

## Research Article

# Existence of Solutions for Nonconvex and Nonsmooth Vector Optimization Problems

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We consider the weakly efficient solution for a class of nonconvex and nonsmooth vector optimization problems in Banach spaces. We show the equivalence between the nonconvex and nonsmooth vector optimization problem and the vector variational-like inequality involving set-valued mappings. We prove some existence results concerned with the weakly efficient solution for the nonconvex and nonsmooth vector optimization problems by using the equivalence and Fan-KKM theorem under some suitable conditions.

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## 1. Introduction

The concept of vector variational inequality was first introduced by Giannessi [1] in 1980. Since then, existence theorems for solution of general versions of the vector variational inequality have been studied by many authors (see, e.g., [2–9] and the references therein). Recently, vector variational inequalities and their generalizations have been used as a tool to solve vector optimization problems (see [7, 10–14]). Chen and Craven [11] obtained a sufficient condition for the existence of weakly efficient solutions for differentiable vector optimization problems involving differentiable convex functions by using vector variational inequalities for vector valued functions. Kazmi [12] proved a sufficient condition for the existence of weakly efficient solutions for vector optimization problems involving differentiable preinvex functions by using vector variational-like inequalities. For the nonsmooth case, Lee et al. [7] established the existence of the weakly efficient solution for nondifferentiable vector optimization problems by using vector variational-like inequalities for set-valued mappings. Similar results can be found in [10]. It is worth mentioning that Lee et al. [7] and Ansari and Yao [10] obtained their

existence results under the assumption that  $R_+^m \subset C(x)$  for all  $x \in R^n$ , where  $C(x)$  is a convex cone in  $R^m$ . However, this condition is restrictive and it does not hold in general.

In this paper, we consider the weakly efficient solution for a class of nonconvex and nonsmooth vector optimization problems in Banach spaces. We show the equivalence between the nonconvex and nonsmooth vector optimization problem and the vector variational-like inequality involving set-valued mappings. We prove some existence results concerned with the weakly efficient solution for the nonconvex and nonsmooth vector optimization problems by using the equivalence and Fan-KKM theorem without the restrictive condition  $R_+^m \subset C(x)$  for all  $x \in R^n$ . Our results generalize and improve the results obtained by Lee et al. [7] and Ansari and Yao [10].

## 2. Preliminaries

Let  $X$  be a real Banach space endowed with a norm  $\|\cdot\|$  and  $X^*$  its dual space, we denote by  $\langle \cdot, \cdot \rangle$  the dual pair between  $X$  and  $X^*$ . Let  $R^m$  be the  $m$ -dimensional Euclidean space, let  $S \subset X$  be a nonempty subset, and let  $K \subset R^m$  be a nonempty closed convex cone with  $\text{int } K \neq \emptyset$ , where  $\text{int}$  denotes interior.

*Definition 2.1.* A real valued function  $h : X \rightarrow R$  is said to be locally Lipschitz at a point  $x \in X$  if there exists a number  $L > 0$  such that

$$|h(y) - h(z)| \leq L\|y - z\| \quad (2.1)$$

for all  $y, z$  in a neighborhood of  $x$ .  $h$  is said to be locally Lipschitz on  $X$  if it is locally Lipschitz at each point of  $X$ .

*Definition 2.2.* Let  $h : X \rightarrow R$  be a locally Lipschitz function. Clarke [15] generalized directional derivative of  $h$  at  $x \in X$  in the direction  $v$ , denoted by  $h^\circ(x; v)$ , is defined by

$$h^\circ(x; v) = \limsup_{y \rightarrow x, t \downarrow 0} \frac{h(y + tv) - h(y)}{t}. \quad (2.2)$$

Clarke [15] generalized gradient of  $h$  at  $x \in X$ , denoted by  $\partial h(x)$ , is defined by

$$\partial h(x) = \{ \xi \in X^* : h^\circ(x; v) \geq \langle \xi, v \rangle \forall v \in X \}. \quad (2.3)$$

Let  $f : X \rightarrow R^m$  be a vector valued function given by  $f = (f_1, f_2, \dots, f_m)$ , where each  $f_i$ ,  $i = 1, 2, \dots, m$ , is a real valued function defined on  $X$ . Then  $f$  is said to be locally Lipschitz on  $X$  if each  $f_i$  is locally Lipschitz on  $X$ .

The generalized directional derivative of a locally Lipschitz function  $f : X \rightarrow R^m$  at  $x \in X$  in the direction  $v$  is given by

$$f^\circ(x; v) = (f_1^\circ(x; v), f_2^\circ(x; v), \dots, f_m^\circ(x; v)). \quad (2.4)$$

The generalized gradient of  $f$  at  $x$  is the set

$$\partial f(x) = \partial f_1(x) \times \partial f_2(x) \times \dots \times \partial f_m(x), \quad (2.5)$$

where  $\partial f_i(x)$  is the generalized gradient of  $f_i$  at  $x$  for  $i = 1, 2, \dots, m$ .

Every element  $A = (\xi_1, \xi_2, \dots, \xi_m) \in \partial f(x)$  is a continuous linear operator from  $X$  to  $R^m$  and

$$Ay = (\langle \xi_1, y \rangle, \langle \xi_2, y \rangle, \dots, \langle \xi_m, y \rangle) \in R^m, \quad \forall y \in X. \quad (2.6)$$

*Definition 2.3.* Let  $f : X \rightarrow R^m$  be a locally Lipschitz function.

- (i)  $f$  is said to be  $K$ -invex with respect to  $\eta$  at  $u \in X$ , if there exists  $\eta : X \times X \rightarrow X$  such that for all  $x \in X$  and  $A \in \partial f(u)$ ,

$$f(x) - f(u) - \langle A, \eta(x, u) \rangle \in K. \quad (2.7)$$

- (ii)  $f$  is said to be  $K$ -pseudoinvex with respect to  $\eta$  at  $u \in X$  if there exists  $\eta : X \times X \rightarrow X$  such that for all  $x \in X$  and  $A \in \partial f(u)$ ,

$$f(x) - f(u) \in -\text{int } K \implies \langle A, \eta(x, u) \rangle \in -\text{int } K. \quad (2.8)$$

In this paper, we consider the following nonsmooth vector optimization problem:

$$\begin{aligned} &K\text{-minimize } f(x), \\ &\text{subject to } x \in S, \end{aligned} \quad (\text{VOP})$$

where  $f = (f_1, f_2, \dots, f_m)$ ,  $f_i : X \rightarrow R$ ,  $i = 1, 2, \dots, m$ , are locally Lipschitz functions.

*Definition 2.4.* A point  $x_0 \in S$  is said to be a weakly efficient solution of  $f$  if there exists no  $y \in S$  such that

$$f(y) - f(x) \in -\text{int } K. \quad (2.9)$$

In order to prove our main results, we need the following definition and lemmas.

*Definition 2.5* (see [16]). A multivalued mapping  $G : X \rightarrow 2^X$  is called KKM-mapping if for any finite subset  $\{x_1, x_2, \dots, x_n\}$  of  $X$ ,  $\text{co}\{x_1, x_2, \dots, x_n\}$  is contained in  $\bigcup_{i=1}^n G(x_i)$ , where  $\text{co}A$  denotes the convex hull of the set  $A$ .

**Lemma 2.6** (see [16]). *Let  $M$  be a nonempty subset of a Hausdorff topological vector space  $X$ . Let  $G : M \rightarrow 2^X$  be a KKM-mapping such that  $G(x)$  is closed for any  $x \in M$  and is compact for at least one  $x \in M$ . Then  $\bigcap_{y \in M} G(y) \neq \emptyset$ .*

**Lemma 2.7** (see [2]). *Let  $K$  be a convex cone of topological vector space  $X$ . If  $y - x \in K$  and  $x \notin -\text{int } K$ , then  $y \notin -\text{int } K$  for any  $x, y \in X$ .*

### 3. Main results

In order to obtain our main results, we introduce the following vector variational-like inequality problem, which consists in finding  $x_0 \in S$  such that for all  $A \in \partial f(x_0)$ ,

$$\langle A, \eta(y, x_0) \rangle \notin -\text{int } K, \quad \forall y \in S. \quad (\text{VVIP})$$

First, we establish the following relations between (VOP) and (VVIP).

**Lemma 3.1.** *Let  $f : X \rightarrow R^m$  be a locally Lipschitz function and  $\eta : S \times S \rightarrow X$ . Then the following arguments hold.*

- (i) *Suppose that  $f$  is  $K$ -invex with respect to  $\eta$ . If  $x_0$  is a solution of (VVIP), then  $x_0$  is a weakly efficient solution of (VOP).*
- (ii) *Suppose that  $f$  is  $K$ -pseudoinvex with respect to  $\eta$ . If  $x_0$  is a solution of (VVIP), then  $x_0$  is a weakly efficient solution of (VOP).*
- (iii) *Suppose that  $f$  is  $-K$ -invex with respect to  $\eta$ . If  $x_0$  is a weakly efficient solution of (VOP), then  $x_0$  is a solution of (VVIP).*

*Proof.* (i) Let  $x_0$  be a solution of (VVIP). Then

$$\langle A, \eta(y, x_0) \rangle \notin -\text{int } K, \quad \forall A \in \partial f(x_0), y \in S. \quad (3.1)$$

By the  $K$ -invexity of  $f$  with respect to  $\eta$ , we get

$$f(y) - f(x_0) - \langle A, \eta(y, x_0) \rangle \in K, \quad \forall A \in \partial f(x_0), y \in S. \quad (3.2)$$

From (3.1), (3.2) and Lemma 2.7, we obtain

$$f(y) - f(x_0) \notin -\text{int } K, \quad \forall y \in S. \quad (3.3)$$

Therefore,  $x_0$  is a weakly efficient solution of (VOP).

(ii) Let  $x_0$  be a solution of (VVIP). Suppose that  $x_0$  is not a weakly efficient solution of (VOP). Then, there exists  $y \in S$  such that

$$f(y) - f(x_0) \in -\text{int } K. \quad (3.4)$$

Since  $f$  is  $K$ -pseudoinvex with respect to  $\eta$ , then

$$\langle A, \eta(y, x_0) \rangle \in -\text{int } K, \quad \forall A \in \partial f(x_0), \quad (3.5)$$

which contradicts the fact that  $x_0$  is a solution of (VVIP).

(iii) Assume that  $x_0$  is a weakly efficient solution of (VOP). Then,

$$f(y) - f(x_0) \notin -\text{int } K, \quad \forall y \in S. \quad (3.6)$$

Since  $f$  is  $-K$ -invex with respect to  $\eta$ , then

$$f(y) - f(x_0) - \langle A, \eta(y, x_0) \rangle \in -K, \quad \forall A \in \partial f(x_0), y \in S. \quad (3.7)$$

It follows from Lemma 2.7 that

$$\langle A, \eta(y, x_0) \rangle \notin -\text{int } K, \quad \forall A \in \partial f(x_0), y \in S. \quad (3.8)$$

Therefore,  $x_0$  is a solution of (VVIP). □

Now we establish the following existence theorem.

**Theorem 3.2.** *Let  $S \subset X$  be a nonempty convex set and  $\eta : S \times S \rightarrow X$ . Let  $f : X \rightarrow \mathbb{R}^m$  be a locally Lipschitz  $K$ -pseudoinvex function. Assume that the following conditions hold*

- (i)  $\eta(x, x) = 0$  for any  $x \in S$ ,  $\eta(y, x)$  is affine with respect to  $y$  and continuous with respect to  $x$ ;
- (ii) there exist a compact subset  $D$  of  $S$  and  $y_0 \in D$  such that

$$\langle A, \eta(y_0, x) \rangle \in -\text{int } K, \quad \forall x \in S \setminus D, \quad A \in \partial f(x). \quad (3.9)$$

Then (VOP) has a weakly efficient solution.

*Proof.* By Lemma 3.1(ii), it suffices to prove that (VVIP) has a solution. Define  $G : S \rightarrow 2^S$  by

$$G(y) = \{x \in S : \langle A, \eta(y, x) \rangle \notin -\text{int } K, \forall A \in \partial f(x)\}, \quad \forall y \in S. \quad (3.10)$$

First we show that  $G$  is a KKM-mapping. By condition (i), we get  $y \in G(y)$ . Hence,  $G(y) \neq \emptyset$  for all  $y \in S$ . Suppose that there exists a finite subset  $\{x_1, x_2, \dots, x_m\} \subseteq S$  and that  $\alpha_i \geq 0, i = 1, 2, \dots, m$ , with  $\sum_{i=1}^m \alpha_i = 1$  such that  $x = \sum_{i=1}^m \alpha_i x_i \notin \bigcup_{i=1}^m G(x_i)$ . Then,  $x \notin G(x_i)$  for all  $i = 1, 2, \dots, m$ . It follows that there exists  $A \in \partial f(x)$  such that

$$\langle A, \eta(x_i, x) \rangle \in -\text{int } K, \quad i = 1, 2, \dots, m. \quad (3.11)$$

Since  $K$  is a convex cone and  $\eta$  is affine with respect to the first argument,

$$\langle A, \eta(x, x) \rangle \in -\text{int } K. \quad (3.12)$$

which gives  $0 \in -\text{int } K$ . This is a contradiction since  $0 \notin -\text{int } K$ . Therefore,  $G$  is a KKM-mapping.

Next, we show that  $G(y)$  is a closed set for any  $y \in S$ . In fact, let  $\{x_n\}$  be a sequence of  $G(y)$  which converges to some  $x_0 \in S$ . Then for all  $A_n \in \partial f(x_n)$ , we have

$$\langle A_n, \eta(y, x_n) \rangle \notin -\text{int } K. \quad (3.13)$$

Since  $f$  is locally Lipschitz, then there exists a neighborhood  $N(x_0)$  of  $x_0$  and  $L > 0$  such that for any  $x, y \in N(x_0)$ ,

$$|f(x) - f(y)| \leq L\|x - y\|. \quad (3.14)$$

It follows that for any  $x \in N(x_0)$  and any  $A \in \partial f(x)$ ,  $\|A\| \leq L$ . Without loss of generality, we may assume that  $A_n$  converges to  $A_0$ . Since the set-valued mapping  $x \mapsto \partial f(x)$  is closed (see [15, page 29]) and  $A_n \in \partial f(x_n)$ ,  $A_0 \in \partial f(x_0)$ . By the continuity of  $\eta(y, x)$  with respect to the second argument, we have

$$\langle A_n, \eta(y, x_n) \rangle \longrightarrow \langle A_0, \eta(y, x_0) \rangle. \quad (3.15)$$

Since  $\mathbb{R}^m \setminus -\text{int } K$  is closed, one has

$$\langle A_0, \eta(y, x_0) \rangle \notin -\text{int } K. \quad (3.16)$$

Hence,  $G(y)$  is a closed set for any  $y \in S$ .

By condition (ii), we have  $G(y_0) \subset D$ . As  $G(y_0)$  is closed and  $D$  is compact,  $G(y_0)$  is compact. Therefore, by Lemma 2.6, we have that there exists  $x^* \in S$  such that

$$x^* \in \bigcap_{y \in S} G(y), \quad (3.17)$$

or equivalently,

$$\langle A, \eta(y, x^*) \rangle \notin -\text{int } K, \quad \forall A \in \partial f(x^*), y \in S. \quad (3.18)$$

That is,  $x^*$  is a solution of (VVIP). This completes the proof.  $\square$

**Corollary 3.3.** *Let  $S \subset X$  be a nonempty convex set and  $\eta : S \times S \rightarrow X$ . Let  $f : X \rightarrow \mathbb{R}^m$  be a locally Lipschitz  $K$ -invex function. Assume that the following conditions hold:*

- (i)  $\eta(x, x) = 0$  for any  $x \in S$ ,  $\eta(y, x)$  is affine with respect to  $y$  and continuous with respect to  $x$ ;
- (ii) there exist a compact subset  $D$  of  $S$  and  $y_0 \in D$  such that

$$\langle A, \eta(y_0, x) \rangle \in -\text{int } K, \quad \forall x \in S \setminus D, A \in \partial f(x). \quad (3.19)$$

Then (VOP) has a weakly efficient solution.

*Proof.* Since a  $K$ -invex function is  $K$ -pseudoinvex, by Theorem 3.2, we obtain the result.  $\square$

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