$X(r,s,t;B^{(m)}) = X_{\bar{A}(r,s,t;B^{(m)})} = \{x = (x_k) \in w : \bar{A}(r,s,t;B^{(m)}) x \in X\},\$$

where $\bar{A}(r, s, t; B^{(m)}) = \bar{A}(r, s, t) \cdot B^{(m)}$. The sequence $\bar{x} = (\bar{x}_n)$ is $\bar{A}(r, s, t) \cdot B^{(m)}$ -transform of $x = (x_n)$, *i.e.*

$$\bar{x}_n = \sum_{j=0}^n \left(\sum_{i=j}^n \binom{m}{i-j} \frac{s_{n-i}t_i}{r_n} u^{m+j-i} v^{i-j} \right) x_j \quad (n \in \mathbb{N}).$$

In this paper, we are interested in the study of $\ell_p(r, s, t; B^{(m)})$. We have the following lemma which is immediate by Theorem 4.5 in [35].

Lemma 2.1 If $a = (a_k) \in (\ell_p(r, s, t; B^{(m)}))^{\beta}$, then $\tilde{a} = (\tilde{a}_k) \in \ell_p^{\beta} (= \ell_q)$ and we have

$$\sum_{k=0}^{\infty} a_k x_k = \sum_{k=0}^{\infty} \tilde{a}_k \bar{x}_k \tag{2.6}$$

for all $x = (x_k) \in \overline{\ell}_p$ with $\overline{x} = (\overline{A}(r, s, t; B^{(m)}))x$, where

$$\begin{split} \tilde{a}_{k} &= r_{k} \Bigg[\frac{a_{k}}{s_{0} t_{k} u^{m}} + \sum_{i=k}^{k+1} (-1)^{i-k} \frac{D_{i-k}^{(s)}}{t_{i}} \sum_{j=k+1}^{\infty} \binom{m+j-i-1}{j-i} \frac{(-\nu)^{j-i}}{u^{j-i+m}} a_{j} \\ &+ \sum_{i=k+2}^{\infty} (-1)^{i-k} \frac{D_{i-k}^{(s)}}{t_{i}} \sum_{j=i}^{\infty} \binom{m+j-i-1}{j-i} \frac{(-\nu)^{j-i}}{u^{j-i+m}} a_{j} \Bigg]. \end{split}$$
(2.7)

The following results will be needed in our study.

Lemma 2.2 We have

$$||a||_{\bar{\ell}_n}^* = ||\tilde{a}||_{\ell_p}^*$$

for all $a = (a_k) \in \overline{\ell}_p^{\beta}$, where $\tilde{a} = (\tilde{a}_k)$ is the sequence defined by (2.7).

Proof Let $a = (a_k) \in \bar{\ell}_p^{\beta}$. Then it follows by Lemma 2.1 that $\tilde{a} = (\tilde{a}_k) \in \ell_p^{\beta}$ and the equality (2.6) holds for all sequences $x = (x_k) \in \bar{\ell}_p$ and $\bar{x} = (\bar{x}_k) \in \ell_p$ which are connected by the relation $\bar{x} = (\bar{A}(r, s, t; B^{(m)}))x$. Further, we see that $x \in S_{\bar{\ell}_p}$ if and only if $\bar{x} \in S_{\ell_p}$. Therefore, we derive from (1.2) and (2.6) that

$$\|a\|_{\tilde{\ell}_{p}}^{*} = \sup_{x \in S_{\tilde{\ell}_{p}}} \left| \sum_{k=0}^{\infty} a_{k} x_{k} \right| = \sup_{\bar{x} \in S_{\ell_{p}}} \left| \sum_{k=0}^{\infty} \tilde{a}_{k} \bar{x}_{k} \right| = \|\tilde{a}\|_{\ell_{p}}^{*}.$$

This concludes the proof.

Remark 2.3 By combining Lemmas 1.1 and 2.2, we have the following:

(a) If $a \in (\ell_1(r, s, t; B^{(m)}))^{\beta}$, then $||a||_{\tilde{\ell}_1}^* = \sup_k |\tilde{a}_k| < \infty$. (b) If $a \in (\ell_p(r, s, t; B^{(m)}))^{\beta}$, then $||a||_{\tilde{\ell}_p}^* = (\sum_{k=0}^{\infty} |\tilde{a}_k|^q)^{1/q} < \infty$, where q = p/(p-1) and 1 .

Throughout this paper, if $A = (a_{nk})$ is an infinite matrix, we define the *associated matrix* $\tilde{A} = (\tilde{a}_{nk})$ by

$$\tilde{a}_{nk} = r_k \left[\frac{a_{nk}}{s_0 t_k u^m} + \sum_{i=k}^{k+1} (-1)^{i-k} \frac{D_{i-k}^{(s)}}{t_i} \sum_{j=k+1}^{\infty} \binom{m+j-i-1}{j-i} \frac{(-\nu)^{j-i}}{u^{j-i+m}} a_{nj} + \sum_{i=k+2}^{\infty} (-1)^{i-k} \frac{D_{i-k}^{(s)}}{t_i} \sum_{j=i}^{\infty} \binom{m+j-i-1}{j-i} \frac{(-\nu)^{j-i}}{u^{j-i+m}} a_{nj} \right]$$
(2.8)

provided the series on the right converge for all $n, k \in \mathbb{N}$, which is the case whenever $A_n \in (\ell_p(r, s, t))^{\beta}$ for all $n \in \mathbb{N}$ [35], Theorem 4.5. Then we have the following.

Lemma 2.4 Let Y be a sequence space and $A = (a_{nk})$ be an infinite matrix. If $A \in (\ell_p(r,s,t;B^{(m)}), Y)$, then $\tilde{A} \in (\ell_p, Y)$ such that $Ax = \tilde{A}\bar{x}$ for all $x \in \ell_p(r,s,t)$ with $\bar{x} = (\tilde{A}(r,s,t))x$, where $\tilde{A} = (\tilde{a}_{nk})$ is the associated matrix defined by (2.8).

Proof Suppose that $A \in (\ell_p(r, s, t; B^{(m)}), Y)$ and let $x \in \ell_p(r, s, t; B^{(m)})$. Then $A_n \in (\ell_p(r, s, t; B^{(m)}))^{\beta}$ for all $n \in \mathbb{N}$. Thus, it follows by Lemma 2.1 that $\tilde{A}_n \in \ell_p^{\beta}$ for all $n \in \mathbb{N}$ and the equality $Ax = \tilde{A}\bar{x}$ holds which yields that $\tilde{A}\bar{x} \in Y$, where \bar{x} is the sequence of generalized means of x, *i.e.*, $\bar{x} = (\bar{A}(r, s, t; B^{(m)}))x$. Further, it is obvious by (2.4) and Remark 2.3 that every $\bar{x} \in \ell_p$ is the sequence of generalized means of some $x \in \ell_p(r, s, t; B^{(m)})$. Hence, we deduce that $\tilde{A} \in (\ell_p, Y)$. This completes the proof.

Finally, we conclude this section by the following results on operator norms.

Theorem 2.5 Let $A = (a_{nk})$ an infinite matrix and $\tilde{A} = (\tilde{a}_{nk})$ the associated matrix. If A is in any of the classes $(\ell_p(r, s, t; B^{(m)}), \ell_\infty), (\ell_p(r, s, t; B^{(m)}), c)$ or $(\ell_p(r, s, t; B^{(m)}), c_0)$, then

$$||L_A|| = ||A||_{(\ell_p(r,s,t;B^{(m)}),\ell_\infty)} = \sup_n ||\tilde{A}_n||_{\ell_p}^* < \infty$$

Proof This is immediate by combining Lemmas 1.1 and 2.2.

Theorem 2.6 *If* $A \in (\ell_p(r, s, t; B^{(m)}), \ell_1)$, *then*

$$\|A\|_{(\ell_n(r,s,t;B^{(m)}),\ell_1)} \le \|L_A\| \le 4 \cdot \|A\|_{(\ell_n(r,s,t;B^{(m)}),\ell_1)},$$

where

$$\|A\|_{(\ell_p(r,s,t;B^{(m)}),\ell_1)} = \sup_{N\in\mathcal{F}} \left\|\sum_{n\in N} \tilde{A}_n\right\|_{\ell_p}^* < \infty.$$

Proof This result follows from Lemmas 1.2 and 2.2.

Theorem 2.7 *If* $A \in (\ell_1(r, s, t; B^{(m)}), \ell_p)$, *then*

$$\|L_A\| = \|A\|_{(\ell_1(r,s,t;B^{(m)}),\ell_p)} = \sup_k \left(\sum_{n=0}^{\infty} |\tilde{a}_{nk}|^p\right)^{1/p} < \infty.$$

Proof The proof is elementary and left to the reader.

Remark 2.8 The characterizations of matrix classes considered in this paper can easily be obtained as in Corollaries 5.4 and 5.7 of [35]. Thus, we shall omit these characterizations and only deal with the operator norms and the Hausdorff measures of noncompactness of some matrix operators which are given by infinite matrices in such classes.

3 Main results

In this section, we derive some identities or estimates for the Hausdorff measures of noncompactness of certain matrix operators on the spaces of generalized means. Further, we apply our results to obtain the necessary and sufficient (or only sufficient) conditions for such operators to be compact.

We may begin with quoting the following lemma [28], Theorem 3.7.

Lemma 3.1 Let $X \supset \phi$ be a BK space. Then we have:

(a) If $A \in (X, \ell_{\infty})$, then

$$0 \le \|L_A\|_{\chi} \le \limsup_{n \to \infty} \|A_n\|_{\chi}^*$$

(b) If $A \in (X, c_0)$, then

$$\|L_A\|_{\chi} = \limsup_{n \to \infty} \|A_n\|_{\chi}^*$$

(c) If X has AK or $X = \ell_{\infty}$ and $A \in (X, c)$, then

$$\frac{1}{2} \cdot \limsup_{n \to \infty} \|A_n - \alpha\|_X^* \le \|L_A\|_{\chi} \le \limsup_{n \to \infty} \|A_n - \alpha\|_X^*,$$

where $\alpha = (\alpha_k)$ with $\alpha_k = \lim_{n \to \infty} a_{nk}$ for all $k \in \mathbb{N}$.

Now, let $A = (a_{nk})$ be an infinite matrix and $\tilde{A} = (\tilde{a}_{nk})$ the associated matrix defined by (2.8). Then, by combining Lemmas 2.2, 2.4 and 3.1, we have the following result.

Theorem 3.2 We have:

(a) If $A \in (\ell_p(r, s, t; B^{(m)}), \ell_\infty)$, then

$$0 \le \|L_A\|_{\chi} \le \limsup_{n \to \infty} \|\tilde{A}_n\|_{\ell_p}^* \tag{3.1}$$

and

$$L_A \text{ is compact} \quad \text{if } \lim_{n \to \infty} \|\hat{A}_n\|_{\ell_p}^* = 0. \tag{3.2}$$

(b) If
$$A \in (\ell_p(r, s, t; B^{(m)}), c_0)$$
, then

$$\|L_A\|_{\chi} = \limsup_{n \to \infty} \|\tilde{A}_n\|_{\ell_p}^* \tag{3.3}$$

and

$$L_A \text{ is compact} \quad \text{if and only if} \quad \lim_{n \to \infty} \|\tilde{A}_n\|_{\ell_p}^* = 0. \tag{3.4}$$

(c) If $A \in (\ell_p(r, s, t; B^{(m)}), c)$, then

$$\frac{1}{2} \cdot \limsup_{n \to \infty} \|\tilde{A}_n - \tilde{\alpha}\|_{\ell_p}^* \le \|L_A\|_{\chi} \le \limsup_{n \to \infty} \|\tilde{A}_n - \tilde{\alpha}\|_{\ell_p}^*$$
(3.5)

and

$$L_A \text{ is compact} \quad \text{if and only if} \quad \lim_{n \to \infty} \|\tilde{A}_n - \tilde{\alpha}\|_{\ell_p}^* = 0, \tag{3.6}$$

where $\tilde{\alpha} = (\tilde{\alpha}_k)$ with $\tilde{\alpha}_k = \lim_{n \to \infty} \tilde{a}_{nk}$ for all $k \in \mathbb{N}$.

Proof Note that parts (a) and (b) are proved in [37]. Further it is obvious that (3.2), (3.4) and (3.6) are, respectively, obtained from (3.1), (3.3), and (3.5) by using (1.2). Thus, we have to prove (3.1), (3.3) and (3.5).

Since $\ell_p(r, s, t; B^{(m)})$ is a *BK* space, we deduce by means of Lemma 2.2 that (3.1) and (3.3) are immediate by parts (a) and (b) of Lemma 3.1, respectively.

To prove (3.5), we have $A \in (\ell_p(r, s, t; B^{(m)}), c)$ and hence $\tilde{A} \in (X, c)$ by Lemma 2.4. Therefore, it follows by part (c) of Lemma 3.1 that

$$\frac{1}{2} \cdot \limsup_{n \to \infty} \|\tilde{A}_n - \tilde{\alpha}\|_X^* \le \|L_{\tilde{A}}\|_X \le \limsup_{n \to \infty} \|\tilde{A}_n - \tilde{\alpha}\|_X^*,$$
(3.7)

where $\tilde{\alpha} = (\tilde{\alpha}_k)$ and $\tilde{\alpha}_k = \lim_{n \to \infty} \tilde{a}_{nk}$ for all $k \in \mathbb{N}$.

Now, let us write $S = S_X$ and $\overline{S} = S_{\ell_p(r,s,t;B^{(m)})}$, for short. Then we obtain by (1.3) and Lemma 1.1

$$\|L_A\|_{\chi} = \chi \left(L_A(\bar{S}) \right) = \chi (A\bar{S}) \tag{3.8}$$

and

$$\|L_{\tilde{A}}\|_{\chi} = \chi \left(L_{\tilde{A}}(S) \right) = \chi (\tilde{A}S).$$
(3.9)

Further, we see that $x \in \overline{S}$ if and only if $\overline{x} \in S$, and since $Ax = \overline{A}\overline{x}$ by Lemma 2.4, we deduce that $A\overline{S} = \overline{A}S$. This leads us with (3.8) and (3.9) to the consequence that $\|L_A\|_{\chi} = \|L_{\overline{A}}\|_{\chi}$. Hence, we get (3.5) from (3.7). This completes the proof.

It is worth mentioning that the condition in (3.2) is only a sufficient condition for the operator L_A to be compact, where $A \in (\ell_p(r, s, t; B^{(m)}), \ell_\infty)$ and X is a BK space with AK or $X = \ell_\infty$. More precisely, the following example will show that it is possible for L_A to be compact while $\lim_{n\to\infty} \|\tilde{A}_n\|_X^* \neq 0$. Hence, in general, we have just 'if' in (3.2) of Theorem 3.2(a).

Example 3.3 Let us define the matrix $A = (a_{nk})$ by $a_{n0} = s_0 t_0/r_0$ and $a_{nk} = 0$ for $k \ge 1$ $(n \in \mathbb{N})$. Let $B^{(m)} = I$, the identity matrix. Then we have for every $x = (x_k) \in \ell_p(r, s, t; B^{(m)})$, $Ax = (s_0 t_0 x_0/r_0)e$ and hence $A \in (\ell_p(r, s, t; B^{(m)}), \ell_\infty)$. Further, it is obvious that L_A is of finite rank and so L_A is compact. On the other hand, by using (2.8), it can easily be seen that $\tilde{A}_n = e^{(0)}$ for all $n \in \mathbb{N}$. Thus, we obtain by Lemma 1.1 that $\|\tilde{A}_n\|_X^* = 1$ for all $n \in \mathbb{N}$, which implies that $\lim_{n\to\infty} \|\tilde{A}_n\|_X^* = 1$.

Moreover, as an immediate consequence of Theorem 3.2, we have the following corollary.

Corollary 3.4 If either $A \in (\ell_{\infty}(r, s, t; B^{(m)}), c_0)$ or $A \in (\ell_{\infty}(r, s, t; B^{(m)}), c)$, then the operator L_A is compact.

Proof Let $A \in (\tilde{\ell}_{\infty}, c_0)$. Then we have by Lemma 2.4 that $\tilde{A} \in (\ell_{\infty}, c_0)$ which implies that $\lim_{n\to\infty} (\sum_{k=0}^{\infty} |\tilde{a}_{nk}|) = 0$, that is, $\lim_{n\to\infty} \|\tilde{A}_n\|_{\ell_{\infty}}^* = 0$ by Lemma 1.1. This leads us with Theorem 3.2(b) to the consequence that L_A is compact. Similarly, if $A \in (\ell_{\infty}(r, s, t; B^{(m)}), c)$ then $\tilde{A} \in (\ell_{\infty}, c)$ and hence $\lim_{n\to\infty} (\sum_{k=0}^{\infty} |\tilde{a}_{nk} - \tilde{\alpha}_k|) = 0$, which can be written as $\lim_{n\to\infty} \|\tilde{A}_n - \tilde{\alpha}\|_{\ell_{\infty}}^* = 0$, where $\tilde{\alpha} = (\tilde{\alpha}_k)$ and $\tilde{\alpha}_k = \lim_{n\to\infty} \tilde{a}_{nk}$ for all $k \in \mathbb{N}$. Therefore, we deduce from Theorem 3.2(c) that L_A is compact.

Throughout, let \mathcal{F}_r ($r \in \mathbb{N}$) be the subcollection of \mathcal{F} consisting of all non-empty and finite subsets of \mathbb{N} with elements that are greater than r, that is,

$$\mathcal{F}_r = \{ N \in \mathcal{F} : n > r \text{ for all } n \in N \} \quad (r \in \mathbb{N}).$$

Then we have the following.

Lemma 3.5 (Theorem 3.11 in [28]) Let $X \supset \phi$ be a BK space. If $A \in (X, \ell_1)$, then

$$\lim_{r \to \infty} \left(\sup_{N \in \mathcal{F}_r} \left\| \sum_{n \in N} A_n \right\|_X^* \right) \le \|L_A\|_{\chi} \le 4 \cdot \lim_{r \to \infty} \left(\sup_{N \in \mathcal{F}_r} \left\| \sum_{n \in N} A_n \right\|_X^* \right).$$

Theorem 3.6 *If* $A \in (\ell_p(r, s, t; B^{(m)}), \ell_1)$, *then*

$$\lim_{r \to \infty} \|A\|_{(\ell_p(r,s,t;B^{(m)}),\ell_1)}^{(r)} \le \|L_A\|_{\chi} \le 4 \cdot \lim_{r \to \infty} \|A\|_{(\ell_p(r,s,t;B^{(m)}),\ell_1)}^{(r)}$$
(3.10)

and

$$L_A \text{ is compact} \quad \text{if and only if} \quad \lim_{r \to \infty} \|A\|_{(\ell_p(r,s,t;B^{(m)}),\ell_1)}^{(r)} = 0, \tag{3.11}$$

where

$$\|A\|_{(\ell_p(r,s,t;B^{(m)}),\ell_1)}^{(r)} = \sup_{N \in \mathcal{F}_r} \left\|\sum_{n \in \mathcal{N}} \tilde{A}_n\right\|_X^* \quad (r \in \mathbb{N})$$

Proof It is obvious that (3.10) is obtained by combining Lemmas 2.2 and 3.5. Also, by using (1.2), we get (3.11) from (3.10). □

$$\lim_{r \to \infty} \|A\|_{(\ell_p(r,s,t;B^{(m)}),\ell_1)}^{(r)} \le \|L_A\|_{\chi} \le 4 \cdot \lim_{r \to \infty} \|A\|_{(\ell_p(r,s,t;B^{(m)}),\ell_1)}^{(r)}$$

and

$$L_A \text{ is compact} \quad \text{if and only if} \quad \lim_{r \to \infty} \|A\|_{(\ell_p(r,s,t;B^{(m)}),\ell_1)}^{(r)} = 0,$$

where

$$\|A\|_{(\ell_p(r,s,t;B^{(m)}),\ell_1)}^{(r)} = \sup_{N \in \mathcal{F}_r} \left(\sum_{k=0}^{\infty} \left| \sum_{n \in N} \tilde{a}_{nk} \right|^q \right)^{1/q} \quad (r \in \mathbb{N}).$$

Now, we prove the following result.

Theorem 3.8 *Let* $1 \le p < \infty$. *If* $A \in (\ell_1(r, s, t; B^{(m)}), \ell_p)$, *then*

$$\|L_A\|_{\chi} = \lim_{r \to \infty} \left(\sup_k \left(\sum_{n=r}^{\infty} |\tilde{a}_{nk}|^p \right)^{1/p} \right)$$
(3.12)

and

$$L_A \text{ is compact} \quad \text{if and only if} \quad \lim_{r \to \infty} \left(\sup_k \left(\sum_{n=r}^{\infty} |\tilde{a}_{nk}|^p \right) \right) = 0. \tag{3.13}$$

Proof We write $\bar{S} = S_{\bar{\ell}_1}$. Then we see by Lemma 1.1 that $L_A(\bar{S}) = A\bar{S} \in \mathcal{M}_{\ell_p}$. Thus, it follows from (1.3) and Lemma 1.3 that

$$\|L_A\|_{\chi} = \chi(A\bar{S}) = \lim_{r \to \infty} \left(\sup_{x \in \bar{S}} \| (I - P_r)(Ax) \|_{\ell_p} \right),$$
(3.14)

where $P_r : \ell_p \to \ell_p$ ($r \in \mathbb{N}$) is the operator defined by $P_r(x) = (x_0, x_1, \dots, x_r, 0, 0, \dots)$ for all $x = (x_k) \in \ell_p$ and *I* is the identity operator on ℓ_p .

On the other hand, let $x \in \ell_1(r, s, t; B^{(m)})$ be given. Then $\bar{x} \in \ell_1$ and since $A \in (\ell_1(r, s, t; B^{(m)}), \ell_p)$, we obtain from Lemma 2.4 that $\tilde{A} \in (\ell_1, \ell_p)$ and $Ax = \tilde{A}\bar{x}$. Thus, we have for every $r \in \mathbb{N}$,

$$\begin{aligned} \left| (I - P_r)(Ax) \right\|_{\ell_p} &= \left\| (I - P_r)(\tilde{A}\bar{x}) \right\|_{\ell_p} \\ &= \left(\sum_{n=r+1}^{\infty} \left| \tilde{A}_n(\bar{x}) \right|^p \right)^{1/p} \\ &= \left(\sum_{n=r+1}^{\infty} \left| \sum_{k=0}^{\infty} \tilde{a}_{nk} \bar{x}_k \right|^p \right)^{1/p} \\ &\leq \sum_{k=0}^{\infty} \left(\sum_{n=r+1}^{\infty} \left| \tilde{a}_{nk} \bar{x}_k \right|^p \right)^{1/p} \end{aligned}$$

$$\leq \|\bar{x}\|_{\ell_1} \left(\sup_k \left(\sum_{n=r+1}^{\infty} |\tilde{a}_{nk}|^p \right)^{1/p} \right)$$
$$= \|x\|_{\ell_1(r,s,t)} \left(\sup_k \left(\sum_{n=r+1}^{\infty} |\tilde{a}_{nk}|^p \right)^{1/p} \right).$$

This yields

$$\sup_{x\in \widehat{S}} \left\| (I-P_r)(Ax) \right\|_{\ell_p} \leq \sup_k \left(\sum_{n=r+1}^{\infty} |\widetilde{a}_{nk}|^p \right)^{1/p} \quad (r\in \mathbb{N}).$$

Therefore, we deduce from (3.14) that

$$\|L_A\|_{\chi} \leq \lim_{r \to \infty} \left(\sup_k \left(\sum_{n=r+1}^{\infty} |\tilde{a}_{nk}|^p \right)^{1/p} \right).$$
(3.15)

To prove the converse inequality, let $b^{(k)} \in \ell_1(r, s, t; B^{(m)})$ be such that $(\bar{A}(r, s, t; B^{(m)}))b^{(k)} = e^{(k)}$ ($k \in \mathbb{N}$), that is, $e^{(k)}$ is the sequence of generalized means of $b^{(k)}$ for each $k \in \mathbb{N}$ (see Corollary 3.5 in [35]). Then we have by Lemma 2.4 that $Ab^{(k)} = \tilde{A}e^{(k)} = (\tilde{a}_{nk})_{n=0}^{\infty}$ for every $k \in \mathbb{N}$.

Now, let $B = \{b^{(k)} : k \in \mathbb{N}\}$. Then $B \subset \overline{S}$ and hence $AB \subset A\overline{S}$, which implies that $\chi(AB) \leq \chi(A\overline{S}) = \|L_A\|_{\chi}$.

Further, it follows by applying Lemma 1.3 that

$$\chi(AB) = \lim_{r \to \infty} \left(\sup_{k} \left(\sum_{n=r+1}^{\infty} \left| A_n(b^{(k)}) \right|^p \right)^{1/p} \right)$$
$$= \lim_{r \to \infty} \left(\sup_{k} \left(\sum_{n=r+1}^{\infty} \left| \tilde{a}_{nk} \right|^p \right)^{1/p} \right).$$

Thus, we obtain

$$\lim_{r \to \infty} \left(\sup_{k} \left(\sum_{n=r+1}^{\infty} |\tilde{a}_{nk}|^p \right)^{1/p} \right) \le \|L_A\|_{\chi}.$$
(3.16)

Hence, we get (3.12) by combining (3.15) and (3.16). This completes the proof, since (3.13) is immediate by (1.2) and (3.12). \Box

Finally, we end this section with the following example, which shows that the limit in (3.12) may not be zero, that is, there exist matrix operators in the class $\mathcal{B}(\bar{\ell}_1, \ell_p)$ which are not compact, where $1 \le p < \infty$.

Example 3.9 Let $A = (a_{nk})$ be the infinite matrix defined by $A = \overline{A}(r, s, t; B^{(m)})$. Let $B^{(m)} = I$, the identity matrix. Since $\ell_1(r, s, t; B^{(m)})$ is the matrix domain of A in ℓ_1 , we have $A \in (\ell_1(r, s, t; B^{(m)}), \ell_1)$ and hence $A \in (\overline{\ell}_1, \ell_p)$ for $1 \le p < \infty$. Further, it is trivial to see that the associated matrix \widetilde{A} is the identity matrix, that is, $\widetilde{a}_{nn} = 1$ and $\widetilde{a}_{nk} = 0$ for $k \ne n$ $(n \in \mathbb{N})$.

Now, let $r \in \mathbb{N}$ be given. Then we have, for every $k \in \mathbb{N}$,

$$\sum_{n=r}^{\infty} \left| \tilde{a}_{nk} \right|^p = \begin{cases} 1 & (k \ge r), \\ 0 & (k < r). \end{cases}$$

This implies that

$$\sup_{k} \left(\sum_{n=r}^{\infty} |\tilde{a}_{nk}|^{p} \right)^{1/p} = 1 \quad (r \in \mathbb{N})$$

which leads us with (3.12) of Theorem 3.8 to the conclusion that $||L_A||_{\chi} = 1$ and hence L_A is not compact.

4 Geometric properties

Recently there has been a lot of interest in investigating geometric properties of sequence spaces besides topological and some other usual properties. In the literature, there are many papers concerning geometric properties of various Banach sequence spaces.

A Banach space X is said to be a *Köthe sequence space* (see [15, 17], and [21]) if X is a subspace of w such that

- (i) if $x \in w$, $y \in X$, and $|x(i)| \le |y(i)|$ for all $i \in \mathbb{N}$, then $x \in X$ and $||x|| \le ||y||$;
- (ii) there exists an element $x \in X$ such that x(i) > 0 for all $i \in \mathbb{N}$.

A Köthe sequence space *X* is said to have the *Fatou property* if for any real sequence *x* and any $\{x_n\}$ in *X* such that $x_n \to x$ coordinatewise and $\sup_n ||x_n|| < \infty$, we have $x \in X$ and $||x_n|| \to ||x||$.

A Banach space *X* is said to have the *Banach-Saks property* if every bounded sequence $\{x_n\}$ in *X* admits a subsequence $\{z_n\}$ such that the sequence $\{t_k(z)\}$ is convergent in *X* with respect to the norm, where

$$t_k(z) = \frac{1}{k}(z_1 + z_2 + \dots + z_k) \quad \forall k \in \mathbb{N}.$$

A Banach space X is said to have the *weak Banach-Saks property* whenever given any weakly null sequence $\{x_n\}$ in X there exists its subsequence $\{z_n\}$ such that the sequence $\{t_k(z)\}$ converges to zero strongly.

Given any $p \in (1, \infty)$, we say that a Banach space $(X, \|\cdot\|)$ has the *Banach-Saks property of type* p if there exists a constant c > 0 such that every weakly null sequence $\{x_k\}$ has a subsequence $\{x_{k_\ell}\}$ such that (see [22])

$$\left\|\sum_{\ell=1}^n x_{k_\ell}\right\| \le cn^{\frac{1}{p}} \quad \forall n \in \mathbb{N}.$$

The Banach-Saks property of type $p \in (1, \infty)$ and weak Banach-Saks property for Cesàro sequence spaces have been considered in [15].

We say that a Banach space *X* has the *weak fixed point property* if every nonexpansive self-mapping defined on a non-empty weakly compact convex subset of *X* has a fixed point.

In [18], García-Falset introduced the following coefficient for a Banach space $(X, \|\cdot\|)$:

$$R(X) = \sup\left\{\liminf_{n \to \infty} \|x_n - x\| : x \in B(X), \{x_n\} \subset B(X) \text{ and } x_n \to 0 \text{ weakly}\right\}$$

and he proved (see [18, 19]) that a Banach space *X* with R(X) < 2 has the weak fixed point property.

A Köthe sequence space *X* is said to be *order continuous* if for any sequence $\{x_n\}$ and any *x* in X_+ (the positive cone in *X*) such that $x_n(i) \le x(i)$ as $n \to \infty$ for all $i, n \in \mathbb{N}$ and $x_n(i) \to 0$ for any $i \in \mathbb{N}$, we have $||x_n|| \to 0$ as $n \to \infty$.

Clarkson *modulus of convexity* of a normed space $(X, \|\cdot\|)$ is defined (see work by Clarkson [14] and Day [16]) by the formula

$$\delta_X(\varepsilon) = \inf\left\{1 - \frac{\|x + y\|}{2}; x, y \in S(X), \|x - y\| = \varepsilon\right\}$$

for any $\varepsilon \in [0, 2]$. The inequality $\delta_X(\varepsilon) > 0$ for all $\varepsilon \in (0, 2]$ characterizes the uniform convexity of *X* and the equality $\delta_X(2) = 1$ characterizes strict convexity (= rotundity) of *X*.

The Gurariĭ modulus of convexity of a normed space X is defined (see [20]) by

$$\beta_X(\varepsilon) = \inf \left\{ 1 - \inf_{\alpha \in [0,1]} \left\| \alpha x + (1-\alpha)y \right\|; x, y \in \delta(X), \|x-y\| = \varepsilon \right\}$$

for any $\varepsilon \in [0, 2]$. It is obvious that $\delta_X(\varepsilon) \le \beta_X(\varepsilon)$ for any Banach space *X* and any $\varepsilon \in [0, 2]$. It is also known that $\beta_X(\varepsilon) \le 2\delta_X(\varepsilon)$ for any $\varepsilon \in [0, 2]$ and that *X* is rotund if and only if $\beta_X(\varepsilon) = 2$ and *X* is uniformly convex if and only if $\beta_X(\varepsilon) > 0$ for any $\varepsilon \in [0, 2]$.

Theorem 4.1 The Banach-Saks type of the space $\ell_p(r, s, t; B^{(m)})$ is equal to p.

Proof Let (ε_n) be a sequence of positive numbers for which $\sum_{n=1}^{\infty} \varepsilon_n \leq \frac{1}{2}$. Let $\{x_n\}$ be a weakly null sequence in $\ell_p(r, s, t; B^{(m)})$. Set $t_0 = x_0 = 0$ and $t_1 = x_{n_1} = x_1$. Then there exists $r_1 \in \mathbb{N}$ such that

$$\left\|\sum_{i=r_1+1}^{\infty}t_1(i)e^{(i)}\right\|_{\ell_p(r,s,t;B^{(m)})}<\varepsilon_1.$$

Since the fact that $\{x_n\}$ is a weakly null sequence implies that $x_n \to 0$, coordinatewise, there is an $n_2 \in \mathbb{N}$ such that

$$\left\|\sum_{i=0}^{r_1} x_n(i) e^{(i)}\right\|_{\ell_p(r,s,t;B^{(m)})} < \varepsilon_1$$

for all $n \ge n_2$. Set $t_2 = x_{n_2}$. Then there exists an $r_2 > r_1$ such that

$$\left\|\sum_{i=r_2+1}^{\infty}t_2(i)e^{(i)}\right\|_{\ell_p(r,s,t;B^{(m)})}<\varepsilon_2.$$

By using the fact that $x_n \rightarrow 0$ coordinatewise, there exists an $n_3 > n_2$ such that

$$\left\|\sum_{i=0}^{r_2} x_n(i)e^{(i)}\right\|_{\ell_p(r,s,t;B^{(m)})} < \varepsilon_2$$

for all $n \ge n_3$. Continuing this process, we can find by induction two increasing subsequences (r_i) and (n_i) such that

$$\left\|\sum_{i=0}^{r_j} x_n(i) e^{(i)}\right\|_{\ell_p(r,s,t;B^{(m)})} < \varepsilon_j$$

for all $n \ge n_{j+1}$ and

$$\left\|\sum_{i=r_j+1}^{\infty}t_j(i)e^{(i)}\right\|_{\ell_p(r,s,t;B^{(m)})}<\varepsilon_j,$$

where $t_j = x_{n_j}$. Hence,

$$\begin{split} \left\|\sum_{j=0}^{n} t_{j}\right\|_{\ell_{p}(r,s,t;B^{(m)})} &= \left\|\sum_{j=0}^{n} \left(\sum_{i=0}^{r_{j-1}} t_{j}(i)e^{(i)} + \sum_{i=r_{j-1}+1}^{r_{j}} t_{j}(i)e^{(i)} + \sum_{i=r_{j}+1}^{\infty} t_{j}(i)e^{(i)}\right)\right\|_{\ell_{p}(r,s,t;B^{(m)})} \\ &\leq \left\|\sum_{j=0}^{n} \left(\sum_{i=r_{j-1}+1}^{r_{j}} t_{j}(i)e^{(i)}\right)\right\|_{\ell_{p}(r,s,t;B^{(m)})} + \left\|\sum_{j=0}^{n} \left(\sum_{i=0}^{r_{j-1}} t_{j}(i)e^{(i)}\right)\right\|_{\ell_{p}(u,v)} \\ &+ \left\|\sum_{j=0}^{n} \left(\sum_{i=r_{j}+1}^{\infty} t_{j}(i)e^{(i)}\right)\right\|_{\ell_{p}(r,s,t;B^{(m)})} + 2\sum_{j=0}^{n} \varepsilon_{j} \end{split}$$

and

$$\begin{split} \left\| \sum_{j=0}^{n} \left(\sum_{i=r_{j-1}+1}^{r_{j}} t_{j}(i) e^{(i)} \right) \right\|_{\ell_{p}(r,s,t;B^{(m)})}^{p} &= \sum_{j=0}^{n} \sum_{i=r_{j-1}+1}^{r_{j}} \left| \sum_{k=0}^{i} u_{i} v_{k} t_{j}(k) \right|^{p} \\ &\leq \sum_{j=0}^{n} \sum_{i=0}^{\infty} \left| \sum_{k=0}^{i} u_{i} v_{k} t_{j}(k) \right|^{p} \\ &\leq (n+1). \end{split}$$

Hence we obtain

$$\left\|\sum_{j=0}^{n} \left(\sum_{i=r_{j-1}+1}^{r_{j}} t_{j}(i) e^{(i)}\right)\right\| \leq \left(\sum_{j=0}^{n} 1\right)^{\frac{1}{p}} = (n+1)^{\frac{1}{p}}.$$

By using the inequality $1 \le (n+1)^{\frac{1}{p}}$ for all $n \in \mathbb{N}$ and $1 \le p < \infty$, we have

$$\left\|\sum_{j=0}^{n} t_{j}\right\|_{\ell_{p}(r,s,t;B^{(m)})} \leq (n+1)^{\frac{1}{p}} + 1 \leq 2(n+1)^{\frac{1}{p}}.$$

Therefore, the space $\ell_p(r, s, t; B^{(m)})$ has the Banach-Saks type p, which completes the proof of the theorem.

Theorem 4.2 The Gurarit of modulus of convexity for the normed space $\ell_p(r, s, t; B^{(m)})$ satisfies the inequality

$$\beta_{\ell_p(r,s,t;B^{(m)})}(\varepsilon) \leq 1 - \left(1 - \left(\frac{\varepsilon}{2}\right)^p\right)^{\frac{1}{p}}$$

for any $0 \le \varepsilon \le 2$ *.*

Proof Let $x \in \ell_p(r, s, t; B^{(m)})$. By using (1.1), we have

$$\|x\|_{\ell_p(r,s,t;B^{(m)})} = \|(\bar{A}(r,s,t)\cdot B^{(m)})x\|_{\ell_p} = \left(\sum_n |((\bar{A}(r,s,t)\cdot B^{(m)})x)_n|^p\right)^{\frac{1}{p}}.$$

Let $0 \le \varepsilon \le 2$ and using (1.2), let us consider the following sequences:

$$x = (x_n) = \left(H\left(\left(1 - \left(\frac{\varepsilon}{2}\right)^p\right)^{\frac{1}{p}}\right), H\left(\frac{\varepsilon}{2}\right), 0, 0, \ldots\right),$$
$$t = (t_n) = \left(H\left(\left(1 - \left(\frac{\varepsilon}{2}\right)^p\right)^{\frac{1}{p}}\right), H\left(-\frac{\varepsilon}{2}\right), 0, 0, \ldots\right),$$

where $H = (\bar{A}(r, s, t) \cdot B^{(m)})_{nk}^{-1}$. Since $y_n = ((\bar{A}(r, s, t) \cdot B^{(m)})x)_n$ and $z_n = ((\bar{A}(r, s, t) \cdot B^{(m)})t)_n$, we have

$$y = (y_n) = \left(\left(1 - \left(\frac{\varepsilon}{2}\right)^p \right)^{\frac{1}{p}}, \left(\frac{\varepsilon}{2}\right), 0, 0, \ldots \right),$$
$$z = (z_n) = \left(\left(1 - \left(\frac{\varepsilon}{2}\right)^p \right)^{\frac{1}{p}}, \left(-\frac{\varepsilon}{2}\right), 0, 0, \ldots \right).$$

By using the sequences given above, we obtain the following equalities:

$$\begin{aligned} \|x\|_{\ell_p(r,s,t;B^{(m)})}^p &= \left\| \left(\bar{A}(r,s,t) \cdot B^{(m)} \right) x \right\|_{\ell_p}^p = \left| \left(1 - \left(\frac{\varepsilon}{2} \right)^p \right)^{\frac{1}{p}} \right|^p + \left| \frac{\varepsilon}{2} \right|^p \\ &= 1 - \left(\frac{\varepsilon}{2} \right)^p + \left(\frac{\varepsilon}{2} \right)^p \\ &= 1, \end{aligned}$$

 $\left\|t\right\|_{\ell_p(r,s,t;B^{(m)})}^p = \left\|\left(\bar{A}(r,s,t)\cdot B^{(m)}\right)t\right\|_{\ell_p}^p = \left|\left(1-\left(\frac{\varepsilon}{2}\right)^p\right)^{\overline{p}}\right|^p + \left|-\frac{\varepsilon}{2}\right|^p$

$$\begin{split} &= 1 - \left(\frac{\varepsilon}{2}\right)^p + \left(\frac{\varepsilon}{2}\right)^p \\ &= 1, \\ &\|x - t\|_{\ell_p(r,s,t;B^{(m)})} = \left\| \left(\bar{A}(r,s,t) \cdot B^{(m)}\right)x - \left(\bar{A}(r,s,t) \cdot B^{(m)}\right)t \right\|_{\ell_p} \\ &= \left(\left| \left(1 - \left(\frac{\varepsilon}{2}\right)^p\right)^{\frac{1}{p}} - \left(1 - \left(\frac{\varepsilon}{2}\right)^p\right)^{\frac{1}{p}} \right|^p + \left|\frac{\varepsilon}{2} - \left(-\frac{\varepsilon}{2}\right)\right|^p \right)^{\frac{1}{p}} \\ &= \varepsilon. \end{split}$$

To complete the estimate of the Gurarii on the modulus of convexity, it remains to calculate the infimum of $\|\alpha x + (1-\alpha)t\|_{\ell_n(r,s,t;B^{(m)})}^p$ for $0 \le \alpha \le 1$. We have

$$\begin{split} &\inf_{0\leq \alpha\leq 1} \left\| \alpha x + (1-\alpha)t \right\|_{\ell_p(r,s,t;B^{(m)})} \\ &= \inf_{0\leq \alpha\leq 1} \left\| \alpha \left(\bar{A}(r,s,t)\cdot B^{(m)} \right) x + (1-\alpha) \left(\bar{A}(r,s,t)\cdot B^{(m)} \right) t \right\|_{\ell_p} \\ &= \inf_{0\leq \alpha\leq 1} \left[\left| \alpha \left(1 - \left(\frac{\varepsilon}{2}\right)^p \right)^{\frac{1}{p}} + (1-\alpha) \left(1 - \left(\frac{\varepsilon}{2}\right)^p \right)^{\frac{1}{p}} \right|^p \\ &+ \left| \alpha \left(\frac{\varepsilon}{2}\right) + (1-\alpha) \left(-\frac{\varepsilon}{2} \right) \right|^p \right]^{\frac{1}{p}} \\ &= \inf_{0\leq \alpha\leq 1} \left[1 - \left(\frac{\varepsilon}{2}\right)^p + |2\alpha - 1|^p \left(\frac{\varepsilon}{2}\right)^p \right]^{\frac{1}{p}} \\ &= \left(1 - \left(\frac{\varepsilon}{2}\right)^p \right)^{\frac{1}{p}}. \end{split}$$

Consequently, we get for $p \ge 1$ the inequality

$$\beta_{l_p(u,v)}(\varepsilon) \leq 1 - \left(1 - \left(\frac{\varepsilon}{2}\right)^p\right)^{\frac{1}{p}},$$

which is the desired result.

5 Conclusion

Recently the sequence space $X(r, s, t; B^{(m)})$ for $X \in \{\ell_{\infty}, c, c_0\}$ has been studied by Maji and Srivastava [36] which is obtained by combining the generalized means and the *m*th order generalized difference operator $B^{(m)}(u, v)$. They characterized some compact operators on the spaces $X(r, s, t; B^{(m)})$ for $X \in \{\ell_{\infty}, c, c_0\}$ by using the Hausdorff measure of noncompactness. In this paper, we have derived some identities or estimates for the operator norms and the Hausdorff measures of noncompactness of certain matrix operators on the sequence space $\ell_p(r, s, t; B^{(m)})$. Further, by applying the Hausdorff measure of noncompactness, we obtained the necessary and sufficient conditions for such operators to be compact. In the last section, we have studied some geometric properties of this space, *e.g.* the property Banach-Saks type and Gurariĭ modulus of convexity.

The authors declare that they have no competing interests.

Authors' contributions

All authors of the manuscript have read and agreed to its content and are accountable for all aspects of the accuracy and integrity of the manuscript.

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