Hindawi Publishing Corporation Journal of Inequalities and Applications Volume 2010, Article ID 312602, 18 pages doi:10.1155/2010/312602

Research Article

Hybrid Projection Algorithms for Generalized Equilibrium Problems and Strictly Pseudocontractive Mappings

Jong Kyu Kim, 1 Sun Young Cho, 2 and Xiaolong Qin 3

Correspondence should be addressed to Jong Kyu Kim, jongkyuk@kyungnam.ac.kr

Received 12 October 2009; Accepted 19 July 2010

Academic Editor: András Rontó

Copyright © 2010 Jong Kyu Kim et al. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

The purpose of this paper is to consider the problem of finding a common element in the solution set of equilibrium problems and in the fixed point set of a strictly pseudocontractive mapping. Strong convergence of the purposed hybrid projection algorithm is obtained in Hilbert spaces.

1. Introduction and Preliminaries

Let H be a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and norm $\| \cdot \|$. Let C be a nonempty closed convex subset of H and $S: C \to C$ a nonlinear mapping. In this paper, we use F(S) to denote the fixed point set of S. Recall that the mapping S is said to be nonexpansive if

$$||Sx - Sy|| \le ||x - y||, \quad \forall x, y \in C.$$
 (1.1)

S is said to be k-strictly pseudocontractive if there exists a constant $k \in [0,1)$ such that

$$||Sx - Sy||^2 \le ||x - y||^2 + k||(x - Sx) - (y - Sy)||^2, \quad \forall x, y \in C.$$
 (1.2)

S is said to be pseudocontractive if

$$||Sx - Sy||^2 \le ||x - y||^2 + ||(x - Sx) - (y - Sy)||^2, \quad \forall x, y \in C.$$
(1.3)

¹ Department of Mathematics Education, Kyungnam University, Masan 631-701, Republic of Korea

² Department of Mathematics, Gyeongsang National University, Chinju 660-701, Republic of Korea

³ Department of Mathematics, Hangzhou Normal University, Hangzhou 310036, China

The class of strictly pseudocontractive mappings was introduced by Browder and Petryshyn [1] in 1967. It is easy to see that the class of strictly pseudocontractive mappings falls into the class of nonexpansive mappings and the class of pseudocontractions.

Let $A: C \to H$ be a mapping. Recall that A is said to be monotone if

$$\langle Ax - Ay, x - y \rangle \ge 0, \quad \forall x, y \in C.$$
 (1.4)

A is said to be inverse-strongly monotone if there exists a constant $\alpha > 0$ such that

$$\langle Ax - Ay, x - y \rangle \ge \alpha ||Ax - Ay||^2, \quad \forall x, y \in C.$$
 (1.5)

Let F be a bifunction of $C \times C$ into \mathbb{R} , where \mathbb{R} denotes the set of real numbers and $A:C \to H$ an inverse-strongly monotone mapping. In this paper, we consider the following generalized equilibrium problem.

Find
$$x \in C$$
 such that $F(x, y) + \langle Ax, y - x \rangle \ge 0$, $\forall y \in C$. (1.6)

In this paper, the set of such an $x \in C$ is denoted by EP(F, A), that is,

$$EP(F,A) = \{x \in C : F(x,y) + \langle Ax, y - x \rangle \ge 0, \quad \forall y \in C\}. \tag{1.7}$$

To study the generalized equilibrium problems (1.6), we may assume that F satisfies the following conditions:

- (A1) F(x, x) = 0 for all $x \in C$;
- (A2) *F* is monotone, that is, $F(x, y) + F(y, x) \le 0$ for all $x, y \in C$;
- (A3) for each $x, y, z \in C$,

$$\limsup_{t\downarrow 0} F(tz + (1-t)x, y) \le F(x, y); \tag{1.8}$$

- (A4) for each $x \in C$, $y \mapsto F(x,y)$ is convex and weakly lower semicontinuous. Next, we give two special cases of the problem (1.6).
- (I) If $A \equiv 0$, then the generalized equilibrium problem (1.6) is reduced to the following equilibrium problem:

Find
$$x \in C$$
 such that $F(x, y) \ge 0$, $\forall y \in C$. (1.9)

In this paper, the set of such an $x \in C$ is denoted by EP(F), that is,

$$EP(F) = \{ x \in C : F(x, y) \ge 0, \ \forall y \in C \}. \tag{1.10}$$

(II) If $F \equiv 0$, then the problem (1.6) is reduced to the following classical variational inequality. Find $x \in C$ such that

$$\langle Ax, y - x \rangle \ge 0, \quad \forall y \in C.$$
 (1.11)

It is known that $x \in C$ is a solution to (1.11) if and only if x is a fixed point of the mapping $P_C(I - \rho A)$, where $\rho > 0$ is a constant and I is the identity mapping.

Recently, many authors studied the problems (1.6) and (1.9) based on iterative methods; see, for example, [2–18].

In 2007, Tada and Takahashi [17] considered the problem (1.9) and proved the following result.

Theorem TT. Let C be a nonempty closed convex subset of H. Let F be a bifunction from $C \times C$ to \mathbb{R} satisfying (A1)–(A4) and let S be a nonexpansive mapping of C into H such that $F(S) \cap EP(F) \neq \emptyset$. Let $\{x_n\}$ and $\{u_n\}$ be sequences generated by $x_1 = x \in H$ and let

$$F(u_{n}, y) + \frac{1}{r_{n}} \langle y - u_{n}, u_{n} - x_{n} \rangle \ge 0, \quad \forall y \in C,$$

$$w_{n} = (1 - \alpha_{n})x_{n} + \alpha_{n}Su_{n},$$

$$C_{n} = \{z \in H : ||w_{n} - z|| \le ||x_{n} - z||\},$$

$$D_{n} = \{z \in H : \langle x_{n} - z, x - x_{n} \rangle \ge 0\},$$

$$x_{n+1} = P_{C_{n} \cap D_{n}} x,$$
(1.12)

for every $n \ge 1$, where $\{\alpha_n\} \subset [a,1]$ for some $a \in (0,1)$ and $\{r_n\} \subset [0,\infty)$ satisfies $\liminf_{n\to\infty} r_n > 0$. Then, $\{x_n\}$ converges strongly to $P_{F(S)\cap EP(F)}x$.

In this paper, we consider the generalized equilibrium problem (1.6) and a strictly pseudocontractive mapping based on the shrinking projection algorithm which was first introduced by Takahashi et al. [18]. A strong convergence of common elements of the fixed point sets of the strictly pseudocontractive mapping and of the solution sets of the generalized equilibrium problem is established in the framework of Hilbert spaces. The results presented in this paper improve and extend the corresponding results announced by Tada and Takahashi [17].

In order to prove our main results, we also need the following definitions and lemmas.

Lemma 1.1 (see [19]). Let C be a nonempty closed convex subset of a Hilbert space H and $T: C \to C$ a k-strict pseudocontraction. Then T is (1+k)/(1-k)-Lipschitz and I-T is demiclosed, this is, if $\{x_n\}$ is a sequence in C with $x_n \to x$ and $x_n - Tx_n \to 0$, then $x \in F(T)$.

The following lemma can be found in [2, 3].

Lemma 1.2. Let C be a nonempty closed convex subset of H and let $F: C \times C \to \mathbb{R}$ be a bifunction satisfying (A1)–(A4). Then, for any r > 0 and $x \in H$, there exists $z \in C$ such that

$$F(z,y) + \frac{1}{r} \langle y - z, z - x \rangle \ge 0, \quad \forall y \in C.$$
 (1.13)

Further, define

$$T_r x = \left\{ z \in C : F(z, y) + \frac{1}{r} \langle y - z, z - x \rangle \ge 0, \ \forall y \in C \right\}$$
 (1.14)

for all r > 0 and $x \in H$. Then, the following hold:

- (a) T_r is single-valued;
- (b) T_r is firmly nonexpansive, that is, for any $x, y \in H$,

$$||T_r x - T_r y||^2 \le \langle T_r x - T_r y, x - y \rangle; \tag{1.15}$$

- (c) $F(T_r) = EP(F)$;
- (d) EP(F) is closed and convex.

Lemma 1.3 (see [1]). Let C be a nonempty closed convex subset of a real Hilbert space H and S: $C \to C$ a k-strict pseudocontraction with a fixed point. Define $S: C \to C$ by $S_a x = ax + (1-a)Sx$ for each $x \in C$. If $a \in [k, 1)$, then S_a is nonexpansive with $F(S_a) = F(S)$.

2. Main Results

Theorem 2.1. Let C be a nonempty closed convex subset of a real Hilbert space H. Let F_1 and F_2 be two bifunctions from $C \times C$ to $\mathbb R$ which satisfies (A1)–(A4). Let $A: C \to H$ be an α -inverse-strongly monotone mapping, $B: C \to H$ a β -inverse-strongly monotone mapping, and $S: C \to C$

a k-strict pseudocontraction. Let $\{r_n\}$ and $\{s_n\}$ be two positive real sequences. Assume that $\mathcal{F} := EP(F_1, A) \cap FP(F_2, B) \cap F(S)$ is not empty. Let $\{x_n\}$ be a sequence generated in the following manner:

$$x_{1} \in C,$$

$$C_{1} = C,$$

$$F_{1}(u_{n}, u) + \langle Ax_{n}, u - u_{n} \rangle + \frac{1}{r_{n}} \langle u - u_{n}, u_{n} - x_{n} \rangle \ge 0, \quad \forall u \in C,$$

$$F_{2}(v_{n}, v) + \langle Bx_{n}, v - v_{n} \rangle + \frac{1}{s_{n}} \langle v - v_{n}, v_{n} - x_{n} \rangle \ge 0, \quad \forall v \in C,$$

$$z_{n} = \gamma_{n}u_{n} + (1 - \gamma_{n})v_{n},$$

$$y_{n} = \alpha_{n}x_{n} + (1 - \alpha_{n})(\beta_{n}z_{n} + (1 - \beta_{n})Sz_{n}),$$

$$C_{n+1} = \{w \in C_{n} : \|y_{n} - w\| \le \|x_{n} - w\|\},$$

$$x_{n+1} = P_{C_{n+1}}x_{1}, \quad n \ge 1,$$

$$(Y)$$

where $\{\alpha_n\}$, $\{\beta_n\}$, and $\{\gamma_n\}$ are sequences in (0,1). Assume that $\{\alpha_n\}$, $\{\beta_n\}$, $\{\gamma_n\}$, $\{r_n\}$, and $\{s_n\}$ satisfy the following restrictions:

- (a) $0 \le \alpha_n \le a < 1$;
- (b) $0 \le k \le \beta_n < b < 1$;
- (c) $0 \le c \le \gamma_n \le d < 1$;
- (d) $0 < e \le r_n \le f < 2\alpha$ and $0 < e' \le s_n \le f' < 2\beta$.

Then the sequence $\{x_n\}$ generated in (Υ) converges strongly to some point \overline{x} , where $\overline{x} = P_{\overline{x}}x_1$.

Proof. Note that u_n can be rewritten as

$$u_n = T_{r_n}(x_n - r_n A x_n), \quad \forall n \ge 1$$
 (2.1)

and v_n can be rewritten as

$$v_n = T_{s_n}(x_n - s_n B x_n), \quad \forall n \ge 1.$$
 (2.2)

Fix $p \in \mathcal{F}$. It follows that

$$p = Sp = T_{r_n}(p - r_n Ap) = T_{s_n}(p - s_n Bp), \quad \forall n \ge 1.$$
 (2.3)

Note that $I - r_n A$ is nonexpansive for each $n \ge 1$. Indeed, for any $x, y \in C$, we see from the restriction (d) that

$$\|(I - r_n A)x - (I - r_n A)y\|^2 = \|(x - y) - r_n (Ax - Ay)\|^2$$

$$= \|x - y\|^2 - 2r_n \langle x - y, Ax - Ay \rangle + r_n^2 \|Ax - Ay\|^2$$

$$\leq \|x - y\|^2 - r_n (2\alpha - r_n) \|Ax - Ay\|^2$$

$$\leq \|x - y\|^2.$$
(2.4)

This shows that $I - r_n A$ is nonexpansive for each $n \ge 1$. In a similar way, we can obtain that $I - s_n B$ is nonexpansive for each $n \ge 1$. It follows that

$$||u_n - p|| \le ||x_n - p||, \qquad ||u_n - p|| \le ||x_n - p||.$$
 (2.5)

This implies that

$$||z_n - p|| \le \gamma_n ||u_n - p|| + (1 - \gamma_n) ||v_n - p|| \le ||x_n - p||.$$
(2.6)

Now, we are in a position to show that C_n is closed and convex for each $n \ge 1$. From the assumption, we see that $C_1 = C$ is closed and convex. Suppose that C_m is closed and convex for some $m \ge 1$. We show that C_{m+1} is closed and convex for the same m. Indeed, for any $w \in C_m$, we see that

$$\|y_m - w\| \le \|x_m - w\| \tag{2.7}$$

is equivalent to

$$\|y_m\|^2 - \|x_m\|^2 - 2\langle w, y_m - x_m \rangle \ge 0.$$
 (2.8)

Thus C_{m+1} is closed and convex. This shows that C_n is closed and convex for each $n \ge 1$.

Next, we show that $\mathcal{F} \subset C_n$ for each $n \geq 1$. From the assumption, we see that $\mathcal{F} \subset C = C_1$. Suppose that $\mathcal{F} \subset C_m$ for some $m \geq 1$. Putting

$$S_n = \beta_n I + (1 - \beta_n) S, \quad \forall n \ge 1, \tag{2.9}$$

we see from Lemma 1.3 that S_n is a nonexpansive mapping for each $n \ge 1$. For any $w \in \mathcal{F} \subset C_m$, we see from (2.6) that

$$||y_{m} - w|| = ||\alpha_{m}x_{m} + (1 - \alpha_{m})S_{m}z_{m} - w||$$

$$\leq \alpha_{m}||x_{m} - w|| + (1 - \alpha_{m})||z_{m} - w||$$

$$\leq ||x_{m} - w||.$$
(2.10)

This shows that $w \in C_{m+1}$. This proves that $\mathcal{F} \subset C_n$ for each $n \geq 1$. Note $x_n = P_{C_n} x_1$. For each $w \in \mathcal{F} \subset C_n$, we have

$$||x_1 - x_n|| \le ||x_1 - w||. \tag{2.11}$$

In particular, we have

$$||x_1 - x_n|| \le ||x_1 - P_{\mathcal{F}}x_1||.$$
 (2.12)

This implies that $\{x_n\}$ is bounded. Since $x_n = P_{C_n}x_1$ and $x_{n+1} = P_{C_{n+1}}x_1 \in C_{n+1} \subset C_n$, we have

$$0 \le \langle x_1 - x_n, x_n - x_{n+1} \rangle$$

$$= \langle x_1 - x_n, x_n - x_1 + x_1 - x_{n+1} \rangle$$

$$\le -\|x_1 - x_n\|^2 + \|x_1 - x_n\| \|x_1 - x_{n+1}\|.$$
(2.13)

It follows that

$$||x_n - x_1|| \le ||x_{n+1} - x_1||. \tag{2.14}$$

This proves that $\lim_{n\to\infty} ||x_n - x_1||$ exists. Notice that

$$||x_{n} - x_{n+1}||^{2} = ||x_{n} - x_{1} + x_{1} - x_{n+1}||^{2}$$

$$= ||x_{n} - x_{1}||^{2} + 2\langle x_{n} - x_{1}, x_{1} - x_{n+1} \rangle + ||x_{1} - x_{n+1}||^{2}$$

$$= ||x_{n} - x_{1}||^{2} + 2\langle x_{n} - x_{1}, x_{1} - x_{n} + x_{n} - x_{n+1} \rangle + ||x_{1} - x_{n+1}||^{2}$$

$$= ||x_{n} - x_{1}||^{2} - 2||x_{n} - x_{1}||^{2} + 2\langle x_{n} - x_{1}, x_{n} - x_{n+1} \rangle + ||x_{1} - x_{n+1}||^{2}$$

$$\leq ||x_{1} - x_{n+1}||^{2} - ||x_{n} - x_{1}||^{2}.$$
(2.15)

It follows that

$$\lim_{n \to \infty} ||x_n - x_{n+1}|| = 0.$$
 (2.16)

Since $x_{n+1} = P_{C_{n+1}} x_1 \in C_{n+1}$, we see that

$$||y_n - x_{n+1}|| \le ||x_n - x_{n+1}||.$$
 (2.17)

This implies that

$$||y_n - x_n|| \le ||y_n - x_{n+1}|| + ||x_n - x_{n+1}|| \le 2||x_n - x_{n+1}||.$$
 (2.18)

From (2.16), we obtain that

$$\lim_{n \to \infty} ||x_n - y_n|| = 0. (2.19)$$

On the other hand, we have

$$||x_n - y_n|| = ||x_n - \alpha_n x_n - (1 - \alpha_n) S_n z_n|| = (1 - \alpha_n) ||x_n - S_n z_n||.$$
 (2.20)

From the assumption $0 \le \alpha_n \le a < 1$ and (2.19), we have

$$\lim_{n \to \infty} ||x_n - S_n z_n|| = 0. {(2.21)}$$

For any $p \in \mathcal{F}$, we have

$$||u_{n} - p||^{2} = ||T_{r_{n}}(I - r_{n}A)x_{n} - T_{r_{n}}(I - r_{n}A)p||^{2}$$

$$= ||(x_{n} - p) - r_{n}(Ax_{n} - Ap)||^{2}$$

$$= ||x_{n} - p||^{2} - 2r_{n}\langle x_{n} - p, Ax_{n} - Ap \rangle + r_{n}^{2}||Ax_{n} - Ap||^{2}$$

$$\leq ||x_{n} - p||^{2} - r_{n}(2\alpha - r_{n})||Ax_{n} - Ap||^{2}.$$
(2.22)

In a similar way, we also have

$$\|v_n - p\|^2 \le \|x_n - p\|^2 - s_n(2\beta - s_n) \|Bx_n - Bp\|^2.$$
(2.23)

Note that

$$\|y_{n} - p\|^{2} = \|\alpha_{n}x_{n} + (1 - \alpha_{n})S_{n}z_{n} - p\|^{2}$$

$$\leq \alpha_{n}\|x_{n} - p\|^{2} + (1 - \alpha_{n})\|S_{n}z_{n} - p\|^{2}$$

$$\leq \alpha_{n}\|x_{n} - p\|^{2} + (1 - \alpha_{n})\|z_{n} - p\|^{2}$$

$$\leq \alpha_{n}\|x_{n} - p\|^{2} + (1 - \alpha_{n})\gamma_{n}\|u_{n} - p\|^{2} + (1 - \alpha_{n})(1 - \gamma_{n})\|v_{n} - p\|^{2}.$$

$$(2.24)$$

Substituting (2.22) and (2.23) into (2.24), we arrive at

$$||y_{n} - p||^{2} \le ||x_{n} - p||^{2} - (1 - \alpha_{n})\gamma_{n}r_{n}(2\alpha - r_{n})||Ax_{n} - Ap||^{2} - (1 - \alpha_{n})(1 - \gamma_{n})s_{n}(2\beta - s_{n})||Bx_{n} - Bp||^{2}.$$
(2.25)

It follows that

$$(1 - \alpha_n)\gamma_n r_n (2\alpha - r_n) \|Ax_n - Ap\|^2 \le \|x_n - p\|^2 - \|y_n - p\|^2 \le (\|x_n - p\| + \|y_n - p\|) \|x_n - y_n\|.$$
(2.26)

In view of the restrictions (a)–(d) and (2.19), we obtain that

$$\lim_{n \to \infty} ||Ax_n - Ap|| = 0. {(2.27)}$$

It also follows from (2.25) that

$$(1 - \alpha_n)(1 - \gamma_n)s_n(2\beta - s_n) \|Bx_n - Bp\|^2 \le \|x_n - p\|^2 - \|y_n - p\|^2 \le (\|x_n - p\| + \|y_n - p\|) \|x_n - y_n\|.$$
(2.28)

By virtue of the restrictions (a)–(d) and (2.19), we get that

$$\lim_{n \to \infty} \|Bx_n - Bp\| = 0. \tag{2.29}$$

On the other hand, we have from Lemma 1.1 that

$$\|u_{n} - p\|^{2} = \|T_{r_{n}}(I - r_{n}A)x_{n} - T_{r_{n}}(I - r_{n}A)p\|^{2}$$

$$\leq \langle (I - r_{n}A)x_{n} - (I - r_{n}A)p, u_{n} - p \rangle$$

$$= \frac{1}{2} \Big(\|(I - r_{n}A)x_{n} - (I - r_{n}A)p\|^{2} + \|u_{n} - p\|^{2} - \|(I - r_{n}A)x_{n} - (I - r_{n}A)p - (u_{n} - p)\|^{2} \Big)$$

$$\leq \frac{1}{2} \Big(\|x_{n} - p\|^{2} + \|u_{n} - p\|^{2} - \|x_{n} - u_{n} - r_{n}(Ax_{n} - Ap)\|^{2} \Big)$$

$$= \frac{1}{2} \Big(\|x_{n} - p\|^{2} + \|u_{n} - p\|^{2} - \Big(\|x_{n} - u_{n}\|^{2} - 2r_{n}\langle x_{n} - u_{n}, Ax_{n} - Ap\rangle + r_{n}^{2} \|Ax_{n} - Ap\|^{2} \Big) \Big).$$

$$(2.30)$$

This implies that

$$||u_n - p||^2 \le ||x_n - p||^2 - ||x_n - u_n||^2 + 2r_n ||x_n - u_n|| ||Ax_n - Ap||.$$
(2.31)

In a similar way, we can also obtain that

$$\|v_n - p\|^2 \le \|x_n - p\|^2 - \|x_n - v_n\|^2 + 2s_n\|x_n - v_n\| \|Bx_n - Bp\|.$$
 (2.32)

Substituting (2.31) and (2.32) into (2.24), we obtain that

$$||y_{n} - p||^{2} \leq ||x_{n} - p||^{2} - (1 - \alpha_{n})\gamma_{n}||x_{n} - u_{n}||^{2} + 2r_{n}(1 - \alpha_{n})\gamma_{n}||x_{n} - u_{n}|| ||Ax_{n} - Ap||$$

$$- (1 - \alpha_{n})(1 - \gamma_{n})||x_{n} - v_{n}||^{2} + 2s_{n}(1 - \alpha_{n})(1 - \gamma_{n})||x_{n} - v_{n}|| ||Bx_{n} - Bp||$$

$$\leq ||x_{n} - p||^{2} - (1 - \alpha_{n})\gamma_{n}||x_{n} - u_{n}||^{2} + 2r_{n}||x_{n} - u_{n}|| ||Ax_{n} - Ap||$$

$$- (1 - \alpha_{n})(1 - \gamma_{n})||x_{n} - v_{n}||^{2} + 2s_{n}||x_{n} - v_{n}|| ||Bx_{n} - Bp||.$$

$$(2.33)$$

It follows that

$$(1 - \alpha_{n})\gamma_{n} \|x_{n} - u_{n}\|^{2} \leq \|x_{n} - p\|^{2} - \|y_{n} - p\|^{2} + 2r_{n} \|x_{n} - u_{n}\| \|Ax_{n} - Ap\|$$

$$+ 2s_{n} \|x_{n} - v_{n}\| \|Bx_{n} - Bp\|$$

$$\leq (\|x_{n} - p\| + \|y_{n} - p\|) \|x_{n} - y_{n}\| + 2r_{n} \|x_{n} - u_{n}\| \|Ax_{n} - Ap\|$$

$$+ 2s_{n} \|x_{n} - v_{n}\| \|Bx_{n} - Bp\|.$$

$$(2.34)$$

In view of the restrictions (a) and (c), we obtain from (2.27) and (2.29) that

$$\lim_{n \to \infty} ||x_n - u_n|| = 0. \tag{2.35}$$

It also follows from (2.33) that

$$(1 - \alpha_{n})(1 - \gamma_{n})\|x_{n} - v_{n}\|^{2} \leq \|x_{n} - p\|^{2} - \|y_{n} - p\|^{2} + 2r_{n}\|x_{n} - u_{n}\|\|Ax_{n} - Ap\|$$

$$+ 2s_{n}\|x_{n} - v_{n}\|\|Bx_{n} - Bp\|$$

$$\leq (\|x_{n} - p\| + \|y_{n} - p\|)\|x_{n} - y_{n}\| + 2r_{n}\|x_{n} - u_{n}\|\|Ax_{n} - Ap\|$$

$$+ 2s_{n}\|x_{n} - v_{n}\|\|Bx_{n} - Bp\|.$$

$$(2.36)$$

Thanks to the restrictions (a) and (c), we obtain from (2.27) and (2.29) that

$$\lim_{n \to \infty} ||x_n - v_n|| = 0. {(2.37)}$$

Note that

$$||z_n - x_n|| \le \gamma_n ||u_n - x_n|| + (1 - \gamma_n) ||v_n - x_n||. \tag{2.38}$$

From (2.35) and (2.37), we see that

$$\lim_{n \to \infty} ||x_n - z_n|| = 0. {(2.39)}$$

On the other hand, we see from (2.21) that

$$\beta_n(z_n - x_n) + (1 - \beta_n)(Sz_n - x_n) \longrightarrow 0$$
(2.40)

as $n \to \infty$. In view of (2.39) and the restriction (b), we obtain that

$$\lim_{n \to \infty} ||x_n - Sz_n|| = 0. \tag{2.41}$$

Note that

$$||Sx_n - x_n|| \le ||Sx_n - Sz_n|| + ||Sz_n - x_n|| \le \frac{1+k}{1-k} ||x_n - z_n|| + ||Sz_n - x_n||.$$
 (2.42)

It follows from (2.39) and (2.41) that

$$\lim_{n \to \infty} ||x_n - Sx_n|| = 0.$$
 (2.43)

Since $\{x_n\}$ is bounded, we assume that a subsequence $\{x_{n_i}\}$ of $\{x_n\}$ converges weakly to ξ . Next, we show that $\xi \in F(S) \cap EP(F_1, A) \cap EP(F_2, B)$. First, we prove that $\xi \in EP(F_1, A)$. Since $u_n = T_{r_n}(x_n - r_n A x_n)$ for any $u \in C$, we have

$$F_1(u_n, u) + \langle Ax_n, u - u_n \rangle + \frac{1}{r_n} \langle u - u_n, u_n - x_n \rangle \ge 0.$$
 (2.44)

From the condition (A2), we see that

$$\langle Ax_n, u - u_n \rangle + \frac{1}{r_n} \langle u - u_n, u_n - x_n \rangle \ge F_1(u, u_n). \tag{2.45}$$

Replacing n by n_i , we arrive at

$$\langle Ax_{n_i}, u - u_{n_i} \rangle + \left\langle u - u_{n_i}, \frac{u_{n_i} - x_{n_i}}{r_{n_i}} \right\rangle \ge F_1(u, u_{n_i}).$$
 (2.46)

For any t with $0 < t \le 1$ and $u \in C$, let $u_t = tu + (1 - t)\xi$. Since $u \in C$ and $\xi \in C$, we have $u_t \in C$. It follows from (2.46) that

$$\langle u_{t} - u_{n_{i}}, Au_{t} \rangle \geq \langle u_{t} - u_{n_{i}}, Au_{t} \rangle - \langle Ax_{n_{i}}, u_{t} - u_{n_{i}} \rangle - \left\langle u_{t} - u_{n_{i}}, \frac{u_{n_{i}} - x_{n_{i}}}{r_{n_{i}}} \right\rangle + F_{1}(u_{t}, u_{n_{i}})$$

$$= \langle u_{t} - u_{n_{i}}, Au_{t} - Au_{n_{i}} \rangle + \langle u_{t} - u_{n_{i}}, Au_{n_{i}} - Ax_{n_{i}} \rangle - \left\langle u_{t} - u_{n_{i}}, \frac{u_{n_{i}} - x_{n_{i}}}{r_{n_{i}}} \right\rangle + F_{1}(u_{t}, u_{n_{i}}).$$
(2.47)

Since *A* is Lipschitz continuous, we obtain from (2.35) that $Au_{n_i} - Ax_{n_i} \to 0$ as $i \to \infty$. On the other hand, we get from the monotonicity of *A* that

$$\langle u_t - u_{n_t}, Au_t - Au_{n_t} \rangle \ge 0. \tag{2.48}$$

It follows from (A4) and (2.47) that

$$\langle u_t - \xi, Au_t \rangle \ge F_1(u_t, \xi). \tag{2.49}$$

From (A1), (A4), and (2.49), we see that

$$0 = F_1(u_t, u_t) \le tF_1(u_t, u) + (1 - t)F_1(u_t, \xi)$$

$$\le tF_1(u_t, u) + (1 - t)\langle u_t - \xi, Au_t \rangle$$

$$= tF_1(u_t, u) + (1 - t)t\langle u - \xi, Au_t \rangle,$$
(2.50)

which yields that

$$F_1(u_t, u) + (1 - t)\langle u - \xi, Au_t \rangle \ge 0.$$
 (2.51)

Letting $t \to 0$ in the above inequality, we arrive at

$$F_1(\xi, u) + \langle u - \xi, A\xi \rangle \ge 0. \tag{2.52}$$

This shows that $\xi \in EP(F_1, A)$. In a similar way, we can obtain that $\xi \in EP(F_2, B)$.

Next, we show that $\xi \in F(S)$. We can conclude from Lemma 1.1 the desired conclusion easily. This proves that $\xi \in \mathcal{F}$. Put $\overline{x} = P_{\mathcal{F}}x_1$. Since $\overline{x} = P_{\mathcal{F}}x_1 \subset C_{n+1}$ and $x_{n+1} = P_{C_{n+1}}x_1$, we have

$$||x_1 - x_{n+1}|| \le ||x_1 - \overline{x}||. \tag{2.53}$$

On the other hand, we have

$$\|x_{1} - \overline{x}\| \leq \|x_{1} - \xi\|$$

$$\leq \liminf_{i \to \infty} \|x_{1} - x_{n_{i}}\|$$

$$\leq \limsup_{i \to \infty} \|x_{1} - x_{n_{i}}\|$$

$$\leq \|x_{1} - \overline{x}\|.$$

$$(2.54)$$

We, therefore, obtain that

$$||x_1 - \xi|| = \lim_{i \to \infty} ||x_1 - x_{n_i}|| = ||x_1 - \overline{x}||.$$
 (2.55)

This implies $x_{n_i} \to \xi = \overline{x}$. Since $\{x_{n_i}\}$ is an arbitrary subsequence of $\{x_n\}$, we obtain that $x_n \to \overline{x}$ as $n \to \infty$. This completes the proof.

If *S* is nonexpansive, then we have from Theorem 2.1 the following result immediately.

Corollary 2.2. Let C be a nonempty closed convex subset of a real Hilbert space H. Let F_1 and F_2 be two bifunctions from $C \times C$ to $\mathbb R$ which satisfies (A1)–(A4). Let $A: C \to H$ be an α -inverse-strongly monotone mapping, $B: C \to H$ a β -inverse-strongly monotone mapping, and $S: C \to C$ a nonexpansive mapping. Let $\{r_n\}$ and $\{s_n\}$ be two positive real sequences. Assume that $\mathcal{F} := EP(F_1, A) \cap FP(F_2, B) \cap F(S)$ is not empty. Let $\{x_n\}$ be a sequence generated in the following manner:

$$x_{1} \in C,$$

$$C_{1} = C,$$

$$F_{1}(u_{n}, u) + \langle Ax_{n}, u - u_{n} \rangle + \frac{1}{r_{n}} \langle u - u_{n}, u_{n} - x_{n} \rangle \geq 0, \quad \forall u \in C,$$

$$F_{2}(v_{n}, v) + \langle Bx_{n}, v - v_{n} \rangle + \frac{1}{s_{n}} \langle v - v_{n}, v_{n} - x_{n} \rangle \geq 0, \quad \forall v \in C,$$

$$y_{n} = \alpha_{n}x_{n} + (1 - \alpha_{n})S(\gamma_{n}u_{n} + (1 - \gamma_{n})v_{n}),$$

$$C_{n+1} = \{w \in C_{n} : ||y_{n} - w|| \leq ||x_{n} - w||\},$$

$$x_{n+1} = P_{C_{n+1}}x_{1}, \quad n \geq 1,$$

$$(2.56)$$

where $\{\alpha_n\}$ and $\{\gamma_n\}$ are sequences in (0,1). Assume that $\{\alpha_n\}$, $\{\gamma_n\}$, $\{r_n\}$, and $\{s_n\}$ satisfy the following restrictions:

- (a) $0 < \alpha_n < a < 1$;
- (b) $0 \le c \le \gamma_n \le d < 1$;
- (c) $0 < e \le r_n \le f < 2\alpha \text{ and } 0 < e' \le s_n \le f' < 2\beta$.

Then the sequence $\{x_n\}$ converges strongly to some point \overline{x} , where $\overline{x} = P_{\overline{x}}x_1$.

As applications of Theorem 2.1, we consider the problems (1.9) and (1.11).

Theorem 2.3. Let C be a nonempty closed convex subset of a real Hilbert space H. Let $A: C \to H$ be an α -inverse-strongly monotone mapping, $B: C \to H$ a β -inverse-strongly monotone mapping, and $S: C \to C$ a k-strict pseudocontraction. Let $\{r_n\}$ and $\{s_n\}$ be two positive real sequences. Assume that $\mathcal{F} := VI(C, A) \cap VI(C, B) \cap F(S)$ is not empty. Let $\{x_n\}$ be a sequence generated in the following manner:

$$x_{1} \in C,$$

$$C_{1} = C,$$

$$z_{n} = \gamma_{n} P_{C} (I - r_{n} A) x_{n} + (1 - \gamma_{n}) P_{C} (I - s_{n} B) x_{n},$$

$$y_{n} = \alpha_{n} x_{n} + (1 - \alpha_{n}) (\beta_{n} z_{n} + (1 - \beta_{n}) S z_{n}),$$

$$C_{n+1} = \{ w \in C_{n} : ||y_{n} - w|| \le ||x_{n} - w|| \},$$

$$x_{n+1} = P_{C_{n+1}} x_{1}, \quad n \ge 1,$$
(2.57)

where $\{\alpha_n\}$, $\{\beta_n\}$, and $\{\gamma_n\}$ are sequences in (0,1). Assume that $\{\alpha_n\}$, $\{\beta_n\}$, $\{\gamma_n\}$, $\{r_n\}$, and $\{s_n\}$ satisfy the following restrictions:

- (a) $0 \le \alpha_n \le a < 1$;
- (b) $0 \le k \le \beta_n < b < 1$;
- (c) $0 \le c \le \gamma_n \le d < 1$;
- (d) $0 < e \le r_n \le f < 2\alpha$ and $0 < e' \le s_n \le f' < 2\beta$.

Then the sequence $\{x_n\}$ converges strongly to some point \overline{x} , where $\overline{x} = P_{\overline{x}}x_1$.

Proof. Putting $F_1 = F_2 \equiv 0$, we see that

$$\langle Ax_n, u - u_n \rangle + \frac{1}{r_n} \langle u - u_n, u_n - x_n \rangle \ge 0, \quad \forall u \in C,$$
 (2.58)

is equivalent to

$$\langle x_n - r_n A x_n - u_n, u_n - u \rangle \ge 0, \quad \forall u \in C.$$
 (2.59)

This implies that $u_n = P_C(x_n - r_n A x_n)$. We also have $v_n = P_C(x_n - s_n B x_n)$. We can obtain from Theorem 2.1 the desired results immediately.

Corollary 2.4. Let C be a nonempty closed convex subset of a real Hilbert space H. Let $A: C \to H$ be an α -inverse-strongly monotone mapping, $B: C \to H$ a β -inverse-strongly monotone mapping, and $S: C \to C$ a nonexpansive mapping. Let $\{r_n\}$ and $\{s_n\}$ be two positive real sequences. Assume

that $\mathcal{F} := VI(C, A) \cap VI(C, B) \cap F(S)$ is not empty. Let $\{x_n\}$ be a sequence generated in the following manner:

$$x_{1} \in C,$$

$$C_{1} = C,$$

$$z_{n} = \gamma_{n} P_{C} (I - r_{n} A) x_{n} + (1 - \gamma_{n}) P_{C} (I - s_{n} B) x_{n},$$

$$y_{n} = \alpha_{n} x_{n} + (1 - \alpha_{n}) S z_{n},$$

$$C_{n+1} = \{ w \in C_{n} : ||y_{n} - w|| \le ||x_{n} - w|| \},$$

$$x_{n+1} = P_{C_{n+1}} x_{1}, \quad n \ge 1,$$
(2.60)

where $\{\alpha_n\}$ and $\{\gamma_n\}$ are sequences in (0,1). Assume that $\{\alpha_n\}$, $\{\gamma_n\}$, $\{r_n\}$, and $\{s_n\}$ satisfy the following restrictions:

- (a) $0 \le \alpha_n \le a < 1$;
- (b) $0 \le c \le \gamma_n \le d < 1$;
- (c) $0 < e \le r_n \le f < 2\alpha$ and $0 < e' \le s_n \le f' < 2\beta$.

Then the sequence $\{x_n\}$ converges strongly to some point \overline{x} , where $\overline{x} = P_{\overline{x}}x_1$.

Theorem 2.5. Let C be a nonempty closed convex subset of a real Hilbert space H. Let F_1 and F_2 be two bifunctions from $C \times C$ to \mathbb{R} which satisfies (A1)–(A4). Let $S: C \to C$ be a k-strict pseudocontraction. Let $\{r_n\}$ and $\{s_n\}$ be two positive real sequences. Assume that $\mathfrak{F}:=EP(F_1)\cap FP(F_2)\cap F(S)$ is not empty. Let $\{x_n\}$ be a sequence generated in the following manner:

$$x_{1} \in C,$$

$$C_{1} = C,$$

$$F_{1}(u_{n}, u) + \frac{1}{r_{n}} \langle u - u_{n}, u_{n} - x_{n} \rangle \geq 0, \quad \forall u \in C,$$

$$F_{2}(v_{n}, v) + \frac{1}{s_{n}} \langle v - v_{n}, v_{n} - x_{n} \rangle \geq 0, \quad \forall v \in C,$$

$$z_{n} = \gamma_{n} u_{n} + (1 - \gamma_{n}) v_{n},$$

$$y_{n} = \alpha_{n} x_{n} + (1 - \alpha_{n}) (\beta_{n} z_{n} + (1 - \beta_{n}) S z_{n}),$$

$$C_{n+1} = \{ w \in C_{n} : \|y_{n} - w\| \leq \|x_{n} - w\| \},$$

$$x_{n+1} = P_{C_{n+1}} x_{1}, \quad n \geq 1,$$

$$(2.61)$$

where $\{\alpha_n\}$, $\{\beta_n\}$, and $\{\gamma_n\}$ are sequences in (0,1). Assume that $\{\alpha_n\}$, $\{\beta_n\}$, $\{\gamma_n\}$, $\{r_n\}$, and $\{s_n\}$ satisfy the following restrictions:

- (a) $0 \le \alpha_n \le a < 1$;
- (b) $0 \le k \le \beta_n < b < 1$;

(c)
$$0 \le c \le \gamma_n \le d < 1$$
;

(d)
$$0 < e \le r_n \le f < \infty \text{ and } 0 < e' \le s_n \le f' < \infty.$$

Then the sequence $\{x_n\}$ converges strongly to some point \overline{x} , where $\overline{x} = P_{\overline{x}}x_1$.

Proof. Putting A = B = 0, we can obtain from Theorem 2.1 the desired conclusion immediately.

Remark 2.6. Theorem 2.5 is generalization of Theorem TT. To be more precise, we consider a pair of bifunctions and a strictly pseudocontractive mapping.

Let T : $C \to C$ be a k-strict pseudocontraction. It is known that I - T is a (1 - k)/2-inverse-strongly monotone mapping. The following results are not hard to derive.

Theorem 2.7. Let C be a nonempty closed convex subset of a real Hilbert space H. Let F_1 and F_2 be two bifunctions from $C \times C$ to $\mathbb R$ which satisfies (A1)–(A4). Let $T_A : C \to C$ be a k_α -strict pseudocontraction, $B : C \to C$ a k_β -strict pseudocontraction, and $S : C \to C$ a k-strict pseudocontraction. Let $\{r_n\}$ and $\{s_n\}$ be two positive real sequences. Assume that $\mathcal{F} := EP(F_1, I - T_A) \cap FP(F_2, I - T_B) \cap F(S)$ is not empty. Let $\{x_n\}$ be a sequence generated in the following manner:

$$x_{1} \in C,$$

$$C_{1} = C,$$

$$F_{1}(u_{n}, u) + \langle (I - T_{A})x_{n}, u - u_{n} \rangle + \frac{1}{r_{n}} \langle u - u_{n}, u_{n} - x_{n} \rangle \geq 0, \quad \forall u \in C,$$

$$F_{2}(v_{n}, v) + \langle (I - T_{B})x_{n}, v - v_{n} \rangle + \frac{1}{s_{n}} \langle v - v_{n}, v_{n} - x_{n} \rangle \geq 0, \quad \forall v \in C,$$

$$z_{n} = \gamma_{n}u_{n} + (1 - \gamma_{n})v_{n},$$

$$y_{n} = \alpha_{n}x_{n} + (1 - \alpha_{n})(\beta_{n}z_{n} + (1 - \beta_{n})Sz_{n}),$$

$$C_{n+1} = \{w \in C_{n} : \|y_{n} - w\| \leq \|x_{n} - w\|\},$$

$$x_{n+1} = P_{C_{n+1}}x_{1}, \quad n \geq 1,$$

$$(2.62)$$

where $\{\alpha_n\}$, $\{\beta_n\}$, and $\{\gamma_n\}$ are sequences in (0,1). Assume that $\{\alpha_n\}$, $\{\beta_n\}$, $\{\gamma_n\}$, $\{r_n\}$, and $\{s_n\}$ satisfy the following restrictions:

- (a) $0 \le \alpha_n \le a < 1$;
- (b) $0 \le k \le \beta_n < b < 1$;
- (c) $0 \le c \le \gamma_n \le d < 1$;

(d)
$$0 < e \le r_n \le f < 1 - k_\alpha$$
 and $0 < e' \le s_n \le f' < 1 - k_\beta$.

Then the sequence $\{x_n\}$ converges strongly to some point \overline{x} , where $\overline{x} = P_{\overline{x}}x_1$.

Acknowledgment

This work was supported by a National Research Foundation of Korea Grant funded by the Korean Government (2009-0076898).

References

- [1] F. E. Browder and W. V. Petryshyn, "Construction of fixed points of nonlinear mappings in Hilbert space," *Journal of Mathematical Analysis and Applications*, vol. 20, pp. 197–228, 1967.
- [2] E. Blum and W. Oettli, "From optimization and variational inequalities to equilibrium problems," *The Mathematics Student*, vol. 63, no. 1–4, pp. 123–145, 1994.
- [3] P. L. Combettes and S. A. Hirstoaga, "Equilibrium programming in Hilbert spaces," *Journal of Nonlinear and Convex Analysis*, vol. 6, no. 1, pp. 117–136, 2005.
- [4] L.-C. Ceng, S. Al-Homidan, Q. H. Ansari, and J.-C. Yao, "An iterative scheme for equilibrium problems and fixed point problems of strict pseudo-contraction mappings," *Journal of Computational and Applied Mathematics*, vol. 223, no. 2, pp. 967–974, 2009.
- [5] V. Colao, G. Marino, and H.-K. Xu, "An iterative method for finding common solutions of equilibrium and fixed point problems," *Journal of Mathematical Analysis and Applications*, vol. 344, no. 1, pp. 340–352, 2008.
- [6] S.-S. Chang, H. W. Joseph Lee, and C. K. Chan, "A new method for solving equilibrium problem fixed point problem and variational inequality problem with application to optimization," *Nonlinear Analysis: Theory, Methods & Applications. and Methods*, vol. 70, no. 9, pp. 3307–3319, 2009.
- [7] Y. J. Cho, X. Qin, and J. I. Kang, "Convergence theorems based on hybrid methods for generalized equilibrium problems and fixed point problems," *Nonlinear Analysis: Theory, Methods & Applications*, vol. 71, no. 9, pp. 4203–4214, 2009.
- [8] C. Jaiboon, W. Chantarangsi, and P. Kumam, "A convergence theorem based on a hybrid relaxed extragradient method for generalized equilibrium problems and fixed point problems of a finite family of nonexpansive mappings," Nonlinear Analysis: Hybrid Systems, vol. 4, no. 1, pp. 199–215, 2010.
- [9] P. Kumam, "A hybrid approximation method for equilibrium and fixed point problems for a monotone mapping and a nonexpansive mapping," *Nonlinear Analysis. Hybrid Systems*, vol. 2, no. 4, pp. 1245–1255, 2008.
- [10] A. Moudafi, "Weak convergence theorems for nonexpansive mappings and equilibrium problems," Journal of Nonlinear and Convex Analysis, vol. 9, no. 1, pp. 37–43, 2008.
- [11] S. Plubtieng and R. Punpaeng, "A new iterative method for equilibrium problems and fixed point problems of nonexpansive mappings and monotone mappings," *Applied Mathematics and Computation*, vol. 197, no. 2, pp. 548–558, 2008.
- [12] X. Qin, M. Shang, and Y. Su, "Strong convergence of a general iterative algorithm for equilibrium problems and variational inequality problems," *Mathematical and Computer Modelling*, vol. 48, no. 7-8, pp. 1033–1046, 2008.
- [13] X. Qin, S. M. Kang, and Y. J. Cho, "Convergence theorems on generalized equilibrium problems and fixed point problems with applications," *Proceedings of the Estonian Academy of Sciences*, vol. 58, no. 3, pp. 170–183, 2009.
- [14] X. Qin, Y. J. Cho, and S. M. Kang, "Convergence theorems of common elements for equilibrium problems and fixed point problems in Banach spaces," *Journal of Computational and Applied Mathematics*, vol. 225, no. 1, pp. 20–30, 2009.
- [15] S. Takahashi and W. Takahashi, "Viscosity approximation methods for equilibrium problems and fixed point problems in Hilbert spaces," *Journal of Mathematical Analysis and Applications*, vol. 331, no. 1, pp. 506–515, 2007.
- [16] S. Takahashi and W. Takahashi, "Strong convergence theorem for a generalized equilibrium problem and a nonexpansive mapping in a Hilbert space," Nonlinear Analysis: Theory, Methods & Applications, vol. 69, no. 3, pp. 1025–1033, 2008.
- [17] A. Tada and W. Takahashi, "Weak and strong convergence theorems for a nonexpansive mapping and an equilibrium problem," *Journal of Optimization Theory and Applications*, vol. 133, no. 3, pp. 359–370, 2007.

- [18] W. Takahashi, Y. Takeuchi, and R. Kubota, "Strong convergence theorems by hybrid methods for families of nonexpansive mappings in Hilbert spaces," *Journal of Mathematical Analysis and Applications*, vol. 341, no. 1, pp. 276–286, 2008.
- [19] G. Marino and H.-K. Xu, "Weak and strong convergence theorems for strict pseudo-contractions in Hilbert spaces," *Journal of Mathematical Analysis and Applications*, vol. 329, no. 1, pp. 336–346, 2007.