

RESEARCH

Open Access

A new system of generalized quasi-variational-like inclusions with noncompact valued mappings

Han-Wen Cao

Correspondence: chwhappy@163.com

Department of Science, Nanchang Institute of Technology, Nanchang 330099, P. R. China

Abstract

In this article, we introduce and study a new system of generalized quasi-variational-like inclusions with noncompact valued mappings. By using the η -proximal mapping technique, we prove the existence of solutions and the convergence of some new N -step iterative algorithms for this system of generalized quasi-variational-like inclusions. Our results extend and improve some known results in the literature.

Mathematics Subject Classification 2000: 49H09; 49J40; 49H10.

Keywords: system of generalized quasi-variational-like inclusions, η -proximal mapping, monotone operator, iterative algorithm

1 Introduction

Let H be a real Hilbert space, and $CB(H)$ be the family of all nonempty bounded closed subsets of H . We will consider the following problem:

For $i, j = 1, 2, \dots, N$, let $A_{ij}: H \rightarrow CB(H)$, $\eta_i: H \times H \rightarrow H$, $g_i: H \rightarrow H$, $T_i: \underbrace{H \times H \times \dots \times H}_N \rightarrow H$ be nonlinear mappings, and let $\phi_i: H \rightarrow R \cup \{+\infty\}$ be real function.

$$\begin{aligned} & \text{Find } x_1^*, x_2^*, \dots, x_N^* \in H, \\ & u_{11}^* \in A_{11}x_1^*, u_{12}^* \in A_{12}x_2^*, \dots, u_{1N}^* \in A_{1N}x_N^*, \dots, u_{N1}^* \in A_{N1}x_1^*, u_{N2}^* \in A_{N2}x_2^*, \dots, u_{NN}^* \in A_{NN}x_N^* \text{ such that} \\ & \langle T_i(u_{i1}^*, u_{i2}^*, \dots, u_{iN}^*), \eta_i(x, g_i(x_i^*)) \rangle \geq \phi_i(g_i(x_i^*)) - \phi_i(x), \quad \forall x \in H, \quad i = 1, 2, \dots, N. \end{aligned} \quad (1.1)$$

Problem (1.1) is called the set-valued nonlinear generalized quasi-variational-like inclusions.

Various special cases of the problem (1.1) had been studied by many authors before. Here, we mention some of them as follows:

(1) If $N = 2$, $A_{11} = A_{12} = A$, $A_{21} = A_{22} = B$, $T_1 = T$, $T_1(A(\cdot), B(\cdot)): H \rightarrow CB(H)$, then the problem (1.1) reduces to find $x^* \in H$, $u^* \in Ax^*$, $v^* \in Bx^*$ such that

$$\langle T(u^*, v^*), \eta(x, g(x^*)) \rangle \geq \phi(g(x^*)) - \phi(x), \quad \forall x \in H. \quad (1.2)$$

Problem (1.2) was introduced and studied by Ding [1] in 2001.

(2) If $N = 2$, $A_{11} = A_{12} = A_{21} = A_{22} = I$, $g_i = I$ (identical operator), $\eta(x, y) = x - y$, $\phi_1 = \phi_2 = \phi$, $T: H \times H \rightarrow H$, $T_1(A_{11}x, A_{12}y) = \rho_1 T(A_{12}y, A_{11}x) + A_{11}x - A_{12}y$, $T_2(A_{21}x, A_{22}y) = \rho_2 T(A_{21}x, A_{22}y) + A_{22}y - A_{21}x$, then the problem (1.1) reduces to find $x^*, y^* \in H$ such that

$$\begin{cases} \langle \rho_1 T(\gamma^*, x^*) + x^* - \gamma^*, x - x^* \rangle + \varphi(x) - \varphi(x^*) \geq 0, & \forall x \in H, \rho_1 > 0; \\ \langle \rho_2 T(x^*, \gamma^*) + \gamma^* - x^*, x - \gamma^* \rangle + \varphi(x) - \varphi(\gamma^*) \geq 0, & \forall x \in H, \rho_2 > 0. \end{cases} \quad (1.3)$$

Problem (1.3) was studied by He and Gu [2] in 2009.

(3) Let $K \subset H$ be a closed convex subset, $\phi(x) = I_K(x)$, the problem (1.3) reduces to find $x^*, \gamma^* \in K$ such that

$$\begin{cases} \langle \rho_1 T(\gamma^*, x^*) + x^* - \gamma^*, x - x^* \rangle \geq 0, & \forall x \in K, \rho_1 > 0; \\ \langle \rho_2 T(x^*, \gamma^*) + \gamma^* - x^*, x - \gamma^* \rangle \geq 0, & \forall x \in K, \rho_2 > 0. \end{cases} \quad (1.4)$$

Problem (1.4) was inspected and studied by Chang [3], Verma [4,5] and Huang [6].

(4) If $N = 2, A_{11} = A_{12} = A_{21} = A_{22} = I, g : H \rightarrow H, T_1(x, y) = \rho_1 Ty + g(x) - g(y), T_2(x, y) = \rho_2 Tx + g(y) - g(x), (\rho_1, \rho_2 > 0), \eta(x, y) = g(x) - g(y)$, then the problem (1.1) reduces to find $x^*, \gamma^* \in H$ such that

$$\begin{cases} \langle \rho_1 T\gamma^* + g(x^*) - g(\gamma^*), g(x) - g(x^*) \rangle \geq 0, & \forall x \in H; \\ \langle \rho_2 Tx^* + g(\gamma^*) - g(x^*), g(x) - g(\gamma^*) \rangle \geq 0, & \forall x \in H. \end{cases} \quad (1.5)$$

Problem (1.5) was introduced and studied by Hajjafar and Verma [7].

(5) If $N = 3, \eta(x, y) = x - y$, then the problem (1.1) reduces to find $x_1^*, x_2^*, x_3^* \in H, u_{i1}^* \in A_{i1}x_1^*, u_{i2}^* \in A_{i2}x_2^*, u_{i3}^* \in A_{i3}x_3^* (i = 1, 2, 3)$ such that

$$\begin{cases} \langle T_1(u_{11}^*, u_{12}^*, u_{13}^*), x - g_1(x_1^*) \rangle \geq \varphi_1(g_1(x_1^*)) - \varphi_1(x), & \forall x \in H; \\ \langle T_2(u_{21}^*, u_{22}^*, u_{23}^*), x - g_2(x_2^*) \rangle \geq \varphi_2(g_2(x_2^*)) - \varphi_2(x), & \forall x \in H; \\ \langle T_3(u_{31}^*, u_{32}^*, u_{33}^*), x - g_3(x_3^*) \rangle \geq \varphi_3(g_3(x_3^*)) - \varphi_3(x), & \forall x \in H. \end{cases} \quad (1.6)$$

Problem (1.6) was studied by Kazmi et al. [8].

For more special cases, please refer to [1-9] and the references therein.

Remark 1.1. Yang [10] pointed out a fact for the problem (1.4) discussed in reference [5], namely, if the problem (1.4) has a solution (x^*, γ^*) , then $x^* = \gamma^*$. Therefore, actually, the problem(1.4) is a single variational inequality:

$$\langle T(x^*, x^*), x - x^* \rangle \geq 0, \quad \forall x \in K.$$

In this article, we study the problem (1.1). By using the η proximal mapping technique, we prove the existence of solutions and approximate the solutions by some new N -step iterative algorithms. Our results extend and improve some known results in the references [1-9].

2 Preliminaries

In this article, we need the following concepts and lemmas.

Definition 2.1 [1] A mapping $g : H \rightarrow H$ is said to be

(i) ξ -strongly monotone if there exists a constant $\xi > 0$ such that

$$\langle g(x) - g(y), x - y \rangle \geq \xi \|x - y\|^2, \quad \forall x, y \in H.$$

(ii) ζ -Lipschitz continuous if there exists a constant $\zeta > 0$ such that

$$\|g(x) - g(y)\| \leq \zeta \|x - y\|, \quad \forall x, y \in H.$$

Definition 2.2 [1] A mapping $\eta : H \times H \rightarrow H$ is said to be

(i) σ - strongly monotone if there exists a constant $\sigma > 0$ such that

$$\langle x - \gamma, \eta(x, \gamma) \rangle \geq \sigma \|x - \gamma\|^2, \quad \forall x, \gamma \in H;$$

(ii) τ - Lipschitz continuous if there exists a constant $\tau > 0$ such that

$$\|\eta(x, \gamma)\| \leq \tau \|x - \gamma\|, \quad \forall x, \gamma \in H.$$

Definition 2.3 [1,11] Let $A : H \rightarrow CB(H)$ be a set-valued mapping, $T : \underbrace{H \times H \times \dots \times H}_N \rightarrow H$ is said to be

(i) α - (A, g) -strongly monotone in the i th argument if $\alpha > 0$ such that

$$\langle T(\dots, u_i, \dots) - T(\dots, v_i, \dots), g(x) - g(y) \rangle \geq \alpha \|x - y\|^2, \quad \forall x, y \in H, \quad u_i \in Ax, \quad v_i \in Ay.$$

(ii) (s_1, s_2, \dots, s_N) -Lipschitz continuous if there exist constants $s_1, s_2, \dots, s_N > 0$ such that for all $x_i, y_i \in H, i = 1, 2, \dots, N$,

$$\|T(x_1, x_2, \dots, x_N) - T(y_1, y_2, \dots, y_N)\| \leq s_1 \|x_1 - y_1\| + s_2 \|x_2 - y_2\| + \dots + s_N \|x_N - y_N\|.$$

(iii) A set-valued A is said to be δ - H - Lipschitz continuous if there exists a constant $\delta > 0$ such that

$$H(Ax, Ay) \leq \delta \|x - y\|, \quad \forall x, y \in H,$$

where $H(\cdot, \cdot)$ is the Hausdorff metric on $CB(H)$.

Definition 2.4 [1] A functional $f : H \times H \rightarrow \mathbb{R} \cup \{+\infty\}$ is said to be 0-diagonally quasi-concave (in short, 0-DQCV) in x , if for any finite set $\{x_1, \dots, x_N\} \subset H$ and for any $y = \sum_{i=1}^n \lambda_i x_i$ with $\lambda_i \geq 0$ and $\sum_{i=1}^n \lambda_i = 1$,

$$\min_{1 \leq i \leq n} f(x_i, y) \leq 0.$$

Definition 2.5 [1] Let $\eta : H \times H \rightarrow H$ be a single-valued mapping. A proper functional $\phi : H \rightarrow \mathbb{R} \cup \{+\infty\}$ is said to be η -subdifferentiable at a point $x \in H$, if there exists a point $f^* \in H$ such that

$$\langle f^*, \eta(\gamma, x) \rangle \leq \phi(\gamma) - \phi(x), \quad \forall \gamma \in H,$$

where f^* is called a η -subgradient of ϕ at x . The set of all η -subgradients of ϕ at x is denoted by $\partial_\eta \phi(x)$. We have

$$\partial_\eta \phi(x) = \{f^* \in H, \langle f^*, \eta(\gamma, x) \rangle \leq \phi(\gamma) - \phi(x), \quad \forall \gamma \in H.\} \tag{2.1}$$

Definition 2.6 [1] Let η, ϕ be according to Definition 2.5, if for each $x \in H$ and $\rho > 0$, there exists a unique point $u \in H$ such that

$$\langle u - x, \eta(\gamma, u) \rangle \geq \rho \phi(u) - \rho \phi(\gamma), \quad \forall \gamma \in H, \tag{2.2}$$

then the mapping $x \mapsto u$ denoted by J_ϕ^ρ , is said to be η -proximal mapping of ϕ . By (2.1) and the definition of J_ϕ^ρ , we have $x - u \in \rho \partial_\eta \phi(x)$, it follows that

$$J_\phi^\rho(x) = (I + \rho \partial_\eta \phi)^{-1}(x).$$

Lemma 2.1 [1] Let $\eta : H \times H \rightarrow H$ be continuous and σ -strongly monotone such that $\eta(x, y) = -\eta(y, x)$ for all $x, y \in H$. And for any given $x \in H$, the function $h(y, u) = \langle x - u, \eta(y, u) \rangle$ is 0-DQCV in y . Let $\phi : H \rightarrow R \cup \{+\infty\}$ be a lower semicontinuous η -subdifferentiable proper functional on H , then for any given $\rho > 0$ and $x \in H$ there exists a unique $u \in H$ such that

$$\langle u - x, \eta(y, u) \rangle \geq \rho\phi(u) - \rho\phi(y), \quad \forall y \in H.$$

i.e., $u = J_\phi^\rho(x)$.

Lemma 2.2 Let $\eta : H \times H \rightarrow H$ be σ -strongly monotone and τ -Lipschitz continuous such that $\eta(x, y) = -\eta(y, x)$. Let $h(y, u)$, ϕ , ρ be according to Lemma 2.1, then the η -proximal mapping $J_\phi^\rho(x)$ of ϕ is $\frac{\tau}{\sigma}$ -Lipschitz continuous.

3 Main results

Theorem 3.1 $(x_1^*, x_2^*, \dots, x_N^*; u_{11}^*, u_{12}^*, \dots, u_{iN}^*, i = 1, 2, \dots, N.)$ is a solution of problem (1.1) if and only if $(x_1^*, x_2^*, \dots, x_N^*; u_{11}^*, u_{12}^*, \dots, u_{iN}^*, i = 1, 2, \dots, N.)$ satisfies the following relation: For every $i = 1, 2, \dots, N$,

$$g_i(x_i^*) = J_{\phi_i}^{\rho_i}(g_i(x_i^*) - \rho_i T_i(u_{i1}^*, u_{i2}^*, \dots, u_{iN}^*)), \quad (3.1)$$

where $J_{\phi_i}^{\rho_i} = (I + \rho_i \partial_{\eta_i} \phi_i)^{-1}$, $\rho_i > 0$.

Proof. Assume the $(x_1^*, x_2^*, \dots, x_N^*; u_{11}^*, u_{12}^*, \dots, u_{1N}^*, \dots, u_{N1}^*, u_{N2}^*, \dots, u_{NN}^*)$ satisfies relation (3.1). Since $J_{\phi_i}^{\rho_i} = (I + \rho_i \partial_{\eta_i} \phi_i)^{-1}$, we have

$$g_i(x_i^*) + \rho_i \partial_{\eta_i} \phi_i(g_i(x_i^*)) \in g_i(x_i^*) - \rho_i T_i(u_{i1}^*, u_{i2}^*, \dots, u_{iN}^*).$$

i.e.,

$$-T_i(u_{i1}^*, u_{i2}^*, \dots, u_{iN}^*) \in \partial_{\eta_i} \phi_i(g_i(x_i^*)).$$

By the Definition 2.5 of η_i -subdifferential, the above relation holds if and only if

$$-\langle T_i(u_{i1}^*, u_{i2}^*, \dots, u_{iN}^*), \eta_i(x, g_i(x_i^*)) \rangle \leq \phi_i(x) - \phi_i(g_i(x_i^*)), \quad \forall x \in H,$$

and hence

$$\langle T_i(u_{i1}^*, u_{i2}^*, \dots, u_{iN}^*), \eta_i(x, g_i(x_i^*)) \rangle \geq \phi_i(g_i(x_i^*)) - \phi_i(x), \quad \forall x \in H, i = 1, 2, \dots, N.$$

i.e., $(x_1^*, x_2^*, \dots, x_N^*; u_{11}^*, u_{12}^*, \dots, u_{iN}^*, i = 1, 2, \dots, N.)$ is a solution of the problem (1.1). \square

Now, we give iterative algorithms of problem (1.1).

Algorithm(I) For given $x_1^0, x_2^0, \dots, x_N^0 \in H, u_{11}^0 \in A_{i1}x_1^0, u_{12}^0 \in A_{i2}x_2^0, \dots, u_{iN}^0 \in A_{iN}x_N^0$, let

$$\begin{aligned} x_1^1 &= x_1^0 - g_1(x_1^0) + J_{\phi_1}^{\rho_1}(g_1(x_1^0) - \rho_1 T_1(u_{11}^0, u_{12}^0, \dots, u_{1N}^0)); \\ x_2^1 &= x_2^0 - g_2(x_2^0) + J_{\phi_2}^{\rho_2}(g_2(x_2^0) - \rho_2 T_2(u_{21}^0, u_{22}^0, \dots, u_{2N}^0)); \\ &\vdots \\ x_N^1 &= x_N^0 - g_N(x_N^0) + J_{\phi_N}^{\rho_N}(g_N(x_N^0) - \rho_N T_N(u_{N1}^0, u_{N2}^0, \dots, u_{NN}^0)). \end{aligned}$$

By Nadler [12], for $i = 1, 2, \dots, N, j = 1, 2, \dots, N$, there exists $u_{ij}^1 \in A_{ij}x_j^1$ such that

$$\|u_{ij}^0 - u_{ij}^1\| \leq (1 + 1)H(A_{ij}x_j^0, A_{ij}x_j^1), \quad j = 1, 2, \dots, N.$$

Let

$$x_i^2 = x_i^1 - g_i(x_i^1) + J_{\varphi_i}^{\rho_i}(g_i(x_i^1) - \rho_i T_i(u_{i1}^1, u_{i2}^1, \dots, u_{iN}^1)), \quad i = 1, 2, \dots, N.$$

By induction, we can define sequences $\{x_i^n\}, \{u_{ij}^n\}$ satisfying

$$x_i^{n+1} = x_i^n - g_i(x_i^n) + J_{\varphi_i}^{\rho_i}(g_i(x_i^n) - \rho_i T_i(u_{i1}^n, u_{i2}^n, \dots, u_{iN}^n)),$$

where for any $i, j = 1, 2, \dots, N; n = 0, 1, 2, \dots$,

$$u_{ij}^n \in A_{ij}^n x_j^n, \quad u_{ij}^n - u_{ij}^{n+1} \leq \left(1 + \frac{1}{n+1}\right) H\left(A_{ij}\left(x_j^n\right), A_{ij}\left(x_j^{n+1}\right)\right).$$

Theorem 3.2 Let H be a real Hilbert space. For $i, j = 1, 2, \dots, N$, let set-valued mapping $A_{ij}: H \rightarrow CB(H)$ be δ_{ij} - H -Lipschitz continuous. Let mapping $\eta_i: H \times H \rightarrow H$ be σ_i -strongly monotone and τ_i -Lipschitz continuous such that $\eta_i(x, y) = -\eta_i(y, x)$ for all $x, y \in H$ and for any given $x \in H$, the function $h_i(y, u) = \langle x - g_i(u), \eta_i(y, u) \rangle$ is 0-DQCU in y . Let mapping $g_i: H \rightarrow H$ be ζ_i -strongly monotone and ζ_i -Lipschitz continuous, and $T_i: \underbrace{H \times H \times \dots \times H}_N \rightarrow H$ be (s_1, \dots, s_N) -Lipschitz continuous and α_i - (A_{ij}, g_i) -strongly monotone in the i th argument. Let $\phi_i: H \rightarrow R \cup \{+\infty\}$ be a lower semi-continuous η_i -subdifferentiable proper functional. If there exist $\rho_1, \dots, \rho_N > 0$ such that for all $i = 1, 2, \dots, N$

$$(1 - 2\xi_i + \zeta_i^2) \frac{1}{2} + \frac{\tau_i}{\sigma_i} (\xi_i^2 - 2\rho_i \alpha_i + \rho_i^2 s_i^2 \delta_{ii}^2) \frac{1}{2} + \sum_{k=1, k \neq i}^N \frac{\tau_k}{\sigma_k} \rho_k s_i \delta_{ki} < 1; \tag{3.2}$$

then the iterative sequences $\{x_1^n\}, \dots, \{x_N^n\}, \{u_{11}^n\}, \dots, \{u_{1N}^n\}, \dots, \{u_{N1}^n\}, \dots, \{u_{NN}^n\}$, generated by algorithm (I) converge strongly to $x_1^*, \dots, x_N^*, u_{11}^*, \dots, u_{1N}^*, \dots, u_{N1}^*, \dots, u_{NN}^*$, respectively, and $(x_1^*, x_2^*, \dots, x_N^*, u_{11}^*, u_{12}^*, \dots, u_{1N}^*, \dots, u_{N1}^*, u_{N2}^*, \dots, u_{NN}^*)$ is a solution of the problem (1.1).

Proof. For $i = 1, 2, \dots, N$, by algorithm (I) and Lemma 2.2, we have

$$\begin{aligned} \|x_i^{n+1} - x_i^n\| &= \|x_i^n - g_i(x_i^n) + J_{\varphi_i}^{\rho_i}(g_i(x_i^n) - \rho_i T_i(u_{i1}^n, u_{i2}^n, \dots, u_{iN}^n)) \\ &\quad - x_i^{n-1} + g_i(x_i^{n-1}) - J_{\varphi_i}^{\rho_i}(g_i(x_i^{n-1}) - \rho_i T_i(u_{i1}^{n-1}, u_{i2}^{n-1}, \dots, u_{iN}^{n-1}))\| \\ &\leq \|x_i^n - x_i^{n-1} - g_i(x_i^n) + g_i(x_i^{n-1})\| \\ &\quad + \|J_{\varphi_i}^{\rho_i}(g_i(x_i^n) - \rho_i T_i(u_{i1}^n, u_{i2}^n, \dots, u_{iN}^n)) \\ &\quad - J_{\varphi_i}^{\rho_i}(g_i(x_i^{n-1}) - \rho_i T_i(u_{i1}^{n-1}, u_{i2}^{n-1}, \dots, u_{iN}^{n-1}))\| \\ &\leq \|x_i^n - x_i^{n-1} - g_i(x_i^n) + g_i(x_i^{n-1})\| \\ &\quad + \frac{\tau_i}{\sigma_i} \|g_i(x_i^n) - g_i(x_i^{n-1}) - \rho_i T_i(u_{i1}^n, \dots, u_{iN}^n) + \rho_i T_i(u_{i1}^{n-1}, \dots, u_{iN}^{n-1})\|. \end{aligned} \tag{3.3}$$

Since g_i is ζ_i -strongly monotone and ζ_i -Lipschitz continuous, we obtain

$$\|x_i^n - x_i^{n-1} - (g_i(x_i^n) - g_i(x_i^{n-1}))\| \leq \sqrt{1 - 2\xi_i + \zeta_i^2} \|x_i^n - x_i^{n-1}\|. \quad (3.4)$$

Notice that,

$$\begin{aligned} & \|g_i(x_i^n) - g_i(x_i^{n-1}) - \rho_i(T_i(u_{i1}^n, \dots, u_{iN}^n) - T_i(u_{i1}^{n-1}, \dots, u_{iN}^{n-1}))\| \\ & \leq \|g_i(x_i^n) - g_i(x_i^{n-1}) - \rho_i(T_i(u_{i1}^n, u_{i2}^n, \dots, u_{i,i-1}^n, u_{ii}^n, u_{i,i+1}^n, \dots, u_{iN}^n) \\ & \quad - T_i(u_{i1}^n, u_{i2}^n, \dots, u_{i,i-1}^n, u_{ii}^{n-1}, u_{i,i+1}^n, \dots, u_{iN}^n))\| \\ & + \rho_i \|T_i(u_{i1}^n, u_{i2}^n, \dots, u_{i,i-1}^n, u_{ii}^{n-1}, u_{i,i+1}^n, \dots, u_{iN}^n) - T_i(u_{i1}^{n-1}, u_{i2}^{n-1}, \dots, u_{iN}^{n-1})\|. \end{aligned} \quad (3.5)$$

Since T_i is (s_1, \dots, s_N) -Lipschitz continuous and $\alpha_i - (A_{ij}, g_i)$ - strongly monotone in the i th argument, we get

$$\begin{aligned} & \|g_i(x_i^n) - g_i(x_i^{n-1}) - \rho_i(T_i(u_{i1}^n, u_{i2}^n, \dots, u_{i,i-1}^n, u_{ii}^n, u_{i,i+1}^n, \dots, u_{iN}^n) \\ & \quad - T_i(u_{i1}^n, u_{i2}^n, \dots, u_{i,i-1}^n, u_{ii}^{n-1}, u_{i,i+1}^n, \dots, u_{iN}^n))\|^2 \\ & = \|g_i(x_i^n) - g_i(x_i^{n-1})\|^2 - 2\rho_i \langle g_i(x_i^n) - g_i(x_i^{n-1}), T_i(u_{i1}^n, u_{i2}^n, \dots, u_{i,i-1}^n, u_{ii}^n, u_{i,i+1}^n, \dots, u_{iN}^n) \\ & \quad - T_i(u_{i1}^n, u_{i2}^n, \dots, u_{i,i-1}^n, u_{ii}^{n-1}, u_{i,i+1}^n, \dots, u_{iN}^n) \rangle \\ & + \rho_i^2 \|T_i(u_{i1}^n, u_{i2}^n, \dots, u_{i,i-1}^n, u_{ii}^n, u_{i,i+1}^n, \dots, u_{iN}^n) \\ & \quad - T_i(u_{i1}^n, u_{i2}^n, \dots, u_{i,i-1}^n, u_{ii}^{n-1}, u_{i,i+1}^n, \dots, u_{iN}^n)\|^2 \\ & \leq \xi_i^2 \|x_i^n - x_i^{n-1}\|^2 - 2\rho_i \alpha_i \|x_i^n - x_i^{n-1}\|^2 + \rho_i^2 s_i^2 \|u_{ii}^n - u_{ii}^{n-1}\|^2 \\ & \leq (\xi_i^2 - 2\rho_i \alpha_i) \|x_i^n - x_i^{n-1}\|^2 + \rho_i^2 s_i^2 \left(1 + \frac{1}{n}\right)^2 (H(A_{ii}x_i^n, A_{ii}x_i^{n-1}))^2 \\ & \leq \left[\xi_i^2 - 2\rho_i \alpha_i + \rho_i^2 s_i^2 \delta_{ii}^2 \left(1 + \frac{1}{n}\right)^2\right] \|x_i^n - x_i^{n-1}\|^2. \end{aligned} \quad (3.6)$$

Therefore,

$$\begin{aligned} & \|g_i(x_i^n) - g_i(x_i^{n-1}) - \rho_i(T_i(u_{i1}^n, u_{i2}^n, \dots, u_{i,i-1}^n, u_{ii}^n, u_{i,i+1}^n, \dots, u_{iN}^n) \\ & \quad - T_i(u_{i1}^n, u_{i2}^n, \dots, u_{i,i-1}^n, u_{ii}^{n-1}, u_{i,i+1}^n, \dots, u_{iN}^n))\| \\ & \leq \left[\xi_i^2 - 2\rho_i \alpha_i + \rho_i^2 s_i^2 \delta_{ii}^2 \left(1 + \frac{1}{n}\right)^2\right]^{\frac{1}{2}} \|x_i^n - x_i^{n-1}\|. \end{aligned} \quad (3.7)$$

And

$$\begin{aligned} & \rho_i \|T_i(u_{i1}^n, u_{i2}^n, \dots, u_{i,i-1}^n, u_{ii}^{n-1}, u_{i,i+1}^n, \dots, u_{iN}^n) \\ & \quad - T_i(u_{i1}^{n-1}, u_{i2}^{n-1}, \dots, u_{i,i-1}^{n-1}, u_{ii}^{n-1}, u_{i,i+1}^{n-1}, \dots, u_{iN}^{n-1})\| \\ & \leq \rho_i (s_1 \|u_{i1}^n - u_{i1}^{n-1}\| + s_2 \|u_{i2}^n - u_{i2}^{n-1}\| + \dots \\ & \quad + s_{i-1} \|u_{i,i-1}^n - u_{i,i-1}^{n-1}\| + s_{i+1} \|u_{i,i+1}^n - u_{i,i+1}^{n-1}\| + \dots + s_N \|u_{iN}^n - u_{iN}^{n-1}\|) \\ & \leq \rho_i \left[s_1 \left(1 + \frac{1}{n}\right) H(A_{i1}x_1^n, A_{i1}x_1^{n-1}) \right] + s_2 \left(1 + \frac{1}{n}\right) H(A_{i2}x_2^n, A_{i2}x_2^{n-1}) + \dots \\ & \quad + s_{i-1} \left(1 + \frac{1}{n}\right) H(A_{i,i-1}x_{i-1}^n, A_{i,i-1}x_{i-1}^{n-1}) \\ & \quad + s_{i+1} \left(1 + \frac{1}{n}\right) H(A_{i,i+1}x_{i+1}^n, A_{i,i+1}x_{i+1}^{n-1}) + \dots + s_N \left(1 + \frac{1}{n}\right) H(A_{iN}x_N^n, A_{iN}x_N^{n-1}) \\ & \leq \rho_i \left(1 + \frac{1}{n}\right) [s_1 \delta_{i1} \|x_1^n - x_1^{n-1}\| + s_2 \delta_{i2} \|x_2^n - x_2^{n-1}\| + \dots \\ & \quad + s_{i-1} \delta_{i,i-1} \|x_{i-1}^n - x_{i-1}^{n-1}\| + s_{i+1} \delta_{i,i+1} \|x_{i+1}^n - x_{i+1}^{n-1}\| + \dots + s_N \delta_{iN} \|x_N^n - x_N^{n-1}\|]. \end{aligned} \quad (3.8)$$

It follows from (3.3)-(3.8) that for every $i = 1, 2, \dots, N$,

$$\begin{aligned} \|x_i^{n+1} - x_i^n\| &\leq \left[\sqrt{1 - 2\xi_i + \zeta_i^2} + \frac{\tau_i}{\sigma_i} \left(\xi_i^2 - 2\rho_i\alpha_i + \rho_i^2 s_i^2 \delta_{ii}^2 \left(1 + \frac{1}{n}\right)^2 \right) \frac{1}{2} \right] \|x_i^n - x_i^{n-1}\| \\ &\quad + \rho_i \frac{\tau_i}{\sigma_i} \left(1 + \frac{1}{n}\right) \sum_{k=1, k \neq i}^N s_k \delta_{ik} \|x_k^n - x_k^{n-1}\|. \end{aligned} \tag{3.9}$$

So,

$$\begin{aligned} &\|x_1^{n+1} - x_1^n\| + \|x_2^{n+1} - x_2^n\| + \dots + \|x_N^{n+1} - x_N^n\| \\ &\leq \sum_{i=1}^N \left\{ \left[\sqrt{1 - 2\xi_i + \zeta_i^2} + \frac{\tau_i}{\sigma_i} \left(\xi_i^2 - 2\rho_i\alpha_i + \rho_i^2 s_i^2 \delta_{ii}^2 \left(1 + \frac{1}{n}\right)^2 \right) \frac{1}{2} \right] \|x_i^n - x_i^{n-1}\| \right. \\ &\quad \left. + \rho_i \frac{\tau_i}{\sigma_i} \sum_{k=1, k \neq i}^N s_k \delta_{ik} \left(1 + \frac{1}{n}\right) \|x_k^n - x_k^{n-1}\| \right\} \\ &= \sum_{i=1}^N \left\{ \sqrt{1 - 2\xi_i + \zeta_i^2} + \frac{\tau_i}{\sigma_i} \left(\xi_i^2 - 2\rho_i\alpha_i + \rho_i^2 s_i^2 \delta_{ii}^2 \left(1 + \frac{1}{n}\right)^2 \right) \frac{1}{2} \right. \\ &\quad \left. + \sum_{k=1, k \neq i}^N \rho_k \frac{\tau_k}{\sigma_k} s_i \delta_{ki} \left(1 + \frac{1}{n}\right) \right\} \|x_i^n - x_i^{n-1}\| \\ &\leq \theta_n (\|x_1^n - x_1^{n-1}\| + \|x_2^n - x_2^{n-1}\| + \dots + \|x_N^n - x_N^{n-1}\|), \end{aligned} \tag{3.10}$$

where

$$\theta_n = \max_{i=1,2,\dots,N} \left\{ \sqrt{1 - 2\xi_i + \zeta_i^2} + \frac{\tau_i}{\sigma_i} \left(\xi_i^2 - 2\rho_i\alpha_i + \rho_i^2 s_i^2 \delta_{ii}^2 \left(1 + \frac{1}{n}\right)^2 \right) \frac{1}{2} + \sum_{k=1, k \neq i}^N \rho_k \frac{\tau_k}{\sigma_k} s_i \delta_{ki} \left(1 + \frac{1}{n}\right) \right\}$$

Letting

$$\theta = \max_{i=1,2,\dots,N} \left\{ \sqrt{1 - 2\xi_i + \zeta_i^2} + \frac{\tau_i}{\sigma_i} \left(\xi_i^2 - 2\rho_i\alpha_i + \rho_i^2 s_i^2 \delta_{ii}^2 \right) \frac{1}{2} + \sum_{k=1, k \neq i}^N \rho_k \frac{\tau_k}{\sigma_k} s_i \delta_{ki} \right\},$$

from (3.2) we have $0 < \theta < 1$, and hence $\{x_1^n\} \dots \{x_N^n\}$ are also Cauchy sequences. Thus there exist $x_1^*, \dots, x_N^* \in H$ such that $x_i^n \rightarrow x_i^* (n \rightarrow \infty), i = 1, 2, \dots, N$.

Now we prove $u_{ij}^n \rightarrow u_{ij}^* (n \rightarrow \infty)$, for $i = 1, 2, \dots, N, j = 1, 2, \dots, N$. By $\|u_{ij}^n - u_{ij}^{n-1}\| \leq \left(1 + \frac{1}{n}\right) H (A_{ij} x_j^n, A_{ij} x_j^{n-1}) \leq \left(1 + \frac{1}{n}\right) \delta_{ij} \|x_j^n - x_j^{n-1}\|$.

It follows that $\{u_{ij}^n\}$ are also Cauchy sequence. Therefore, there exist $u_{ij}^* \in H$ such that $u_{ij}^n \rightarrow u_{ij}^* (n \rightarrow \infty)$.

Note that

$$\begin{aligned} d(u_{ij}^*, A_{ij}x_j^*) &\leq \|u_{ij}^* - u_{ij}^n\| d(u_{ij}^n, A_{ij}x_j^*) \\ &\leq \|u_{ij}^* - u_{ij}^n\| + H(A_{ij}x_j^n, A_{ij}x_j^*) \leq \|u_{ij}^* - u_{ij}^n\| + \delta_{ij} \|x_j^n - x_j^*\| \rightarrow 0 (n \rightarrow \infty). \end{aligned}$$

We have $d(u_{ij}^*, A_{ij}x_j^*) = 0$. Since $A_{ij}x_j^*$ is closed, $u_{ij}^* \in A_{ij}x_j^*$, for each $i = 1, 2, \dots, N, j = 1, 2, \dots, N$. By

$$x_i^{n+1} = x_i^n - g_i(x_i^n) + J_{\phi_i}^{\rho_i}(g_i(x_i^n) - \rho_i T_i(u_{i1}^n, u_{i2}^n, \dots, u_{iN}^n)), \quad i = 1, 2, \dots, N,$$

and the continuity of $g_i, J_{\phi_i}^{\rho_i}, T_i$, let $n \rightarrow \infty$, we have that

$$0 = -g_i(x_i^*) + J_{\phi_i}^{\rho_i}(g_i(x_i^*) - \rho_i T_i(u_{i1}^*, u_{i2}^*, \dots, u_{iN}^*)),$$

and

$$u_{i1}^* \in A_{i1}x_1^*, u_{i2}^* \in A_{i2}x_2^*, \dots, u_{iN}^* \in A_{iN}x_N^*.$$

By Theorem 3.1, $(x_1^*, x_2^*, \dots, x_N^*, u_{i1}^*, u_{i2}^*, \dots, u_{iN}^*, i = 1, 2, \dots, N)$ is a solution of the problem (1.1). This completes the proof. \square

Remark 3.1 For a suitable choice of T_i, A_{ij}, η_i, g_i and ϕ_i , Theorem 3.2 includes many known results of generalized quasi-variational-like inclusions as special cases (see [1-8]), where ϕ_i is nonconvex and A_{ij} is noncompact.

Acknowledgements

The author thanks to the guidance and support of my supervisor Pro. Li-Wei Liu who taught at the department of mathematics in Nanchang university. The author thanks the anonymous referees for reading this article carefully, providing valuable suggestions and comments. The work was supported by the National Science Foundation of China (No.10561007) and Science and Technology Research Project of Education Department in Jiangxi province (GJJ10269).

Competing interests

The authors declare that they have no competing interests.

Received: 13 October 2011 Accepted: 23 February 2012 Published: 23 February 2012

References

- Ding, XP: Generalized quasi-variational-like inclusions with nonconvex functional. *Appl Math Comput.* **122**, 267–282 (2001). doi:10.1016/S0096-3003(00)00027-8
- He, Z, Gu, F: Generalized system for relaxed cocoercive mixed variational inequalities in Hilbert spaces. *Appl Math Comput.* **214**, 26–30 (2009). doi:10.1016/j.amc.2009.03.056
- Chang, SS, Joseph Lee, HW, Chan, CK: Generalized system for relaxed cocoercive variational inequalities in Hilbert spaces. *Appl Math Lett.* **20**, 329–334 (2007). doi:10.1016/j.aml.2006.04.017
- Verma, RU: General convergence analysis for two-step projection methods and applications to variational problems. *Appl Math Lett.* **18**, 1286–1292 (2005). doi:10.1016/j.aml.2005.02.026
- Verma, RU: Projection methods, algorithms and a new system of nonlinear variational inequalities. *Comput Math Appl.* **42**, 1025–1031 (2001). doi:10.1016/S0898-1221(01)00218-8
- Huang, Z, Noor, MA: An explicit projection method for a system of nonlinear variational inequalities with dierent (γ, r) -cocoercive mapping. *Appl Math Comput.* **190**, 356–361 (2007). doi:10.1016/j.amc.2007.01.032
- Hajjafar, A, Verma, RU: General approximation solvability of a system of strongly g - r -pseudomonotonic nonlinear variational inequalities and projection methods. *Math Comput Model.* **43**, 150–157 (2006). doi:10.1016/j.mcm.2005.01.038
- Kazmi, KR, Bhat, MI, Naeem, Ahmad: An iterative algorithm based on M -proximal mappings for a system of generalized implicit variational inclusions in Banach spaces. *J Comput Appl Math.* **233**(2):361–371 (2009). doi:10.1016/j.cam.2009.07.028
- Ahmad, R, Siddiqi, AH, Khan, Z: Proximal point algorithm for generalized multivalued nonlinear quasi-variational-like inclusions in Banach spaces. *Appl Math Comput.* **163**, 295–308 (2005). doi:10.1016/j.amc.2004.02.021
- Yang, QZ: On a generalized system for relaxed cocoercive variational inequalities and projection methods. *J Optim Theory Appl.* **130**, 545–547 (2006)

11. Peng, JW, Zhu, DL: A new system of generalized mixed quasi-variational inclusion with (H, η) -monotone operators. *J Math Anal Appl.* **327**, 157–187 (2007)
12. Nadler, SB: Multi-valued contraction mappings. *Pac J Math.* **30**, 475–486 (1969)

doi:10.1186/1029-242X-2012-41

Cite this article as: Cao: A new system of generalized quasi-variational-like inclusions with noncompact valued mappings. *Journal of Inequalities and Applications* 2012 2012:41.

Submit your manuscript to a SpringerOpen[®] journal and benefit from:

- ▶ Convenient online submission
- ▶ Rigorous peer review
- ▶ Immediate publication on acceptance
- ▶ Open access: articles freely available online
- ▶ High visibility within the field
- ▶ Retaining the copyright to your article

Submit your next manuscript at ▶ springeropen.com
